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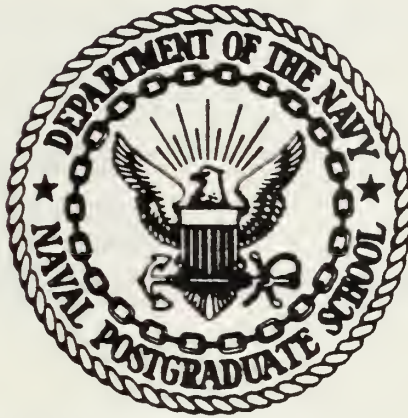
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THESIS

PRELIMINARY MEASUREMENTS AND CODE
CALCULATIONS OF FLOW THROUGH A CASCADE
OF DCA BLADING AT A SOLIDITY OF 1.67

by

William D. Molloy Jr.

June 1982

Thesis Advisor:

Raymond P. Shreeve

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Preliminary Measurements and Code
Calculations of Flow through a Cascade
of DCA Blading at a Solidity of 1.67

by

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Lieutenant Commander, United States Navy
B.S., United States Naval Academy, 1974

Submitted in partial fulfillment of the
requirements for the degree of

MASTER OF SCIENCE IN AERONAUTICAL ENGINEERING

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June 1982

ABSTRACT

An experimental program to obtain uniform inlet flow to the test blading in a large cascade facility designed to use inlet turning vanes, and to measure the conventional blade element performance, is described. Attempts to reduce non-uniformities ($\pm 1\%$ in velocity) using screens were unsuccessful and so abandoned. Preliminary DCA blade element performance data were obtained without screens at one incidence angle before aero-mechanical problems with the inlet guide vane assembly curtailed testing. The blade surface pressure distribution at the one test condition compared very favorably with the distribution predicted using the NASA computer code QSONIC. Recommendations were made that would avoid the aero-mechanical problems encountered.

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LIST OF SYMBOLS

AVDR	Axial velocity-density ratio
C_{P_1}	Coefficient of pressure at the inlet
C_{P_2}	Coefficient of pressure at the outlet
$C_{P_{STATIC}}$	Coefficient of static pressure rise
C	Blade chord (inches)
D	Diffusion factor
i	Incidence angle (degrees)
P	Pressure (in. H ₂ O)
Q	Dynamic pressure (in. H ₂ O)
T	Temperature (°R)
X	Non dimensional velocity
β	Air angle, measured in the cascade midspan plane with respect to the axial direction (degrees)
γ	Stagger angle
σ	Solidity (C/S)
$\bar{\omega}$	Loss coefficient

Subscripts

amb	Ambient
P	Pressure
PLENUM	Plenum (supply)
s	Static
wl	North wall, lower plane

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I. INTRODUCTION

The need for lightweight, fuel efficient gas turbines that are capable of developing large amounts of thrust or power has motivated a continuing drive to obtain more accurate predictions of the flow through turbomachinery. Cascade testing of blade rows has, in the past, been a logical and relatively inexpensive way to learn more about the phenomena involved in the flow through compressor and turbine stages. It is required more today in order to verify two dimensional and near-two dimensional analysis codes for flow through cascades. Such testing also provides two-dimensional blade element performance data which, in the absence of reliable analytical predictions, are required in the design of compressors and turbine stages. Reference 1 describes how cascade measurements are obtained using a cascade wind tunnel and then used in the design process.

Before subsonic cascade wind tunnel data can be accepted as being valid, the flow conditions must meet three requirements. These criteria are discussed in detail in Refs. 1, 2 and 3. First, any disturbance in the airflow should be caused by the test blades; that is, the inlet flow to the test section must be acceptably uniform.

Secondly, the measured flow characteristics should, ideally, be independent of spanwise position along the test

blades. The flow, ideally, should be two dimensional. Duval [Ref. 3] demonstrated that excellent flow conditions could be achieved in the Naval Postgraduate School Turbo-propulsion Laboratory (NPS/TPL) Subsonic Cascade Wind Tunnel using test blades with an aspect ratio of approximately two. The absence of suction along the walls results however, in some degree of streamline contraction which is measured in terms of an Axial Velocity Density Ratio (AVDR).

The third requirement which must be satisfied is the periodicity of the inlet flow to the test section and of the outlet flow. Within one chord length of the leading edges of the test blades an upstream perturbation occurs as the streamlines adjust to negotiate the blade passages. Since the rectilinear cascade is simulating an infinite cascade of blades, the flow characteristics should be the same at corresponding axial and blade-to-blade positions within each blade passage. This same condition should be true at any measurement plane downstream of the test blading.

As described by Rose and Guttormsen [Ref. 4] several unique features were incorporated into the design of the NPS/TPL Cascade to ensure a two-dimensional and periodic flow at the test blading. Initial evaluations of the facility were conducted and reported in Refs. 3, 4, 5 and 6. Work by Moebius [Ref. 6] involved modifications to the tunnel plenum chamber which established satisfactory uniform

flow at the exit of the bellmouth contraction into the test section.

In order to maintain an aspect ratio close to 2.0 at a solidity of 1.67 Cina [Ref. 7], following the work of Duval [Ref. 3], used a cascade configuration of 20 blades with 3 inch spacing. Cina conducted a program of tests of DCA blading at five (5) different air incidence angles. With this cascade configuration, Cina found that the inlet flow to the test section was uniform in direction and of uniform static pressure, but with an imposed variation in velocity and stagnation pressure resulting from the wakes of inlet guide vanes. Although excellent periodicity was found over pairs of test blades, departure from strictly periodic conditions were detected from one blade passage to another. Cina explained this condition as being the result of the inlet guide vane wakes being separated at two inch intervals and entering a test section configured with a three inch blade spacing. Because of these flow conditions, Cina considered his results to be preliminary.

As a result of these findings the Cascade Wind Tunnel was modified so that inlet guide vanes were provided at one inch intervals. The object of the study reported herein was to obtain blade performance data on Cina's cascade with good periodic and uniform flow conditions. A necessary condition was to obtain agreement in the results for blade forces evaluated from surface pressures and from a momentum

balance. A second objective was to compare measured blade surface Mach numbers with the results of code calculations.

At the outset, it was first necessary to carry out an extensive testing program to verify the new inlet guide vane section and the effect the new spacing had on flow uniformity and periodicity. It was found that the uniformity of dynamic pressure was improved with the inlet guide vanes spaced at one inch intervals. Attempts were made to further improve the flow by the use of (various) wire screens placed downstream of the inlet guide vanes. These methods proved unsuccessful for the range of parameters tested and in fact aggravated the situation.

Cina's testing of the Double Circular Arc blading was repeated without screens and with the Cascade Wind Tunnel configured with the modified inlet guide vane arrangement. Limited measurements were obtained before aero-mechanical problems with the new IGV arrangement, at the higher tunnel speeds, were encountered.

The overall purpose of the testing program initiated by Cina was to obtain data with which to verify design optimization computer codes developed by NASA. Towards this goal a fast, reliable computer analysis code (QSONIC) for calculating the flow field about a cascade of arbitrary 2-D airfoils was obtained from NASA. The code was adapted and modified to run on the Naval Postgraduate School's IBM 370/3033 computer.

The program QSONIC was developed by NASA to overcome the Mach number limitations of the earlier program TSONIC [Ref. 8]. QSONIC is described in Ref. 9. Procedures for using the program QSONIC at the Naval Postgraduate School's computer facility are given in Appendix D. The procedures are documented for the case of the DCA blading in the NPS/TPL cascade wind tunnel. A program listing is included to document changes made to the code in order to adapt to the operating system of the NPS computer.

Preliminary results show that experimental measurements and code predictions are in very good agreement.

II. FACILITY DESCRIPTION AND MEASUREMENT APPROACH

A. SUBSONIC CASCADE WIND TUNNEL

The Naval Postgraduate School's Rectilinear Cascade Facility is shown in Fig. 1. A description of the facility as it was originally configured is given in Ref. 4. The test facility is an open cycle wind tunnel, designed for the purpose of testing cascades of axial-flow turbomachinery compressor or turbine blades. The unique design of the test section ensures that the airflow paths from the inlet guide vanes to all of the blades of the cascade test section are of equal length. This particular design was intended to eliminate the problems found in other cascade wind tunnels caused by having wall boundary layers of different thicknesses entering the cascade at different points.

As a result of the work reported in Ref. 1, two fine mesh screens were installed at the bellmouth entrance to improve flow stability. A follow-on study into the cascade performance was conducted by Bartocci and is reported in Ref. 5. As a result of Bartocci's findings, plenum turning vanes were installed to direct plenum inlet air towards the bellmouth entrance and to decrease the total pressure fluctuations present at the bellmouth entrance. Figure 2 shows the configuration of the plenum chamber as modified by Bartocci. Reference 6 describes work by Moebius that resulted

in further modification to the plenum chamber in which the original contraction was changed to two two-dimensional contractions in series. After this modification, acceptably small variations in velocity and flow angle were measured at the inlet guide vane station. Figure 3 shows the internal arrangement of the plenum chamber as modified by Moebius and as it was configured for the work presented here.

Using the plenum configuration shown in Fig. 3, Duval [Ref. 3] found that the wakes from the inlet guide vanes were not mixed out at the lower measuring plane of the test section but gave a well defined periodic variation in the impact pressure. The peak-to-peak variation was $\pm 4\%$ of dynamic pressure over two-inch periodic intervals. This condition was undesirable, but was tolerated while looking only to establish the values of parameters required to achieve two-dimensionality and periodicity. Since the inlet flow conditions were not uniform, mass averages were used to calculate properties at the inlet plane from probe measurements.

In order to achieve a solidity of 1.67 and aspect ratio of about 2, a blade spacing of 3 inches was required for the tests carried out by Cina [Ref. 7]. The tests showed unacceptable departures from blade-to-blade periodicity under conditions of high blade loading and the installation of additional guide vanes was recommended. The modification

to the inlet guide vane section of the tunnel resulting from Cina's findings is described in detail in Appendix A.

In the present work, several tests were completed with the tunnel further modified by the introduction of wire screens between the inlet guide vanes and the lower plane of the test section. Appendix B describes the screen material and the criteria used to select the particular screens used in this study.

B. INSTRUMENTATION

The instrumentation used in the present study is that which is described in detail in Ref. 7. Twenty static pressure taps were located on the north and south side walls. The taps on the south wall were connected to a water manometer board so that the uniformity of the static pressure distribution of the inlet and outlet could be monitored visually. Additionally, one upstream tap on each wall and one downstream tap on each wall (near the centerline) were also connected to the Scanivalve so that these static pressures were recorded.

Figure 4 shows the probe that was used for the upstream survey (at the lower plane). The probe was a United Sensor Corporation DA 125 probe, serial number A847-1, calibrated earlier at various Mach numbers and yaw angles in a calibration facility. The United Sensor Corporation DC-125-24-F-22-CD probe, serial number A981-2 (Fig. 5), which was used

at the upper plane was similarly calibrated. The characteristics of the probes were approximated analytically to facilitate automatic data reduction procedures. The calibration and application procedures were those given by Duval [Ref. 3]. Appendix B of Ref. 3 describes both the upstream and downstream probes in detail. The mounting and traversing mechanisms are described in Ref. 7.

C. REFERENCE MEASUREMENTS

Plenum chamber (supply) pressure and temperatures, and atmospheric pressure were recorded on each data scan. Plenum pressure was also displayed on a water manometer board. The total temperature in the test cascade was assumed to be the same as the plenum chamber temperature.

D. TEST BLADING

The double circular arc test blading modeled the midspan section of the stator of the compressor stage reported in Ref. 10. Coordinates describing the profile of the blading are listed in Table D-2. The leading edge and trailing edge are shown in detail in Fig. 6. A photograph of the centermost blade is shown in Fig. 7.

The three blades centrally located in the cascade were constructed with surface pressure taps along the midspan section as shown in Fig. 8. The centermost blade had 19 ports on each of the pressure and suction surfaces and one tap at the leading edge. The two blades adjacent to the

center blade had 3 surface pressure taps located on each of the pressure and suction surfaces. The surface pressure tap locations for the centermost blade are given in Fig. 9.

E. DATA ACQUISITION, REDUCTION AND ANALYSIS

Data were recorded, reduced, and plotted using the modified Hewlett Packard HP-3052A Data Acquisition System shown in Fig. 10. Reference 11 describes the system in detail. The system incorporated a HP-9845A desktop computer as a controller, with all components connected on the HP-98034A HP-IB Interface Bus. A NPS/TPL HG-78K Scanivalve Controller with two 48 port Scanivalves allowed the programmed acquisition of probe and blade surface pressure measurements.

The software used in the present study for acquisition, reduction and plotting of data were developed from software originally created by Duval and Cina. The programs are listed and described separately in Ref. 12.

The uncertainties in the measurements are listed in Table 1.

III. EXPERIMENTAL PROGRAM AND RESULTS

A. PROGRAM OF TESTS

The test program was in three phases. First, in order to verify the new inlet guide vane assembly, tests were conducted with no blading in the test section and with the upper and lower endwalls set parallel at 35° (design condition), 30° and 50° with respect to axial.

Secondly, tests were made of the effect of wire gauze screen materials in reducing non-uniformities in the flow entering the test section. Appendix B describes the type of screens used and how they were installed.

The last phase of the test program was a continuation of the work initiated by Cina. Table II lists the cascade configuration tested. One test was completed successfully before aero-mechanical problems were encountered and testing was halted until the causes were analyzed.

B. TEST PROCEDURES

1. Cascade Adjustments

In the first and second phases of testing, the same procedures were used to realign the cascade for each new configuration. The lower and upper end walls were set to the desired flow angle and the inlet guide vanes were set so that their trailing edges were approximately aligned with

the end walls. The flow was started, and the desired inlet dynamic pressure was set. All tests were run at an average dimensionless inlet velocity (X) of about .13, corresponding to an inlet flow dynamic pressure of 18 inches water. Before recording data, the water manometer board was checked to ensure that the distributions of wall static pressures at the inlet plane and outlet plane were acceptably uniform. If required, the inlet guide vanes were adjusted to obtain uniform static pressure to within ± 0.5 inches of water.

In the third phase of testing, initially the procedures used by Cina [Ref. 7] were followed, namely: the lower end walls were set to the desired inlet air angle and the upper end walls were set approximately to the expected exit air angle. The inlet guide vanes were set very approximately and the cascade was turned on and set to an inlet dynamic pressure of 18 inches water. The upper end walls and the inlet guide vanes were adjusted in turn to obtain wall static pressure distributions upstream and downstream which were acceptably uniform. Using this procedure however it was found on occasion that the inlet air angle sensed by the probe at the lower plane at mid-span could be 2 or 3 degrees different from the setting of the end walls.

The following procedures was subsequently adopted. The lower end walls were set to the desired inlet air angle. The upper end walls were adjusted to be "wide open", to form a diverging passage in which, when the cascade was turned

on (to an inlet dynamic pressure of 18 inches water), the flow was completely separated. The inlet guide vanes were adjusted to obtain the required inlet air angle on the channel center line over the center 24 inches in the blade-to-blade direction. The upper end walls were then moved individually towards the vertical until the lower plane static pressure distribution was uniform and the upper plane static pressure distribution was acceptably uniform at a value close to atmospheric pressure. No readjustment of the inlet guide vanes was made.

2. Measurements

Probe surveys were carried out in the blade-to-blade direction at midspan at the upper and lower planes. In the first and second phases of testing, data were taken over approximately 24 inches of the test section at intervals of 0.25 inches. Also, in order to test the repeatability of measurements, repetitive samples were taken with the probe held fixed at midspan at the lower plane at the center, 10 inches to the right and 10 inches to the left of center.

During the third phase of testing, data were taken using the procedures established by Cina in Ref. 7.

C. VERIFICATION OF INLET GUIDE VANE (IGV) ASSEMBLY

The results of the first phase are presented (as shown in Table III) in Figs. 11 to 32. The results are arranged into groups. The first group (Figs. 11 to 14) are

measurements of tunnel conditions with the end walls set at 35 degrees. Plots of conditions at the lower plane are followed by plots of conditions at the upper plane.

Results for a wall angle of 30 degrees are given next (Fig. 15 to Fig. 18), followed by results for a wall angle of 50 degrees (Fig. 19 to Fig. 21). Data were taken over 24 inches at the lower plane, and also at the upper plane at 30°. At 50°, at the upper plane, only the center 12 inches were surveyed.

The degree of repeatability of conditions in the wind tunnel from test to test (with no change in wall setting) is demonstrated by the results plotted in Figs. 22, 23 and 24.

The last group of plots, Figs. 25 to 33, shows the degree of repeatability in the probe data from scan to scan. Data for these plots were obtained by holding the probe stationary at midspan in three specific blade-to-blade locations in turn and taking 50 repetitive scans of the channels normally recorded for survey profile data. The time interval for each scan was approximately 20 seconds.

D. TESTING WITH WIRE GAUZE SCREENS

The selection and installation of the wire gauze screens is described in Appendix B.

The measurements obtained with the various screen configurations are given (as shown in Table IV) in Figs. 34 to 45. The results are arranged in four groups.

The first group of plots (Fig. 34 to 40) give data obtained with the 16 mesh .0105 inch diameter wire screen installed. Over a blade-to-blade distance from -1.0 to 7.0 inches (Fig. 35) a peak-to-peak variation in velocity of about 1 percent was noted. This is slightly greater than the less than 1 percent (0.9 percent) variation noted over the same survey region without a screen installed (Fig. 12).

The results shown plotted in Figs. 41 and 42 were obtained with two screens installed. One screen (16 mesh, .0105 inch diameter) was installed as discussed in Appendix B, while the second screen (2 mesh, .0400 inch diameter) was attached across the duct at the leading edges of the inlet guide vanes.

The fourth group of plots (Figs. 43 to 46) show the results for two different single screens. Probe survey data for these screens was taken only at the lower plane. The results shown plotted in Figs. 43 and 44 are data obtained with a 4 mesh, .041 inch diameter wire screen installed. The variation in velocity in the blade-to-blade direction was as much as ± 1.1 percent, peak-to-peak. The results shown in Figs. 45 and 46 are for a 5 mesh, .041 inch diameter wire screen. The variation in flow velocity was approximately ± 1.5 percent, peak-to-peak.

E. PRELIMINARY TESTING OF DCA BLADES

The results contained in Tables V to IX and Figs. 47 to 60 are arranged in the following manner.

The results shown plotted in Figs. 47 to 60 are divided into two separate groups. The first group (Figs. 47 to 57) contain results which exhibit the quality of the wind tunnel flow conditions. The second group (Figs. 58 to 60) shows the blade forces (and surface pressures) from survey data. In the first group of figures, results are presented first to examine the inlet flow uniformity (Figs. 47 and 48); second, to examine the outlet flow periodicity (Figs. 49 to 53); and, finally, to examine outlet flow two dimensionality (Figs. 54 to 57).

All points are shown connected with straight lines.

IV. DISCUSSION OF EXPERIMENTAL RESULTS

A. EFFECT OF INLET GUIDE VANE (IGV) MODIFICATION

The probe survey data shown in Figs. 11 and 12 were taken at the lower plane, with the end walls set at 35 degrees. A turning angle of 35 degrees corresponded to the "design point" of the inlet guide vanes, when the airflow from the plenum chamber was at zero angle of incidence to the leading edge of the IGV's. These two figures show that the inlet plane total pressure at midspan in the blade-to-blade direction had a peak-to-peak periodic variation of about ± 2 percent and therefore about a ± 1 percent peak-to-peak variation in the velocity. Corresponding data from probe surveys at the upper plane (Figs. 13 and 14) show that periodic variations in total pressure were reduced to about 25% of the value at the lower plane by the mixing of the inlet guide vane wakes.

It can be seen in Figs. 15 to 21 that at "off-design" conditions for the IGV's (endwalls at 30° and 50°) there is a greater periodic variation in total pressure at the lower plane in the blade-to-blade direction than at the design point conditions. In Fig. 15 and Fig. 16, it can be seen that the periodic variations in total pressure are more pronounced with the flow from the plenum at a negative incidence angle to the IGV's (endwalls at 30°). Except for the first

8 data points in Fig. 15, there is a well defined period of about 1 inch of travel.

Figures 19 and 20 show the probe surveys conducted with endwalls at 50 degrees. At this off design condition the periodic variation in total pressure was considerably greater than the design point and the individual wakes from the inlet guide vanes were much less well defined.

The repeatability of the survey was examined at wall angles of both 50° and 30° . Figs. 22 to 24 show that the non-uniformities in the flow conditions were repeated to (generally) better than 0.5 percent of total pressure. The question was then, to what accuracy could the individual data points be repeated in successive samples. This was examined at several probe positions and the results given in Figs. 25 to 33 explain the departures in Figs. 22 to 24.

B. EFFECT OF WIRE GAUZE SCREENS

All testing with screens was conducted with the end walls and inlet guide vanes set to yield a flow angle of 35 degrees. The data obtained with screens installed were therefore compared with the data obtained without screens, shown in Figs. 11-14. The effect of the pressure drop across the screen on the pressure coefficient plotted in Figs. 34-35 should be noted. With the first screen installed the drop in total pressure from plenum to the probe in the lower plane was about 10 inches of water (plenum pressure minus total

pressure measured by the probe at the lower plane). Without the screen (at design conditions), the pressure drop from the plenum to the probe at the lower plane was approximately 2.0 inches of water. Since Q_{ref} was defined as the difference between plenum pressure and lower wall static pressure, the value of Q_{ref} with the first screen installed was about 28 inches water and without the screen installed, about 20 inches water. In comparing the peak-to-peak variation in P_1 seen in Fig. 11 with that obtained with the first screen installed in Fig. 34, the difference in the values of Q_{ref} must be considered. Examinations showed that the peak-to-peak variation in velocity remained at approximately 1% when the screen was installed.

Figures 38 to 40 are plots of data obtained during a spanwise traverse of the probe at the lower plane. These figures show that the pressure drop through the screen and turning vanes was nearly uniform over approximately 8.0 inches of the 10.0 inch span of the tunnel.

In an attempt to generate upstream disturbances that might trigger early boundary layer transition on the IGV's and increase the rate of mixing of the wakes, a second screen was attached to the leading edge of the IGV's. The results in Figs. 41 and 42 showed that this was not the case and in fact the second screen increased the magnitude of the non-uniformities at the lower survey plane. Measurements made with a single 4 mesh (Figs. 43 and 44) and a single 5 mesh

screen (Figs. 45 and 46) of similar blockage showed that neither screen influenced the flow in a particularly favorable manner. The 4 mesh screen caused the peak-to-peak variation in velocity to be about ± 1.1 percent, while the 5 mesh screen caused the variation to be about ± 1.5 percent. This compared unfavorably with the variation obtained without any screen installed which was less than ± 1 percent.

It was therefore decided to proceed with measurements of the test cascade without using screens.

C. PRELIMINARY TESTING OF DCA BLADES

1. Inlet Uniformity

The probe survey at the lower plane in Fig. 48 shows that the inlet plane total pressure at midspan varied in the blade to blade direction less than 0.5 inches of water, with no well-defined spatial period. This was an improvement in the inlet conditions found by Cina [Ref. 7: Fig. 16]. That the spatial period was not well defined agreed with the findings presented earlier in this report. The wall static pressure distribution (Fig. 47) showed small variations (less than 0.5 ins. water peak-to-peak at the lower plane, .4 ins. water peak-to-peak at the upper plane).

2. Two-Dimensionality

The data in Figs. 54 to 57 show that, at the downstream plane, an area of (spanwise) nearly uniform conditions

existed near the centerline of the cascade. Reference 2 points out that at higher loadings it is difficult to establish a substantial spanwise area of uniform flow in the region near the suction side of the blade. This difficulty is evident in the data shown in Figs. 54 and 55 which show that only about 20% of the spanwise distance is acceptably uniform. It is noted that Cina also found reduced areas of uniform flow at this incidence angle; however, 30-40% of the spanwise distance was found to be acceptably uniform in his case. The difference could be the result of the reduced spacing of the IGV's and its effect on the side wall boundary layers.

Figure 58 shows results for inlet and outlet flow angles and blade force vectors derived in two ways as shown in Appendix B of Ref. 7. These two methods are first the applications of momentum conservation to probe survey data and second, the integration of surface pressures measured over the blade area. Reference 2 points out that for truly two dimensional flow the blade forces derived from the two methods should be the same. As shown in Fig. 58 the magnitudes and the directions of the two vectors representing the blade forces are in reasonable agreement. It is noted however that at this particular incidence angle Cina [Ref. 7] measured blade forces that were in total agreement in direction but disagreed slightly in magnitude. The values of the

force magnitudes were about 1.5% lower than those measured by Cina.

3. Periodicity

As can be seen in Figs. 50 and 51 the total pressure and velocity qualitatively repeated fairly well over three central blade passages. Acceptably small quantitative differences are noted. There was also a small but measurable difference in the surface pressures on adjacent blades, as is evidenced in Fig. 49.

4. Blade Performance

Figures 59 and 60 are plots of the pressure and velocity distributions respectively over the centermost blade. These results compare favorably to those obtained by Cina for an incidence angle of 5.3° .

Table IX contains the blade performance parameters deduced from the probe survey data listed together with the data obtained for corresponding test parameters in Ref. 7. While differences in two sets of data are evident, the differences are not large. It is noted that the value of the loss coefficient was only 10% lower than was measured by Cina, but the AVDR was less than 2% different from unity rather than the 6.5% measured by Cina. Further measurements need to be made, particularly in the light of the following discussion, before stronger conclusions can be drawn.

5. Aero-Mechanical Problems Encountered

Fifteen cascade tests were made while evaluating the new inlet guide vane assembly and testing the wire screens. All runs were made without test blades installed, with a plenum total pressure of about 20 inches of water and with the upper and lower end walls parallel. No difficulties were encountered in establishing the desired flow conditions or in using the inlet guide vanes to arrive at a satisfactory distribution of wall static pressures.

The first time the Cascade Wind Tunnel was set up with test blades installed to take data at an air inlet angle of 39.2° , the tunnel operated normally and the test was completed. (The data from this test were subsequently found to be highly suspect and are not reported here.) During the next test, with an inlet air angle of 42.4 , the start-up appeared normal and previously established procedures were used to arrive at a satisfactorily uniform wall static pressure distribution. Tunnel operation appeared to be normal while taking data, but on shutdown a very noticeable high frequency vibration was encountered. Examination of the inlet guide vanes revealed that about 40% of the 60 blades were damaged. Damage included chips missing from the trailing edges, blades bent, cracks at the weld where the blade is joined to its support and indications that the suction side near the leading edge of one blade had been vibrating

against the pressure side near the leading edge of an adjacent blade.

After the inlet guide vanes had been repaired and reinstalled extreme care was used at the beginning of the next test to adjust the inlet guide vanes, with two individuals monitoring the movement of the adjustment mechanism. (IGV adjustment mechanism is described in detail in Appendix A.) A lack of stiffness in the mechanism was suspected as having been a contributing factor to the failure.

One successful test was completed at an inlet flow angle of 42.4° and these data were discussed above.

With the next cascade configuration set, at an air inlet angle of 45.9° , when the IGV's were adjusted after starting up, high frequency vibrations were again experienced. The wind tunnel was shut down and no further testing was attempted at plenum total pressures as high as 20 inches of water gauge.

The difficulty encountered with the IGV's is not fully understood, however the lack of stiffness present in the actuation of the two separate rows of vanes is suspected of having allowed the problem to occur. Certainly, the possibility of an aerodynamic flutter condition being present (due to the misadjustment perhaps) can not be ignored. It was noticed after the initial failure that the lead screw which adjusts the IGV's could be turned but the blades mounted from only one side would be caused to rotate. This

could lead to the trailing edge of one blade contacting the trailing edge of an adjacent blade and effectively closing the blade passages.

Also, the holes in which the cylindrical shanks of the IGV's were held were found not to be uniformly machined. As much as 0.1 inches of movement at the tip of some vanes was possible while others could barely move. (The most seriously damaged blades were found in or adjacent to the larger holes.)

The tendency for the mechanism to "hang-up" on one side would be greater as the vanes became more highly loaded. It is noted that the IGV problem was encountered first when going to increased incidence angles with the compressor test cascade installed. In setting a constant plenum total pressure of 20 inches of water gauge, the static pressure increase across the test blades to a constant atmospheric pressure at the downstream side implies that a progressively increasing dynamic pressure was being generated out of the turning vanes. This can be seen in Table IX, where Q_1 for the test at $\beta_1 = 42.4$ was 25 inches of water.

V. COMPUTATIONAL PROGRAM

A. DESCRIPTION OF QSONIC

The computational code, QSONIC, was developed by the staff at the NASA Lewis Research Center.¹ This code is able to calculate the blade-to-blade flow conditions in turbo-machinery blade rows assuming inviscid flow but including streamtube convergence and radius change in the throughflow direction. QSONIC is flexible enough to allow the input of the appropriate boundary conditions to calculate the flow through the test blading in the Subsonic Cascade Wind Tunnel. The program uses a fully conservative solution of the full potential equation combined with the finite volume method on a body-fitted mesh. QSONIC uses an artificial density imposed in the transonic region, if such a region exists, to ensure stability and the capture of shock waves.

The analysis used by QSONIC is a combination of transonic analysis methods to calculate the flow conditions in the vicinity of a cascade of airfoils. A conservative form of the full potential equation is discretized at every point of a body fitted periodic mesh and a mass balance is calculated through the finite volume surrounding the point. The volume

¹The help and advice received from Charles Farrell at NASA Lewis R.C. in the process of adapting QSONIC to the NPS computer is gratefully acknowledged.

is corrected three dimensionally for any change in stream-tube thickness along a streamtube, if a quasi-3D solution is desired. Either elliptic or hyperbolic non-linear partial differential equations are used, depending on the local Mach number.

The analysis used in developing QSONIC made the following assumptions:

- 1) The airflow is inviscid and adiabatic.
- 2) The airflow relative to the test blades is steady.
- 3) Air is a perfect gas with constant specific heat.
- 4) The airflow is isentropic and any discontinuities such as shocks are so weak that they may be approximated as isentropic jumps.
- 5) There is no velocity component normal to the streamsurface.
- 6) The airflow relative to a fixed reference frame (i.e. absolute velocity) is completely irrotational.

Assumption 4 requires that the peak local relative Mach number on a blade surface be 1.4 or less. The Mach numbers measured in test blades in the Subsonic Cascade Wind Tunnel would be well within this limit. However, this limitation would probably preclude the use of QSONIC for analysis of the flow field in the NPS transonic cascade wind tunnel.

There are some combinations of blading geometry and flow conditions which cause unsatisfactory results to be generated. For example, because of assumptions 1 and 6, sharp leading edges at high incidence angles (more than a few degrees) cause large velocity peaks in the blade surface as

the flow tries to turn from the stagnation point to the suction surface.

Reference 9 gives a detailed description of QSONIC and the solution method used including the governing equations. Appendix D describes the operating procedures to use QSONIC on the Naval Postgraduate School's IBM 370/3033 computer. Appendix D also describes the input and output required as applicable to the Subsonic Cascade Wind Tunnel.

B. APPLICATION TO THE TEST CASCADE

Appendix D describes in detail the generation of the input required for QSONIC when applied to test blading in the Subsonic Cascade Wind Tunnel facility. In the present work one comparison of code calculations and measured data was made before testing was stopped. The comparison was for an inlet flow angle (β_1) of 42.4° .

Tables D.1 and D.3 show the input data generated. Table D.6 shows the flow solution output by QSONIC. The flow calculated on the blade surface, using a 15 by 97 mesh, was examined. Figure 61 is a plot of the calculated Mach number along the blade surface using two dimensional inputs. Figure 62 is a plot of computed Mach number incorporating quasi-three dimensional effects. The method of incorporating quasi-three dimensional effects is explained in Appendix D.

C. COMPARISON OF CODE CALCULATIONS AND MEASURED DATA

Table VII lists the data measured in the cascade wind tunnel. C_{p1} , C_{p2} and X_{vel} are defined in Appendix C. The surface Mach number distribution measured on the center blade is shown plotted in Fig. 63.

For comparison, the computed two dimensional, computed quasi-three dimensional, and the Mach number measured in the cascade wind tunnel are plotted together in Fig. 64.

Excellent agreement between all three cases is seen. As would be expected, the greatest difference between measured and calculated data is near the leading edge in the suction side and at the trailing edge of the blade.

VI. CONCLUSIONS AND RECOMMENDATIONS

Based on the results of the first part of the present study, to evaluate the effects of the altered inlet guide vane spacing on flow uniformity and periodicity, the following conclusions were drawn:

1. With the inlet guide vanes operating at design, the peak-to-peak variation in velocity was about $\pm 1\%$, and there was a well defined spatial period of about 1 inch.
2. Operating the cascade wind tunnel in a configuration that requires the inlet guide vanes to be set to other than zero incidence resulted in peak-to-peak variations in velocity greater than $\pm 1\%$ and a spatial period that was less well defined.

The second part of the study, to evaluate the use of wire gauze screens to further reduce the non-uniformities in the flow field, led to the following conclusions:

1. A 16 mesh screen with a blockage factor of .69 had a slightly aggravating effect in the variation in velocity. The peak-to-peak variation in velocity with the screen installed was slightly greater than with no screen installed. This occurred at the expense of a pressure drop of about 10" of water across the screen.
2. The use of screens with similar blockage but with larger mesh and larger diameter wires resulted in larger peak-to-peak variations in the velocity at the lower plane.

The overall objective of the present study was to measure the performance of the DCA test blading. Because of aero-mechanical problems encountered with the inlet turning vanes the performance of the blades was obtained at one

incidence angle only. The following was concluded from the limited test program:

1. As a result of the reduced inlet guide vane spacing the variations in velocity and total pressure at the inlet plane were much less than those reported by Cina.
2. Good periodicity was found from one blade passage to another.
3. An acceptable region of spanwise uniformity (20-40% of blade span) was found at the downstream plane at the one test condition reported. However, this was less than was previously reported for the same incidence angle.
4. The blade forces derived from the integration of surface pressure measurements and probe survey data were in close agreement in both magnitude and direction.
5. The Mach number measured by surface pressure taps over the surface of the blade and Mach number calculated using the program QSONIC were in excellent agreement qualitatively and reasonable agreement quantitatively.
6. The specific reasons for the aero-mechanical problems experienced with the inlet turning vanes have not been identified completely.

Based on these conclusions and other observations, the following recommendations are made:

1. Use of the present inlet guide vane assembly and adjustment mechanism for testing at inlet dynamic pressures higher than about 15 inches of water is unsafe. There are three possible solutions to this problem.
 - a) Operate only within the dynamic pressure range of 10-15 inches of water.
 - b) Modify the new inlet guide vane assembly so that the vanes are supported at both ends on their axes of rotation. [Supporting the IGV's from both ends would prevent flapping vibrations of the (presently) cantilevered vanes. Such vibrations, when the vanes are supported alternately from opposite ends and the gaps are small compared to the chord, might lead to a potentially destructive flutter mode at particular flow velocities.]

- c) Replace the entire inlet turning vane section with one of entirely new design.
- 2. The procedure should be adopted immediately of adjusting the vanes and walls of the cascade at lower values of the dynamic pressure before increasing the blower speed to the desired operating condition.
- 3. More time needs to be spent to examine the flow field produced between the guide vanes and the test blades, and to establish the effects of the movement of the tail boards. The uniqueness of the flow field when the wall static pressure uniformity is used as a criterion of good inlet flow, needs to be examined by conducting repetitive tests at nominally similar test parameters. Only when the adjustment of the flow in the facility and the quality of the flow itself is fully understood should the measured blade performance data be accepted as final.
- 4. The upper electrical yaw adjustment mechanism should be replaced with a manual system to greatly decrease the time required to achieve probe pressure (angle) balancing.
- 5. Develop the computer code necessary to take advantage of the plotting data created by QSONIC.
- 6. Modify the data acquisition and reduction software for the HP 9845 so that real time plots of blade performance parameters can be displayed.

TABLE I. MEASUREMENT UNCERTAINTY

Item	Description	Method	Uncertainty
x	Blade-to-Blade dimension x = 0 in. West end x = 60 in. East end	Position Potentiometer	$\pm .01$ in.
z	Spanwise dimension z = 0 in. North wall z = 10 in. South wall	Position Potentiometer on probe mount	$\pm .01$ in.
β_1	Inlet flow yaw angle	Angle Potentiometer on probe mount (hand adjustment)	$\pm .2$ deg.
β_2	Outlet flow yaw angle	Angle Potentiometer on probe mount (motor driven adjustment)	$\pm .5$ deg.
P_{plen}	Plenum total pressure	Static tap in plenum chamber $V \approx 0$	$\pm .01$ in. H_2O gauge
P_s	Static pressure at the test plane	Calibrated pneumatic probe	$\pm .1$ in. H_2O gauge
P_{wl}	Static pressure at x = 0 in., y = -16.25 in., z = 0 in.	Static tap on North wall	$\pm .01$ in. H_2O gauge
P_{ATM}	Atmospheric pressure	Absolute Strain Gauge Transducer	$\pm .3$ in. H_2O
P	Pressure	Scanivalve Transducer	$\pm .01$ in. H_2O gauge

TABLE II. CASCADE CONFIGURATION FOR DCA BLADE TESTS

Constant Parameters

Number of Blades	20
Spacing (Pitch)	3 inches
Chord	5.01 inches
Solidity	1.67
Thickness	7.0 percent of chord
Camber Angle	45.72 degrees
Stagger Angle	14.72 degrees

Variable Parameters

β_1	42.4 degrees
i	5.3 degrees

TABLE III. SUMMARY OF MEASUREMENTS WITHOUT SCREENS

β_1	Survey Plane	Survey Direction	Fig. Nos.	Purpose
35	Lower	B-B (24 inches)	11 & 12	Flow Field Determination
	Upper	B-B (24 inches)	13 & 14	
30	Lower	B-B (24 inches)	15 & 16	
	Upper	B-B (24 inches)	17 & 18	
50	Lower	B-B (24 inches)	19 & 20	
	Upper	B-B (12 inches)	21	
50	Lower	B-B (24 inches)	22 & 23	Survey Repeatability
30	Lower	B-B (24 inches)	24	
30	Lower	Fixed Probe (10" L. of ζ)	25-27	Point Repeatability
		(on ζ)	28-30	
		(10" R. of ζ)	31-33	

TABLE IV. SUMMARY OF MEASUREMENTS WITH SCREENS

$$(\beta_1 = 35^\circ)$$

	<u>Screen</u>	<u>Survey Plane</u>	<u>Survey Direction</u>	<u>Fig. Nos.</u>
1.	16 mesh .0105 wire	Lower	B-B	34 & 35
		Upper	B-B	36 & 37
		Upper	Spanwise	38-40
2.	16 mesh .0105 wire + 2 mesh ahead of IGV's	Lower	B-B	41 & 42
3.	4 mesh .041 wire	Lower	B-B	43 & 44
4.	5 mesh .041 wire	Lower	B-B	45 & 46

TABLE V. PROBE DATA, UPPER PLANE AT MIDSPAN ($i = 5.3^\circ$)

DATA FROM FILE DBRED2:T14

BLADE TO BLADE TRAVERSE MIDSPAN

UPPER PLANE

Point	Loc(in)	Beta	P_{01}/Q_{1bar}	P_{s2}/Q_{1bar}	P_{t1}/Q_{1bar}	$W/Xbar$
1	-7.31	-1.59	.5686	.2614	.0920	.6475
2	-6.84	-1.84	.5532	.2669	.1041	.6381
3	-6.37	-1.83	.4276	.2561	.2396	.5630
4	-5.87	-2.56	.5096	.2707	.1380	.6149
5	-5.67	-2.56	.5622	.2638	.0995	.6428
6	-5.48	-2.56	.5780	.2534	.0902	.6530
7	-5.23	-1.79	.5739	.2573	.0916	.6503
8	-5.04	-1.79	.5747	.2626	.0927	.6483
9	-4.80	-1.78	.5697	.2578	.0952	.6480
10	-4.60	-1.78	.5705	.2588	.0901	.6495
11	-4.41	-1.78	.5687	.2575	.0955	.6478
12	-4.16	-1.36	.5650	.2591	.0994	.6451
13	-3.96	-1.35	.5629	.2606	.0987	.6443
14	-3.78	-1.36	.5462	.2682	.1123	.6333
15	-3.58	-1.36	.4863	.2684	.1739	.5978
16	-3.39	-1.35	.4349	.2611	.2269	.5677
17	-3.19	-1.88	.4239	.2571	.2456	.5597
18	-3.00	-3.16	.4886	.2738	.1668	.5989
19	-2.80	-2.41	.5467	.2744	.1108	.6318
20	-2.60	-2.19	.5717	.2636	.0962	.6461
21	-2.40	-1.92	.5751	.2608	.0951	.6482
22	-2.20	-1.92	.5773	.2597	.0926	.6498
23	-2.01	-1.92	.5814	.2599	.0926	.6507
24	-1.81	-1.92	.5810	.2612	.0951	.6493
25	-1.61	-1.48	.5765	.2606	.0901	.6502
26	-1.42	-1.47	.5755	.2644	.0912	.6483
27	-1.22	-1.48	.5748	.2626	.0947	.6476
28	-1.02	-1.46	.5679	.2661	.1004	.6430
29	-.83	-1.47	.5378	.2726	.1217	.6267
30	-.64	-1.46	.4704	.2693	.1954	.5862
31	-.44	-1.47	.4140	.2553	.2698	.5497
32	-.25	-1.47	.4295	.2658	.2442	.5594
33	-.05	-3.00	.5011	.2740	.1616	.6040
34	.15	-2.32	.5562	.2718	.1040	.6371
35	.36	-1.74	.5776	.2672	.0879	.6488
36	.55	-1.71	.5795	.2636	.0865	.6509
37	.75	-1.83	.5880	.2591	.0872	.6541
38	.95	-1.80	.5915	.2613	.0833	.6554
39	1.15	-1.83	.5902	.2591	.0844	.6555
40	1.35	-1.83	.5903	.2587	.0833	.6561
41	1.55	-1.83	.5810	.2601	.0922	.6506
42	2.35	-1.83	.4490	.2598	.2202	.5749
43	2.85	-1.84	.4421	.2670	.2278	.5681
44	3.34	-2.01	.5722	.2600	.0990	.6465
45	3.85	-2.01	.5763	.2597	.0972	.6481

TABLE VI. PROBE DATA, LOWER PLANE AT MIDSPAN ($i = 5.3^\circ$)

DATA FROM FILE LBRED2:T14

BLADE TO BLADE TRAVERSE MIDSPAN

LOWER PLANE

Point	Loc(in)	Beta	$Q/Q1bar$	$P_s/Q1bar$	$P_r/Q1bar$	$W/Xbar$
1	-4.00	-42.43	.9533	-.1372	.0932	.8457
2	-3.50	-42.42	.9603	-.1444	.0967	.8474
3	-3.00	-42.42	.9567	-.1427	.0996	.8454
4	-2.50	-42.44	.9614	-.1519	.1031	.8480
5	-2.00	-42.43	.9741	-.1469	.0871	.8524
6	-1.50	-42.43	.9767	-.1493	.0875	.8532
7	-1.00	-42.43	.9722	-.1481	.0889	.8522
8	-.50	-42.43	.9743	-.1564	.0921	.8546
9	0.00	-42.43	.9799	-.1567	.0935	.8540
10	.50	-42.42	.9849	-.1592	.0854	.8585
11	1.00	-42.43	.9814	-.1604	.0850	.8593
12	1.50	-42.43	.9871	-.1628	.0779	.8635
13	2.00	-42.43	.9787	-.1615	.0890	.8582
14	2.50	-42.43	.9742	-.1632	.0971	.8556
15	3.00	-42.41	.9731	-.1650	.1059	.8526
16	3.50	-42.42	.9807	-.1663	.0924	.8589
17	4.00	-42.44	.9736	-.1651	.0968	.8567

TABLE VII. CENTER BLADE DATA ($i = 5.3^\circ$)

α/c	T/C	C_{p1}	C_{p2}	Mach	Wet

PRESSURE SIDE CENTER BLADE					
.0007	.0054	.6655	.4573	.1785	.0796
.0160	.0019	.6417	.4140	.1849	.0824
.0319	.0066	.5240	.1999	.2136	.0951
.0479	.0112	.5287	.2083	.2126	.0946
.0658	.0215	.4871	.1327	.2219	.0988
.1213	.0303	.4818	.1230	.2231	.0993
.1956	.0452	.4700	.1017	.2257	.1004
.2695	.0576	.4757	.1120	.2244	.0999
.3433	.0663	.4764	.1133	.2243	.0998
.4192	.0716	.4892	.1366	.2215	.0986
.4930	.0736	.4871	.1327	.2219	.0988
.5669	.0727	.4771	.1146	.2241	.0997
.6407	.0678	.4956	.1482	.2201	.0979
.7146	.0601	.4889	.1359	.2216	.0986
.7884	.0487	.4949	.1469	.2202	.0980
.8283	.0411	.4672	.0965	.2263	.1007
.8683	.0327	.4537	.0719	.2292	.1020
.9082	.0230	.4245	.0189	.2354	.1047
.9481	.0123	.3815	-.0594	.2443	.1086
.9880	.0006	.2778	-.2482	.2646	.1175
SUCTION SIDE CENTER BLADE					
.0160	.0227	-1.3641	-3.2355	.4973	.2171
.0319	.0310	-.7756	-2.1647	.4249	.1867
.0479	.0389	-.4980	-1.6597	.3878	.1709
.0658	.0563	-.3541	-1.3979	.3675	.1622
.1213	.0710	-.3431	-1.3778	.3659	.1615
.1956	.0970	-.2923	-1.2853	.3585	.1583
.2695	.1170	-.2500	-1.2084	.3522	.1556
.3433	.1309	-.2038	-1.1243	.3453	.1526
.4192	.1399	-.1540	-1.0338	.3377	.1493
.4930	.1432	-.0854	-.9090	.3270	.1447
.5669	.1412	-.0584	-.8599	.3227	.1428
.6407	.1339	.0102	-.7351	.3116	.1380
.7146	.1209	.0631	-.6387	.3028	.1342
.7884	.1021	.1456	-.4887	.2886	.1280
.8283	.0895	.1911	-.4059	.2805	.1245
.8683	.0755	.2326	-.3303	.2730	.1212
.9082	.0593	.2636	-.2740	.2673	.1187
.9481	.0407	.2842	-.2365	.2634	.1170
.9880	.0206	.2948	-.2171	.2613	.1161

TABLE VIII. ADJACENT BLADES DATA ($i = 5.3^\circ$)

X/C	Y/C	Cp1	Cp2	Mach	Angle

PRESSURE SIDE LEFT BLADE					
.1218	.0303	.4014	-.0231	.2402	.1068
.4192	.0716	.4619	.0868	.2275	.1012
.8283	.0411	.4491	.0635	.2302	.1024
SUCTION SIDE LEFT BLADE					
.1218	.0710	-.3438	-1.3791	.3660	.1615
.4192	.1400	-.1505	-1.0273	.3371	.1491
.8283	.0895	.1975	-.3943	.2794	.1240
PRESSURE SIDE RIGHT BLADE					
.1218	.0303	.4640	.0907	.2270	.1010
.4192	.0716	.4658	.0939	.2266	.1008
.8283	.0411	.4597	.0829	.2279	.1014
SUCTION SIDE RIGHT BLADE					
.1218	.0710	-.3285	-1.3513	.3638	.1606
.4192	.1400	-.1519	-1.0299	.3374	.1492
.8283	.0895	.1911	-.4059	.2805	.1245

TABLE IX. BLADE PERFORMANCE DATA

	<u>Present Results</u>	<u>From Ref. 7</u>
β_1	42.42	42.42
i	5.3	5.3
β_2	1.85	0.4
δ	10.44	9.0
D	0.455	0.46
$\bar{\omega}$	0.037	0.041
$\frac{\omega \cos^3 \beta_2}{2 \sigma \cos^2 \beta_1}$	0.020	0.023
$\frac{\omega \cos \beta_2}{2 \sigma} (x 10^2)$	1.09	1.242
AVDR	1.015	1.065
$C_{PSTATIC}$	0.413	0.351
C_{xM}	-1.385	-1.380
C_{yM}	-0.669	-0.566
C_{xB}	-1.330	-1.476
C_{yB}	-0.572	-0.645
\bar{Q}_1 (in. H_2O)	25	22
\bar{X}	.14	.12

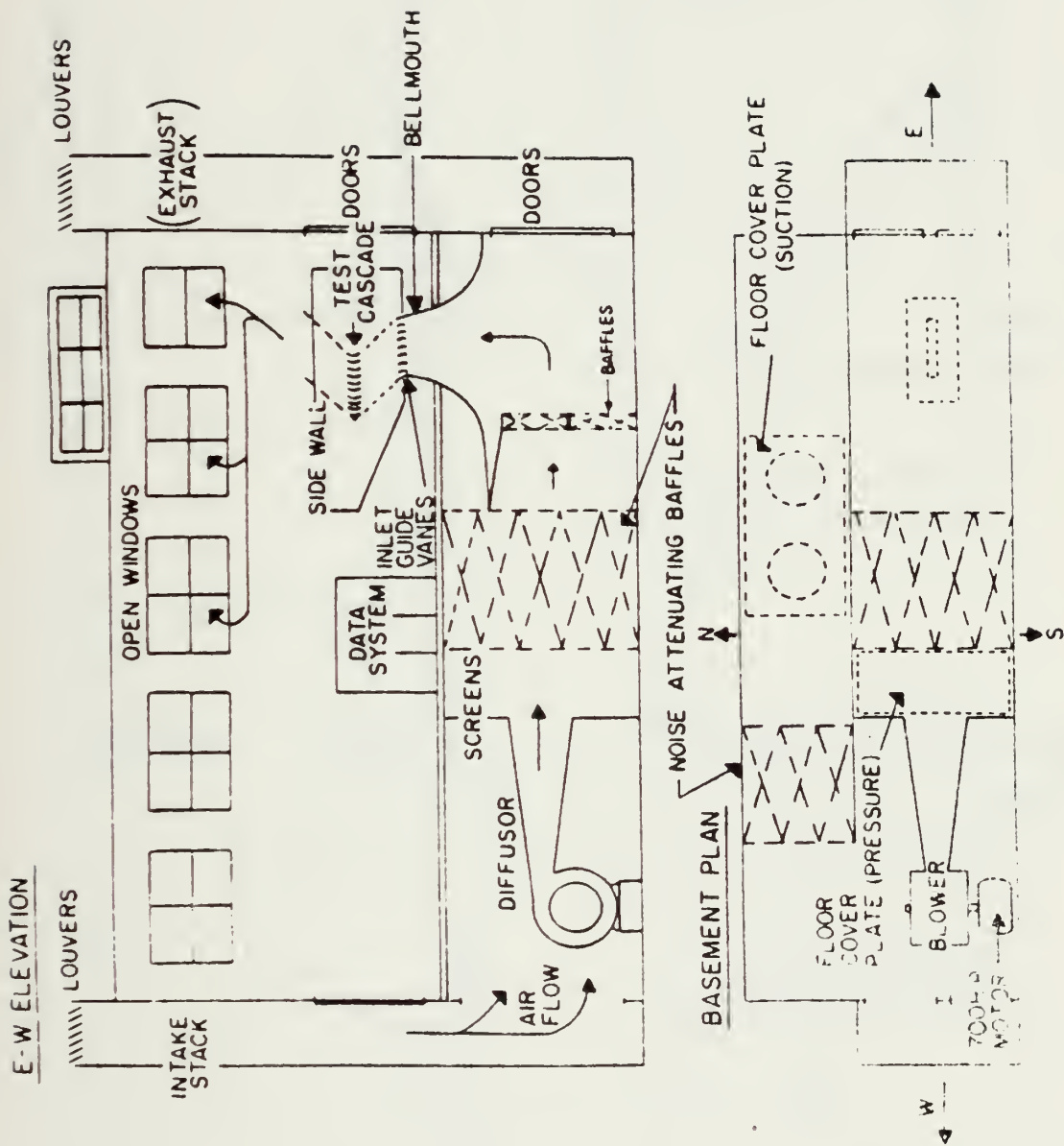


Fig. 1. Subsonic Cascade Facility

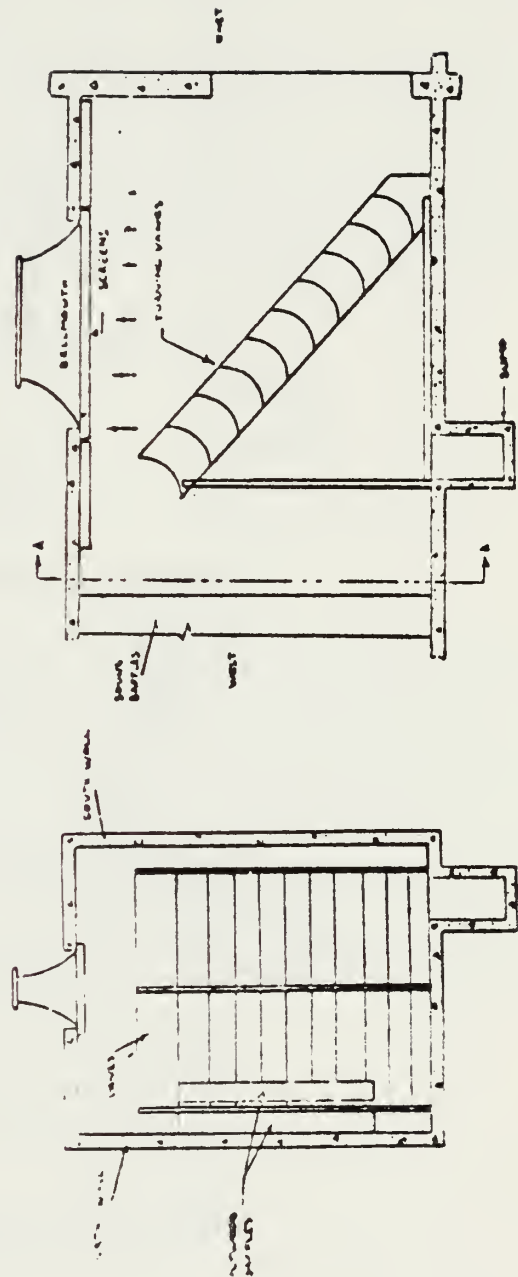
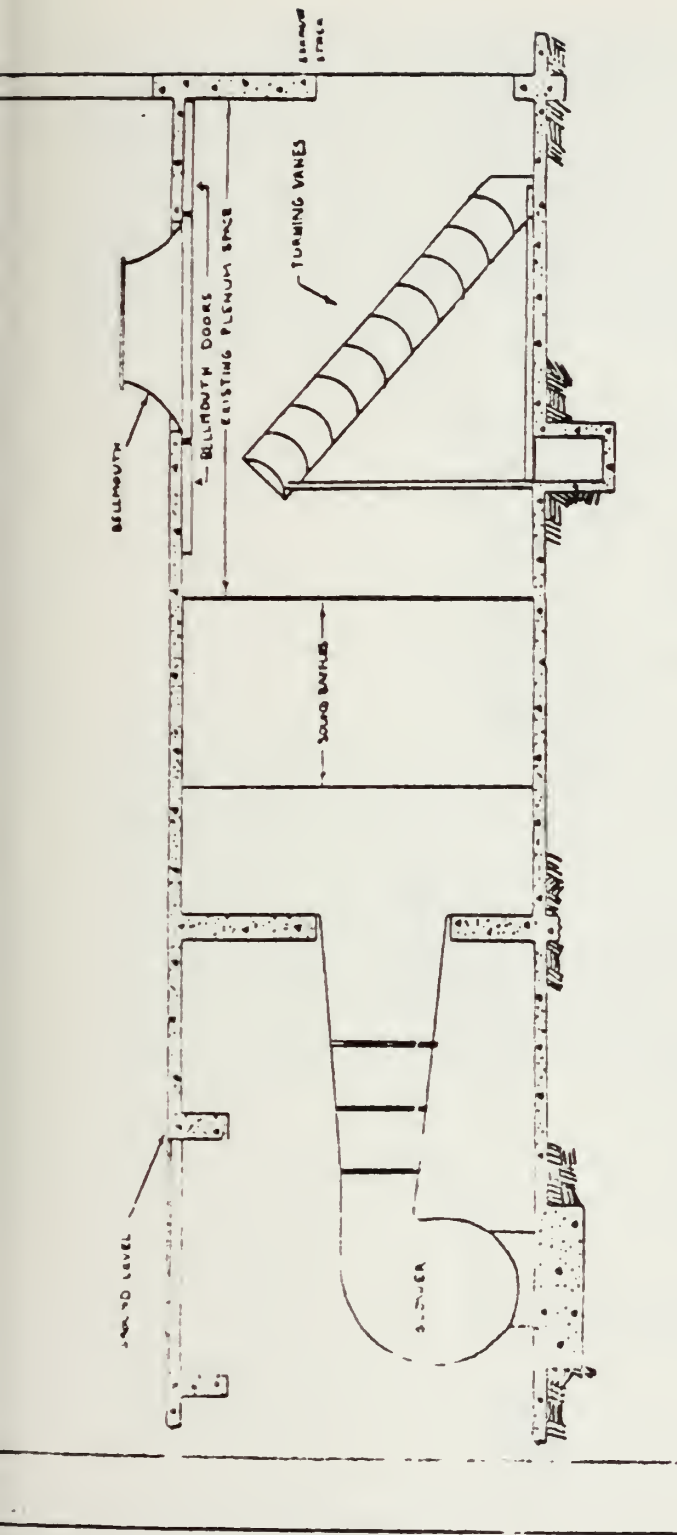


Fig. 2. Plenum Chamber as Modified by Bartocci

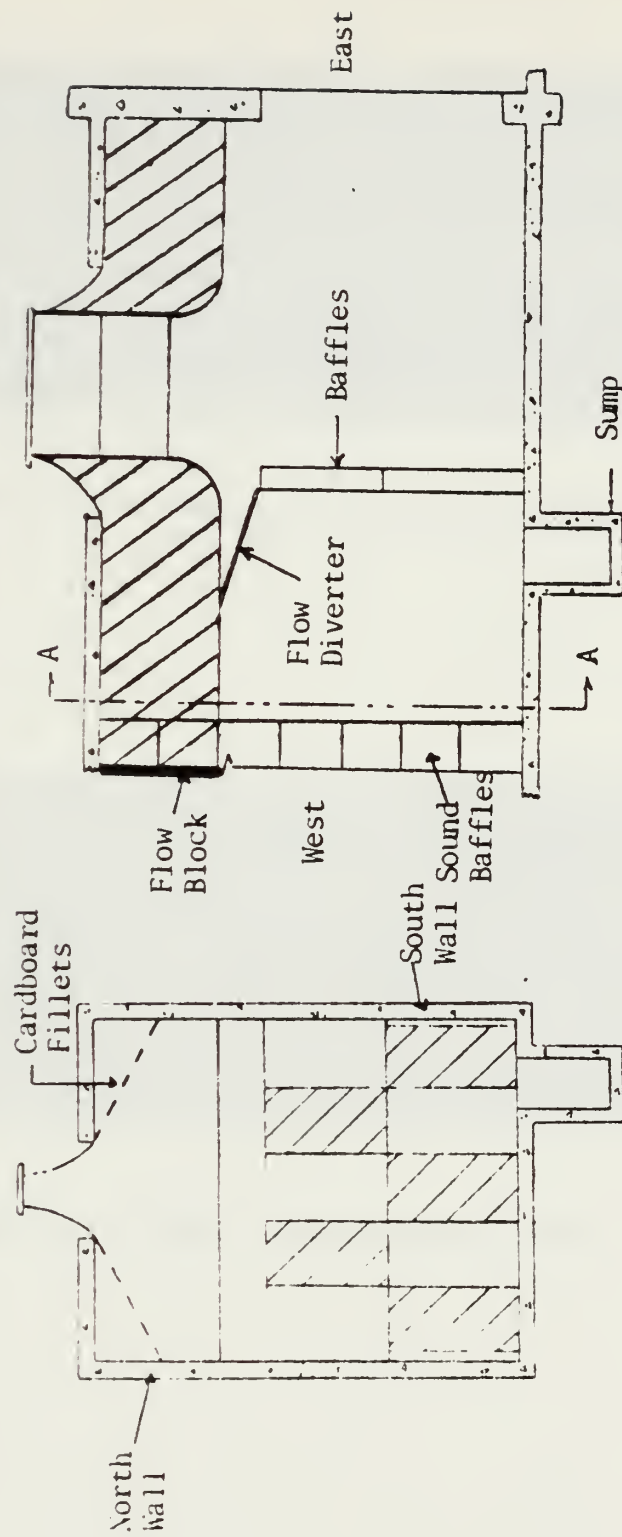


Fig. 3. Plenum Chamber as Modified by Moebius

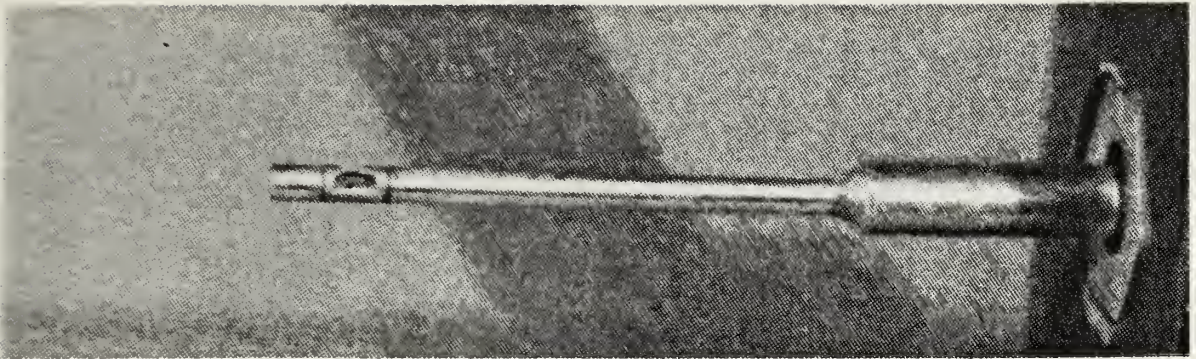


Fig. 4. Lower Plane Survey Probe

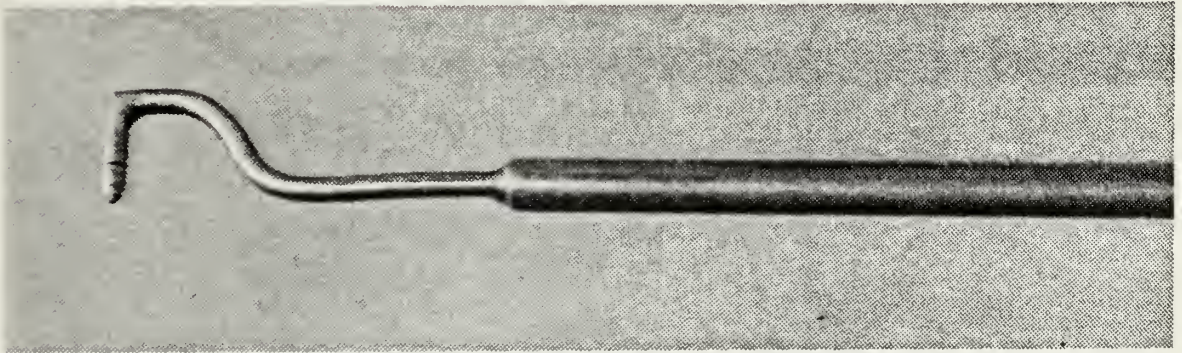


Fig. 5. Upper Plane Survey Probe

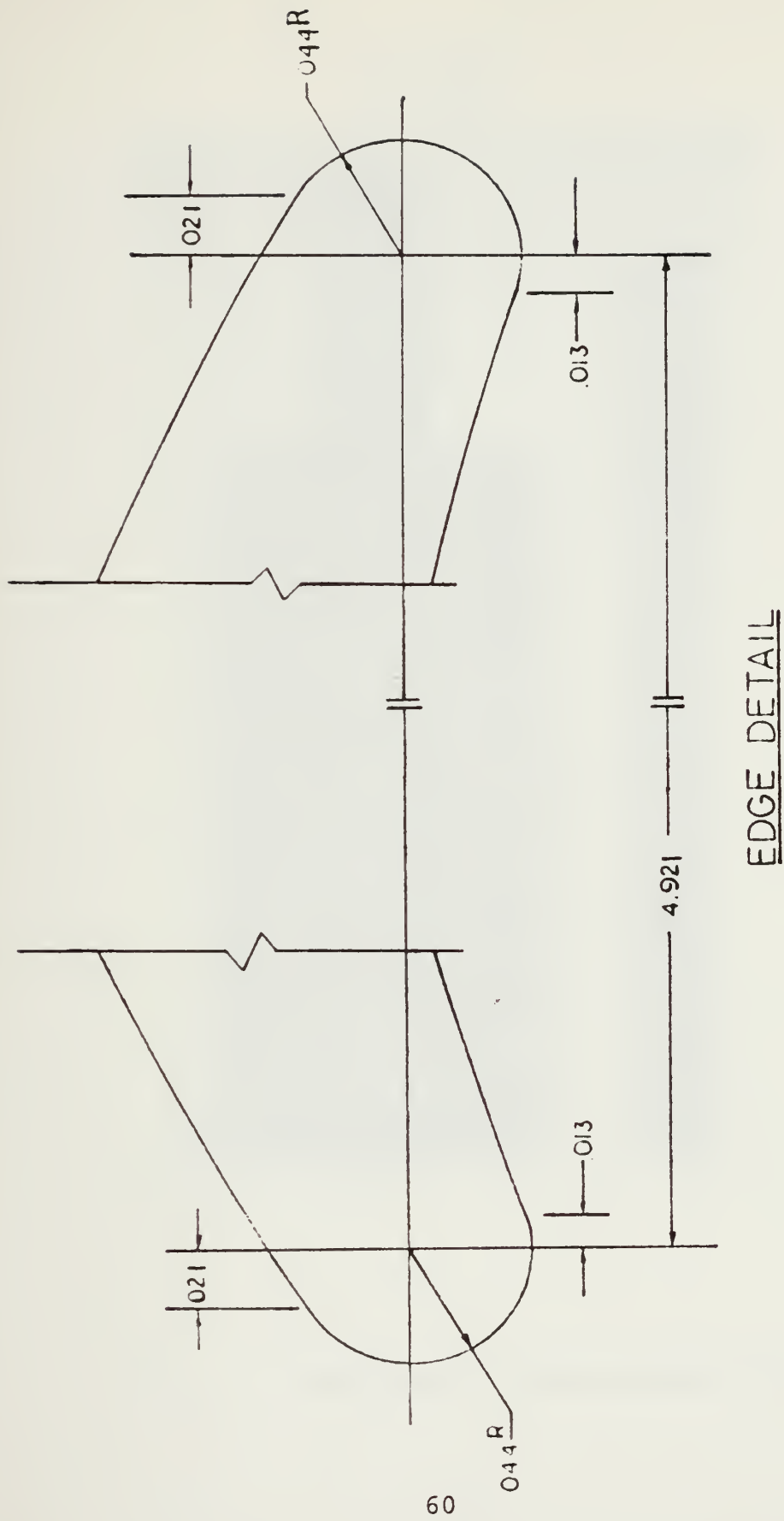


Fig. 6. Blade Edge Detail

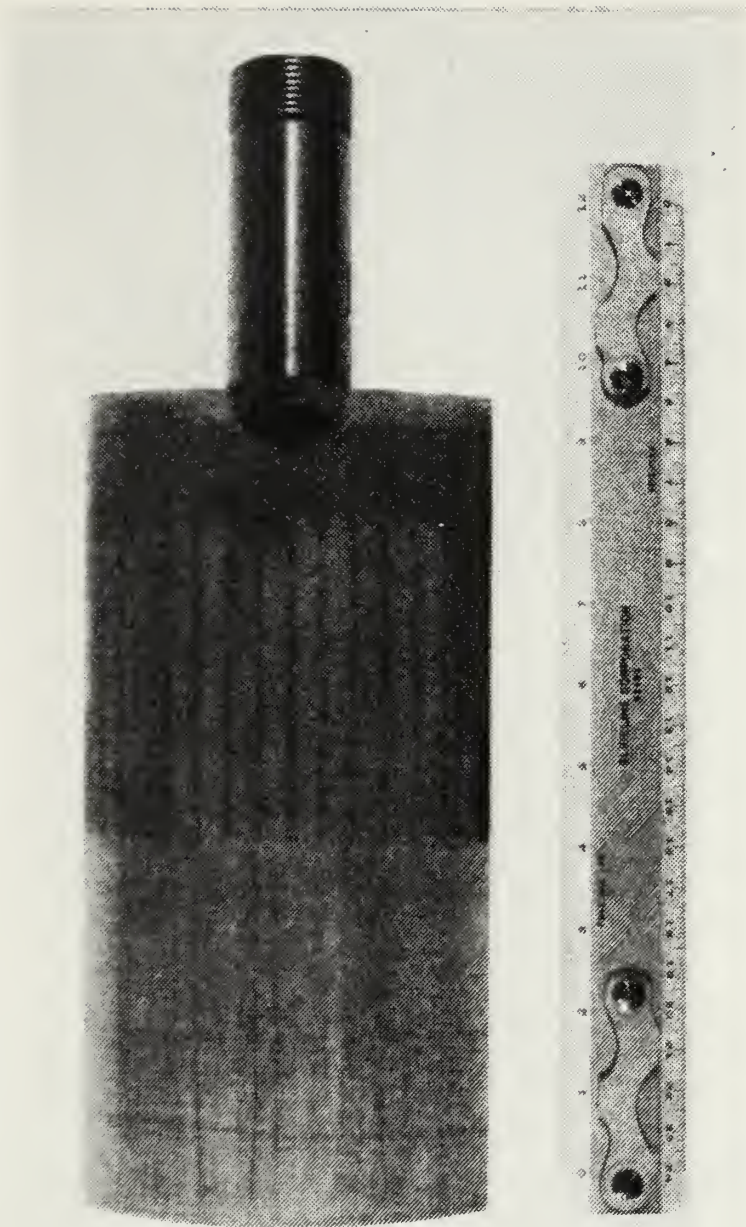


Fig. 7. Photograph of Instrumented Blade

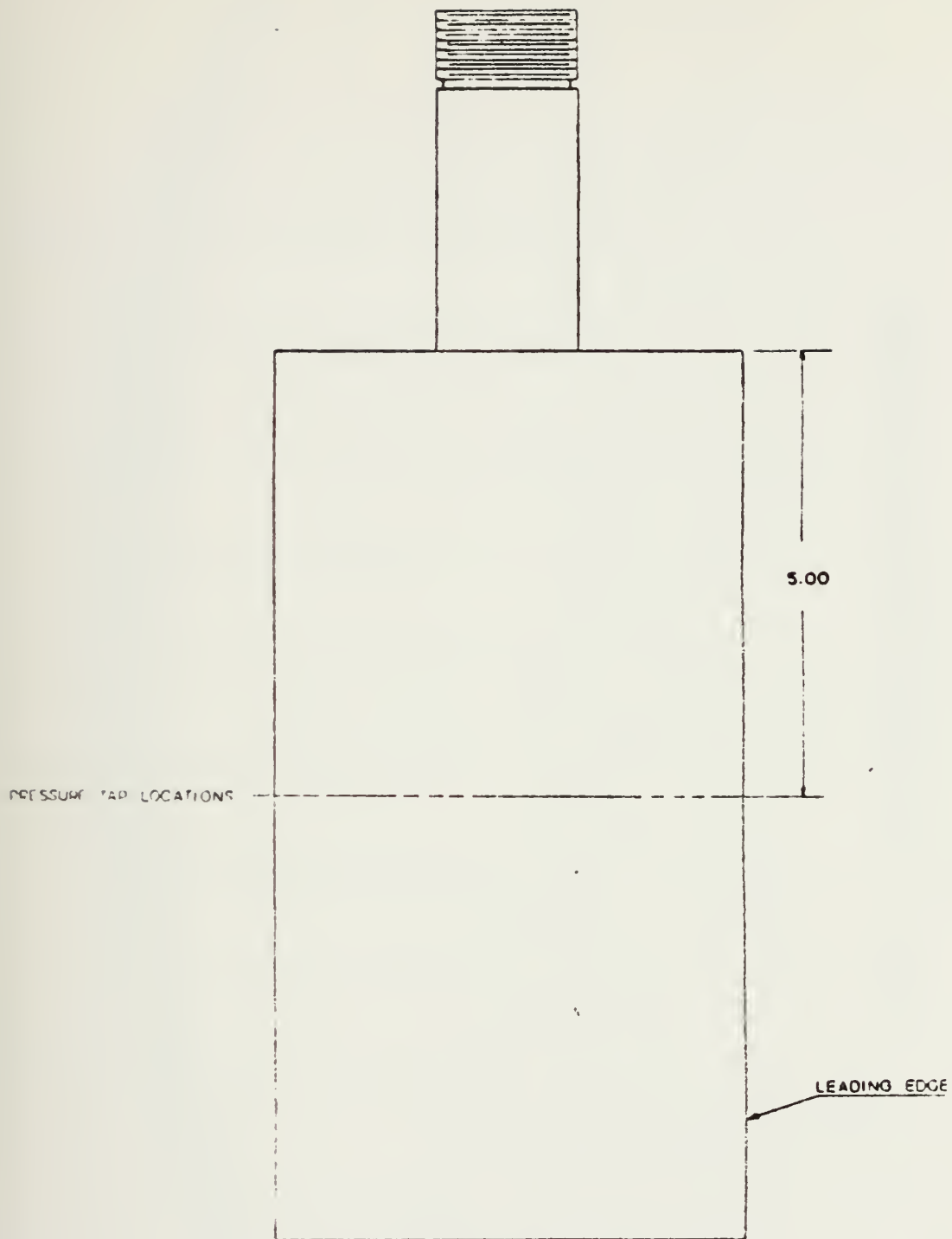


Fig. 8. Instrumented Blade

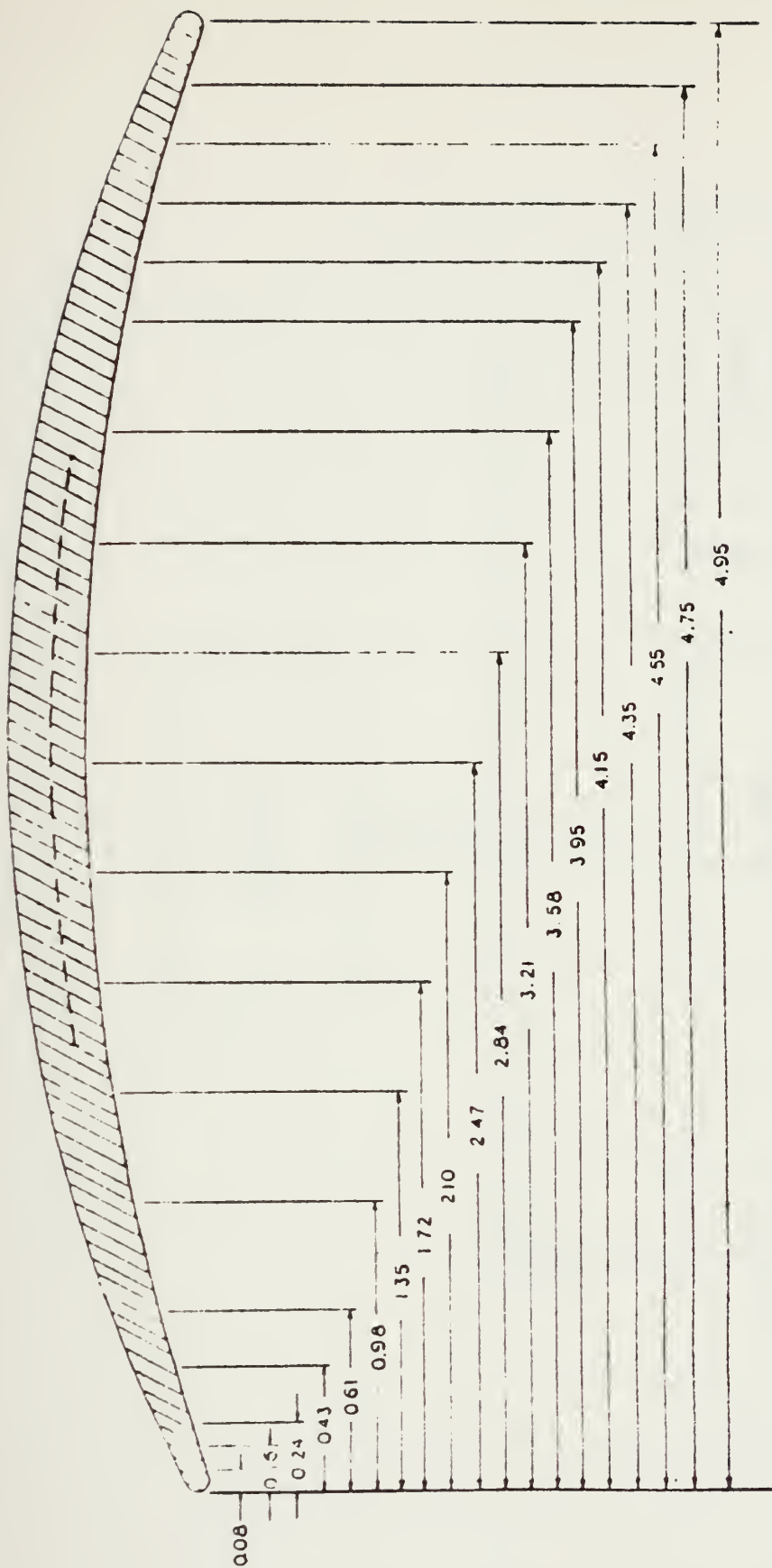


Fig. 9. Instrumented Blade Tap Locations

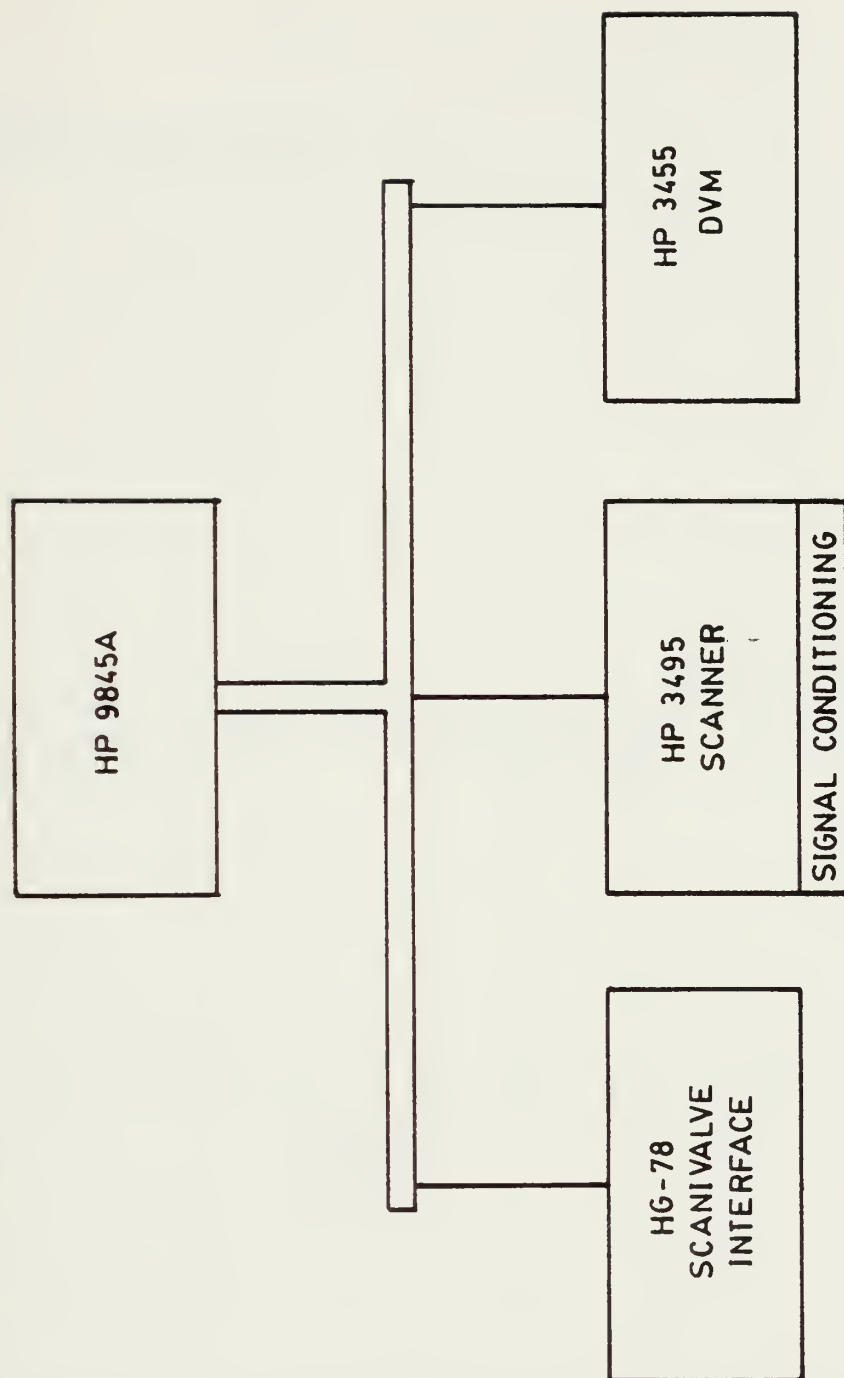


Fig. 10. Data Acquisition System

$P(\text{plenum}) - P_t - Q_{ref}$
 POINTS 1 TO 50 LOWER PLANE 35 DEG

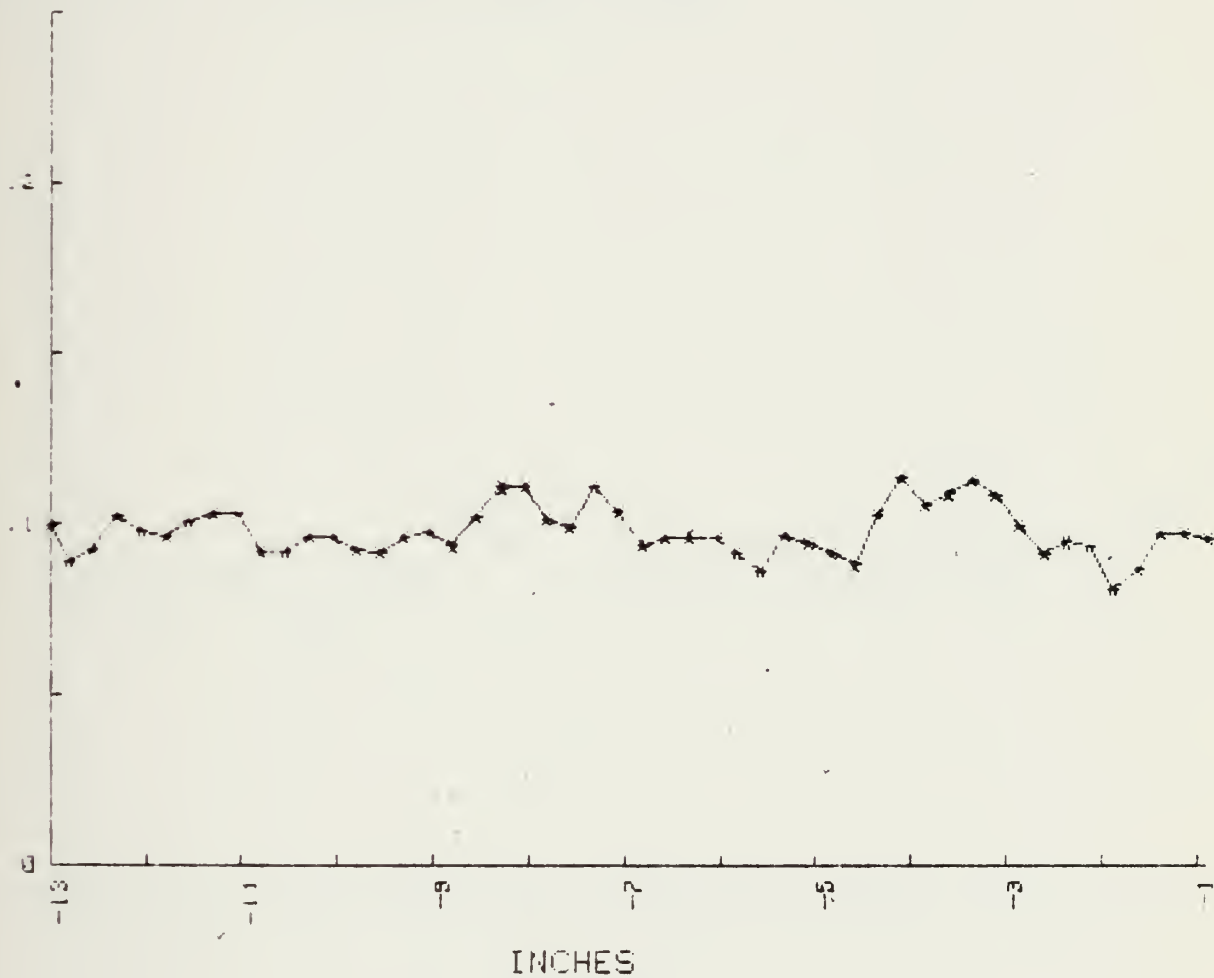


Fig. 11. Probe survey Data at Midspan of Lower Plane
 End Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P_{\text{plenum}} - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 LOWER PLANE 35 DEG

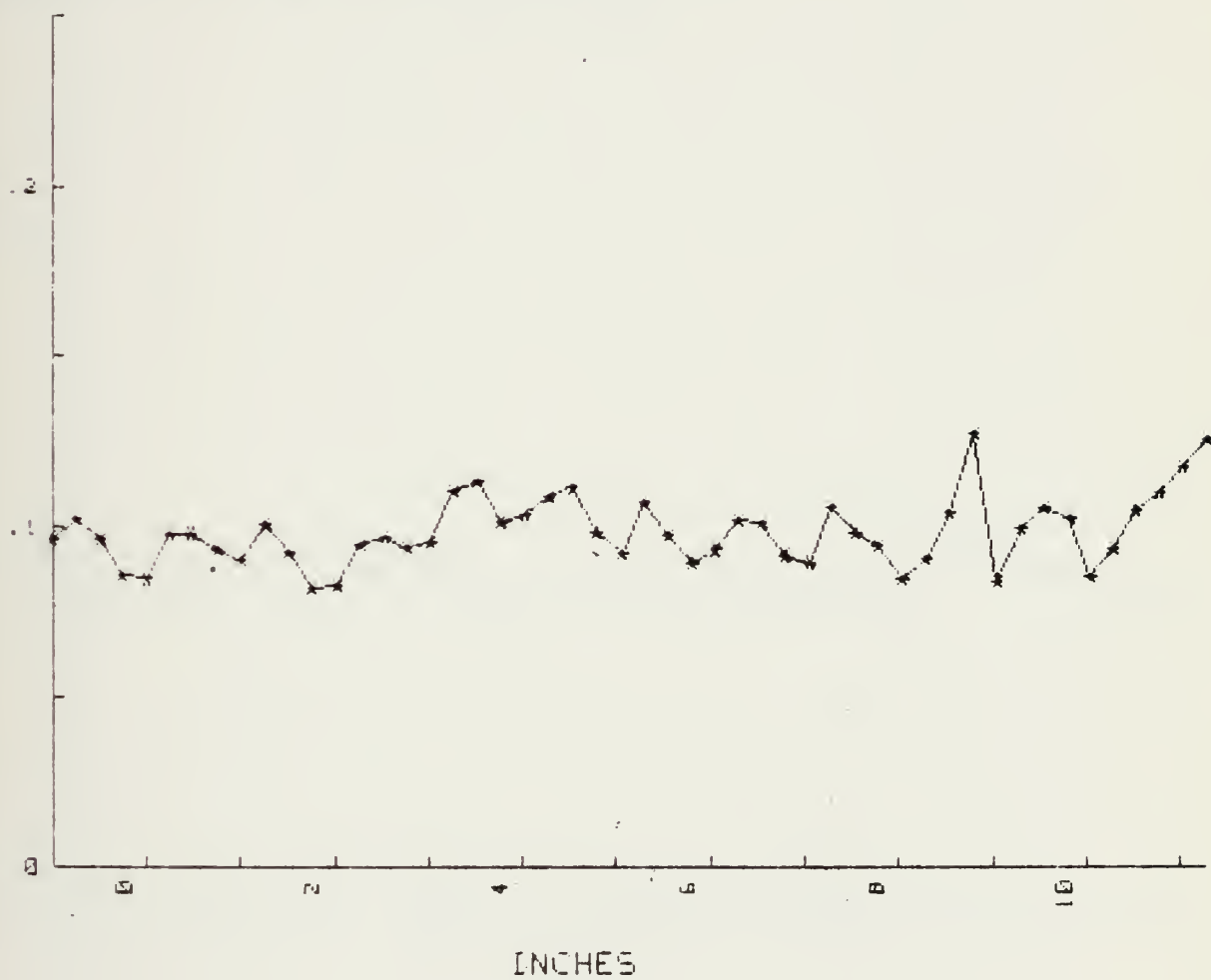


Fig. 12. Probe Survey Data at Midspan of Lower Plane
End Walls at 35°, Points 51 to 100

$$(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 1 TO 50 UPPER PLANE 35 DEG

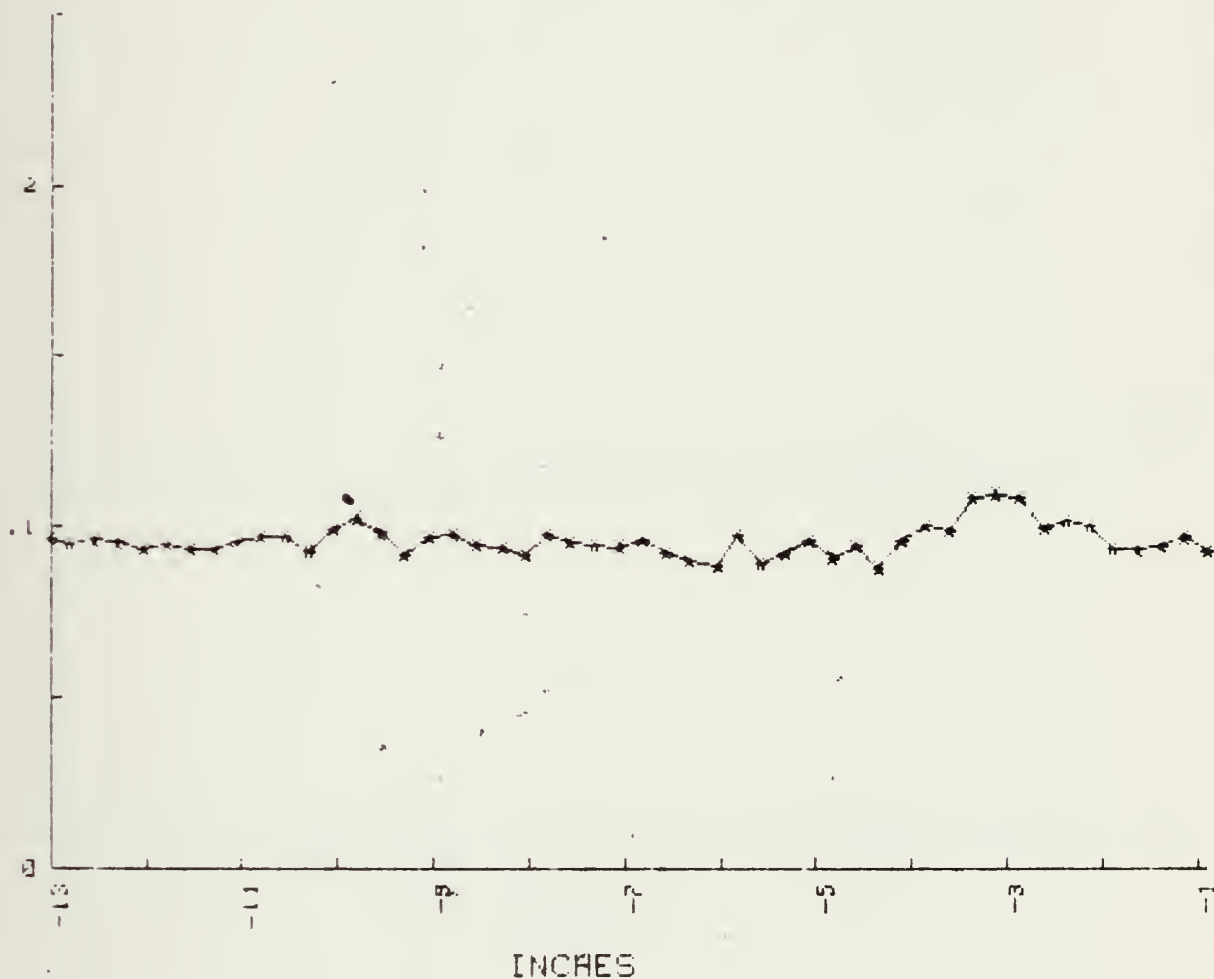


Fig. 13. Probe Survey Data at Midspan of Upper Plane
End Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 UPPER PLANE 35 DEG

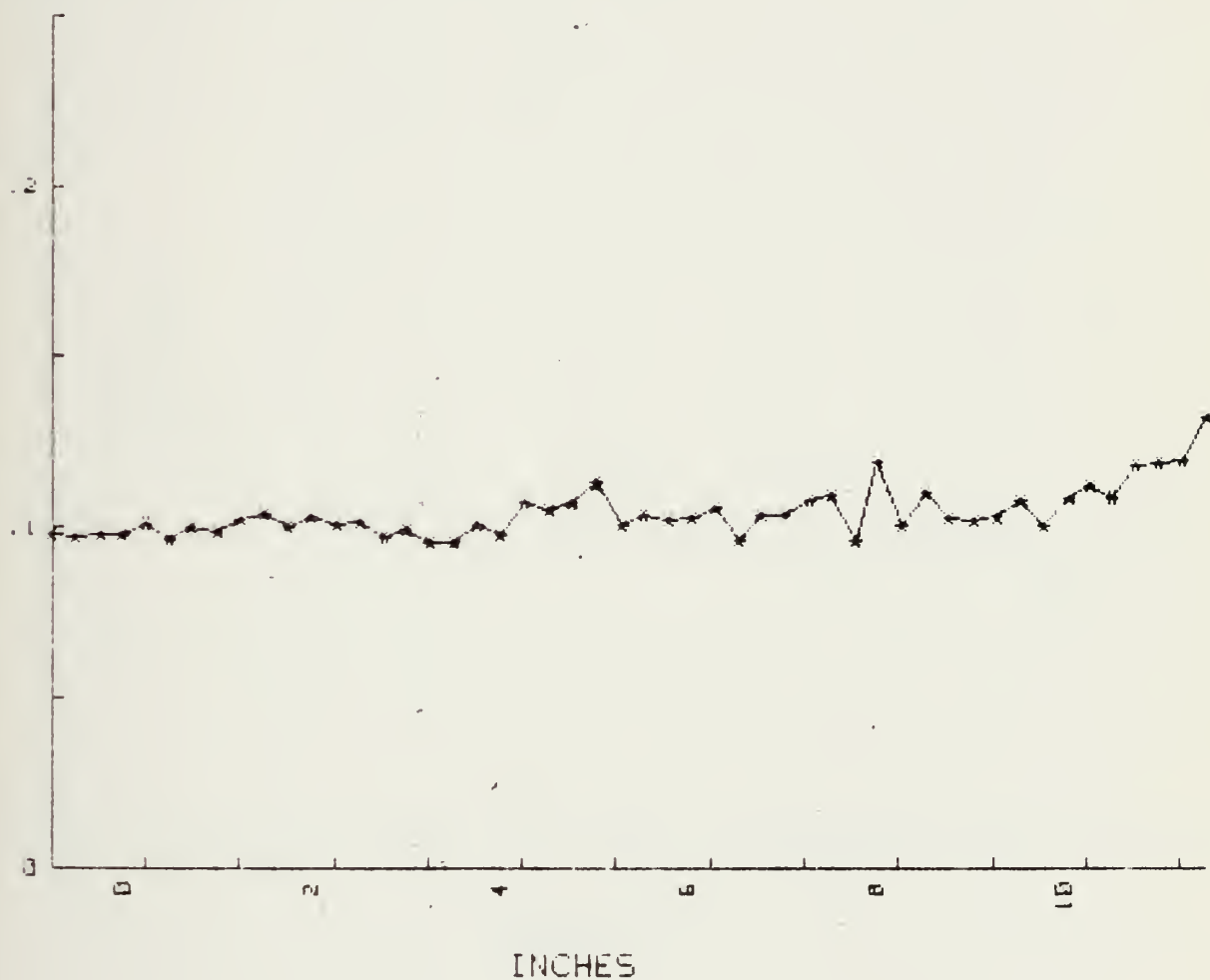


Fig. 14. Probe Survey Data at Midspan of Upper Plane
End Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P_{\text{plenum}} - P_t / Q_{\text{ref}}$

POINTS 1 TO 50 LOWER PLANE 30 DEG

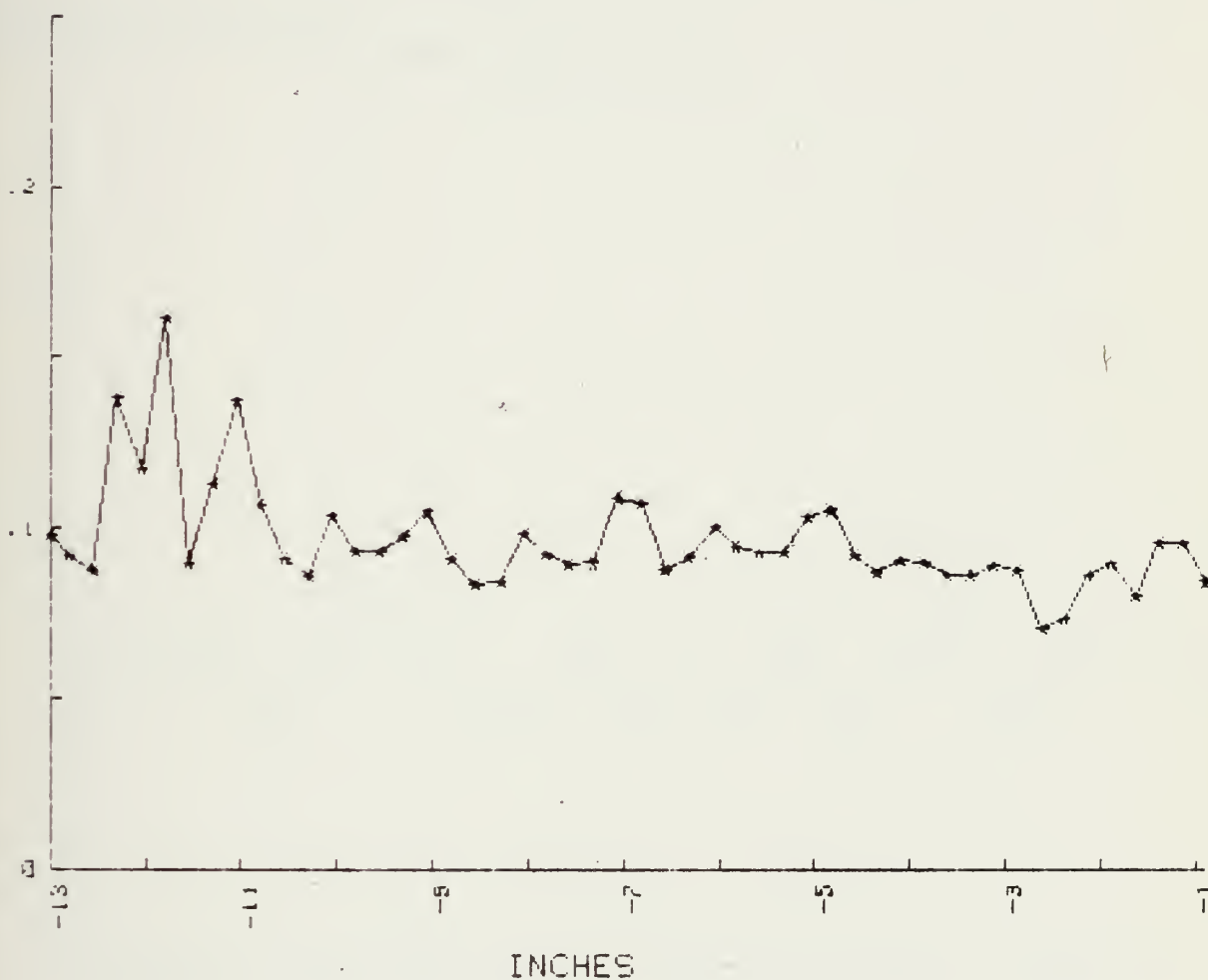


Fig. 15. Probe Survey Data at Midspan of Lower Plane
End Walls at 30°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 LOWER PLANE 30 DEG

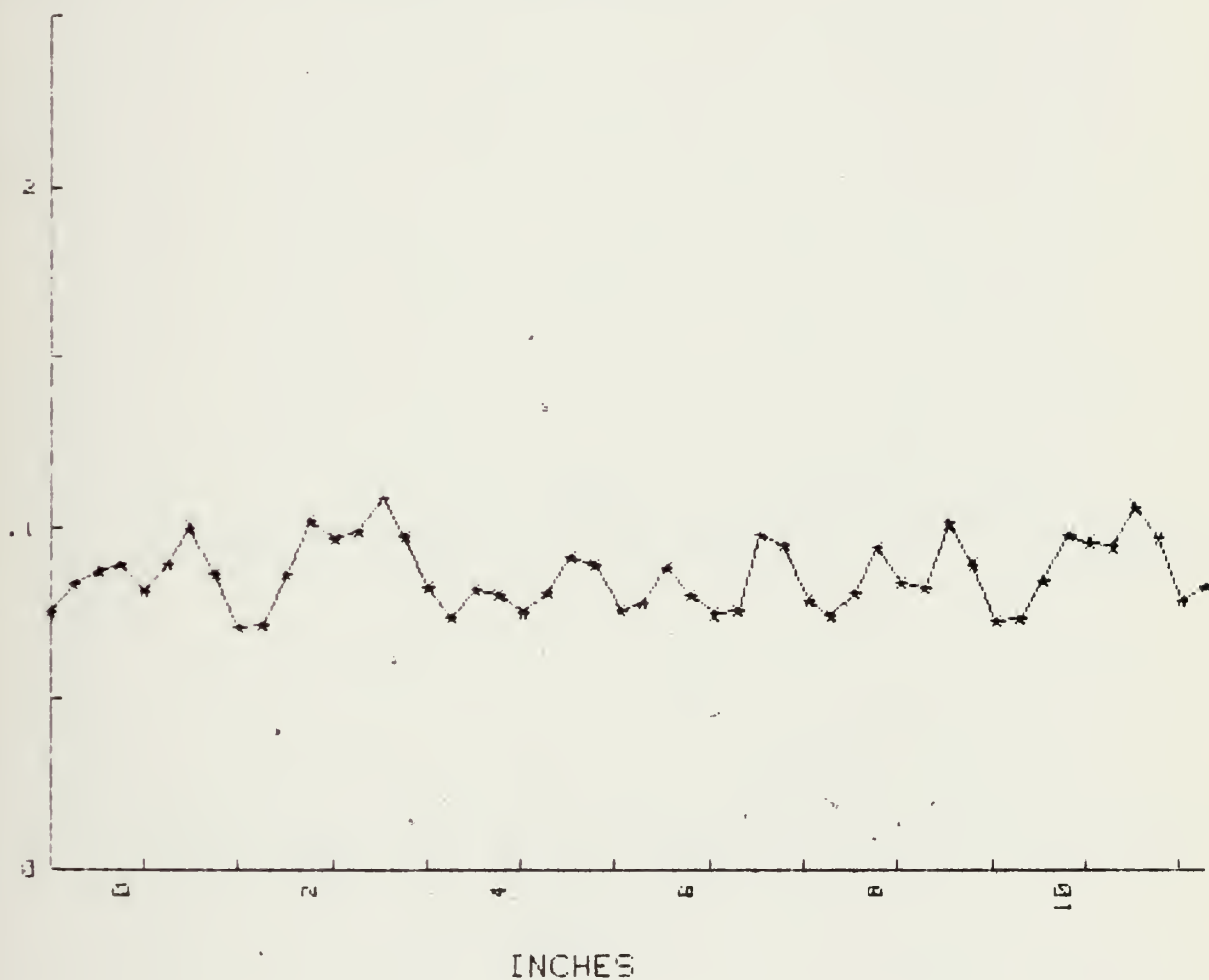


Fig. 16. Probe Survey Data at Midspan of Lower Plane
End Walls at 30°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$(P_{\text{plenum}} - P_t) / Q_{\text{ref}}$

POINTS 1 TO 50 UPPER PLANE 30 DEG

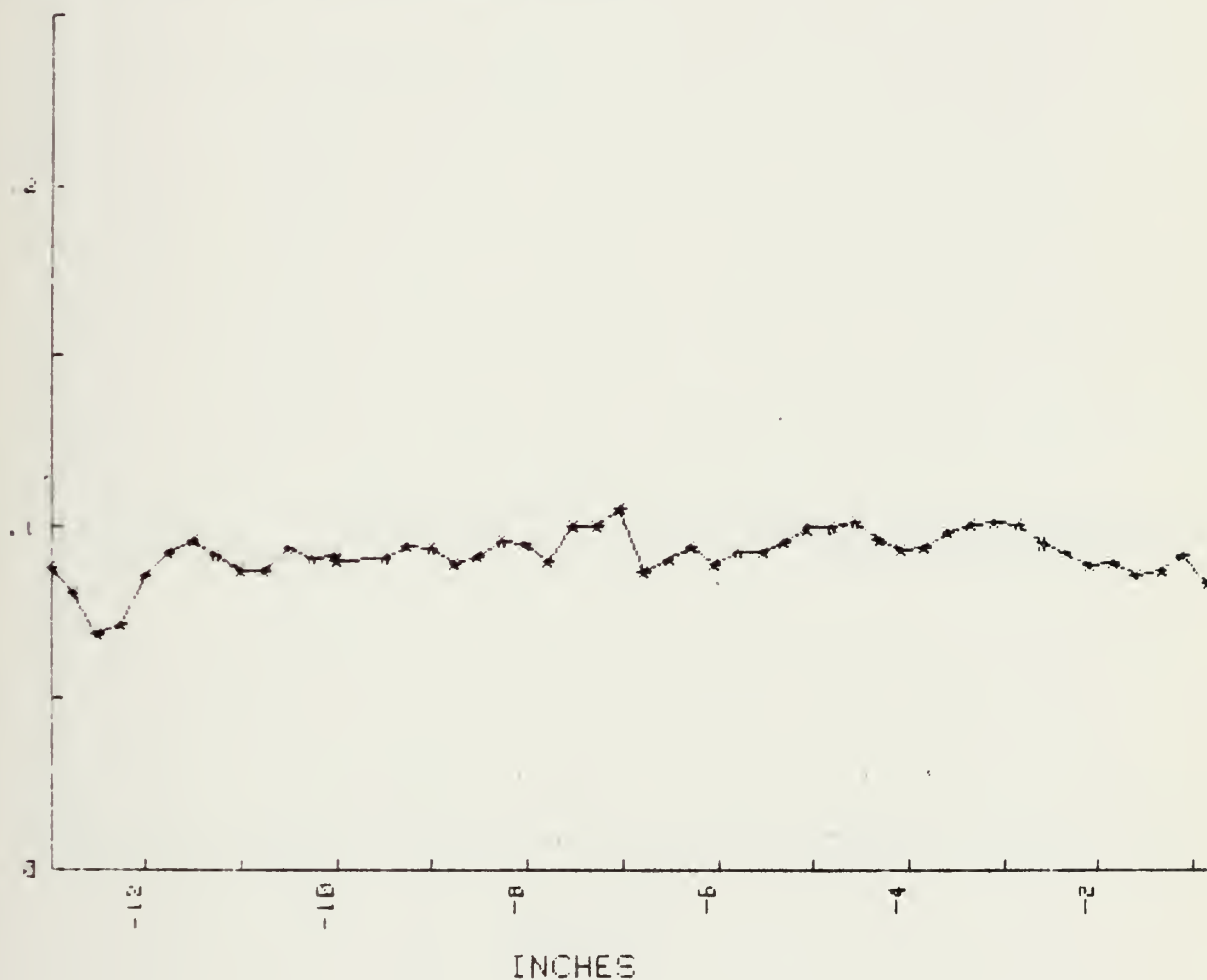


Fig. 17. Probe Survey Data at Midspan of Upper Plane
End Walls at 30°, Points 1 to 50

$$(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$$

$P_{\text{plenum}} - P_t - Q_{\text{ref}}$

POINTS 51 TO 100 UPPER PLANE 30 DEG

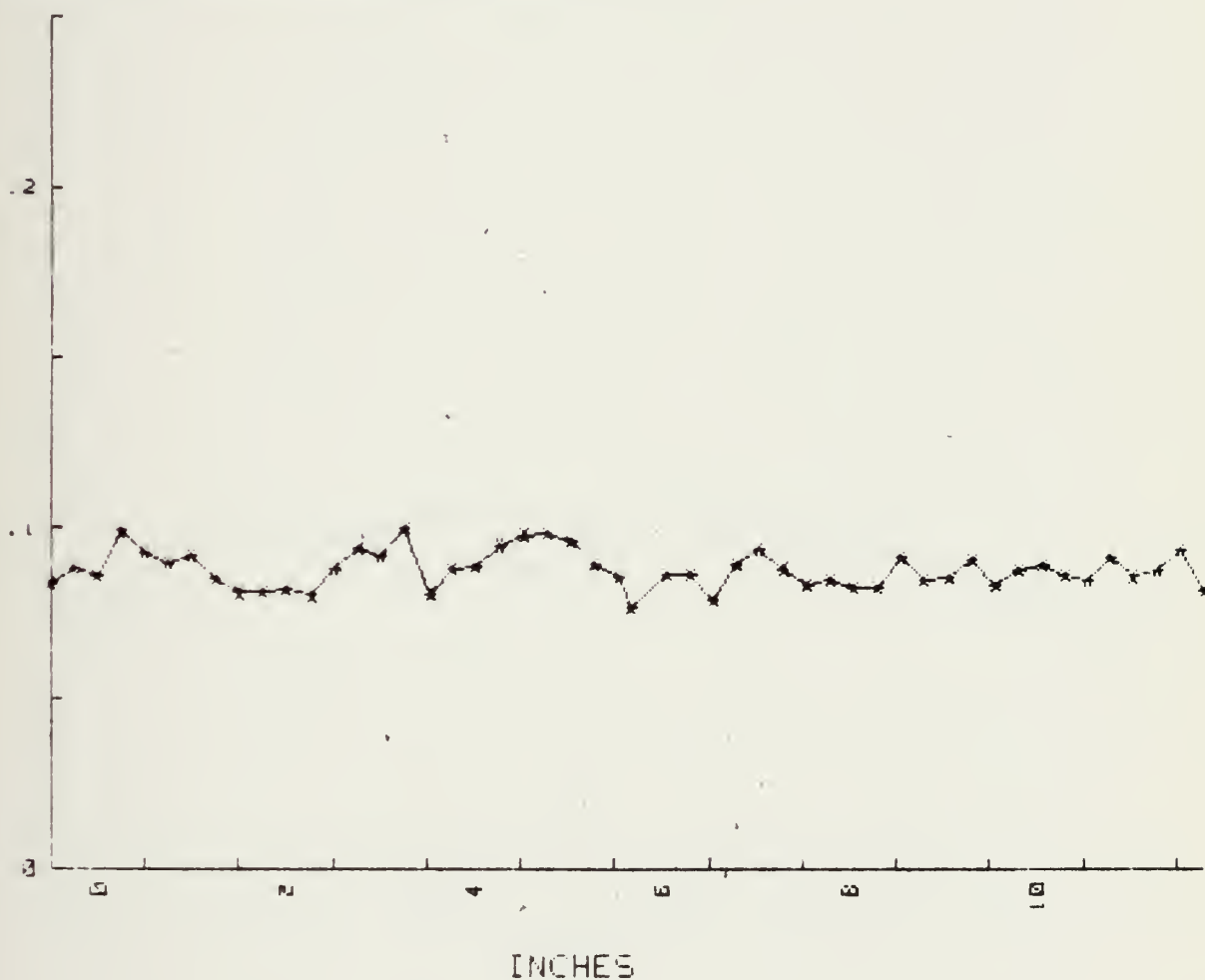


Fig. 18. Probe Survey Data at Midspan of Upper Plane
End Walls at 30°, Points 51 to 100

$$(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$$

$(P_{\text{Plenum}} - P_t) / Q_{\text{ref}}$

POINTS 1 TO 50 LOWER PLANE 50 DEG

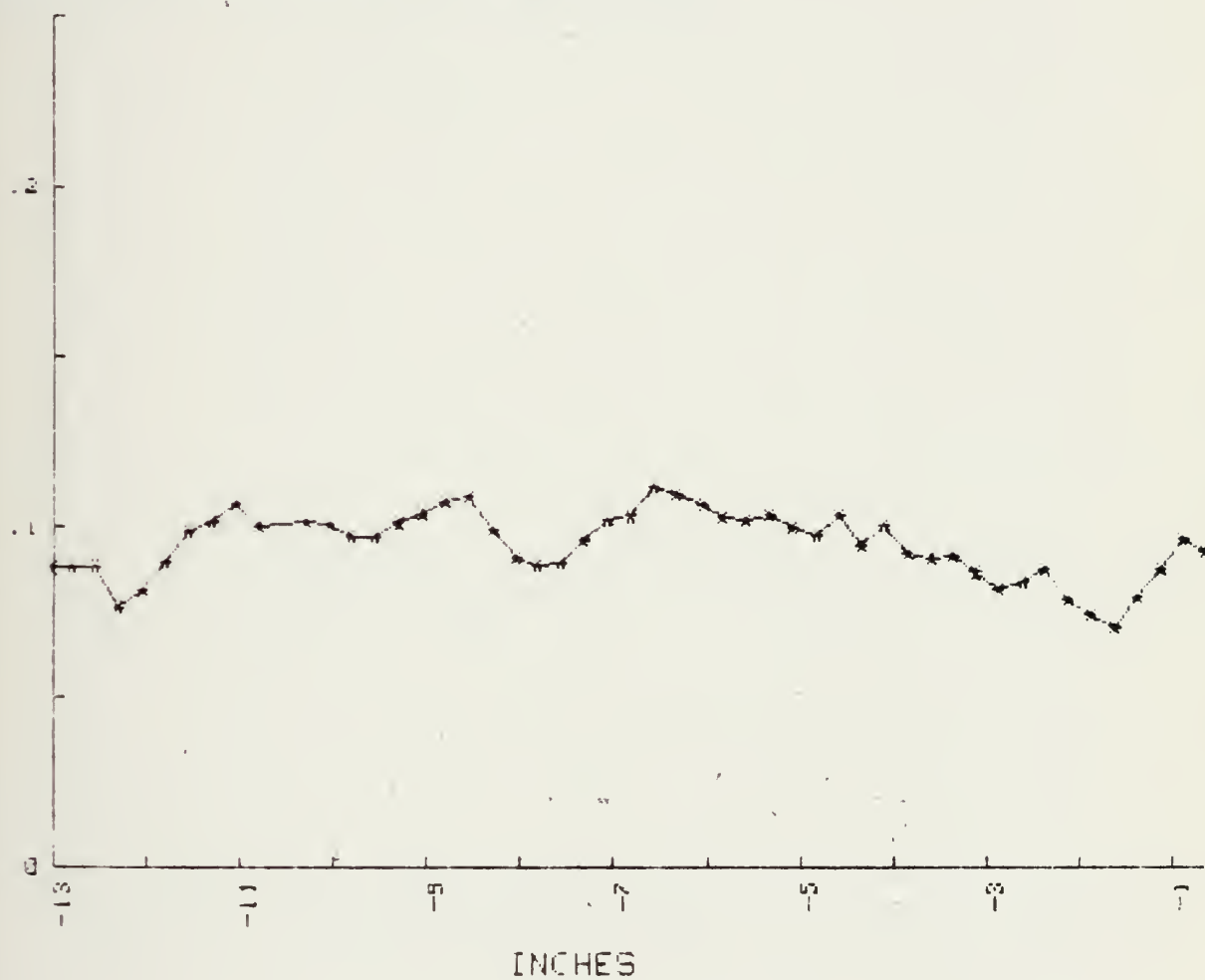


Fig. 19. Probe Survey Data at Midspan of Lower Plane
End Walls at 50°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 LOWER PLANE 50 DEG

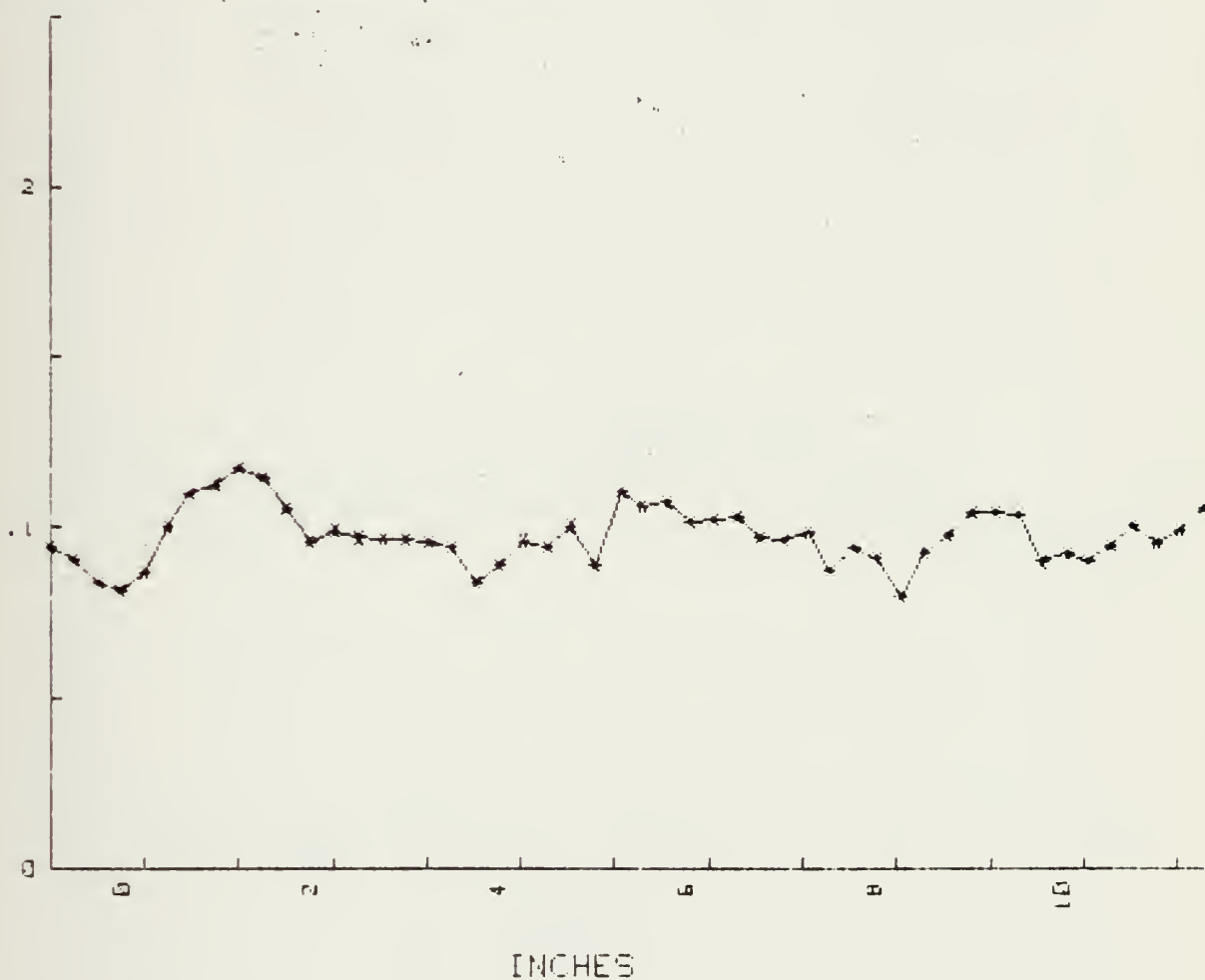


Fig. 20. Probe Survey Data at Midspan of Lower Plane
End Walls at 50°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{Plenum}) - P_t / Q_{\text{ref}}$

50 POINTS UPPER PLANE 50 DEG

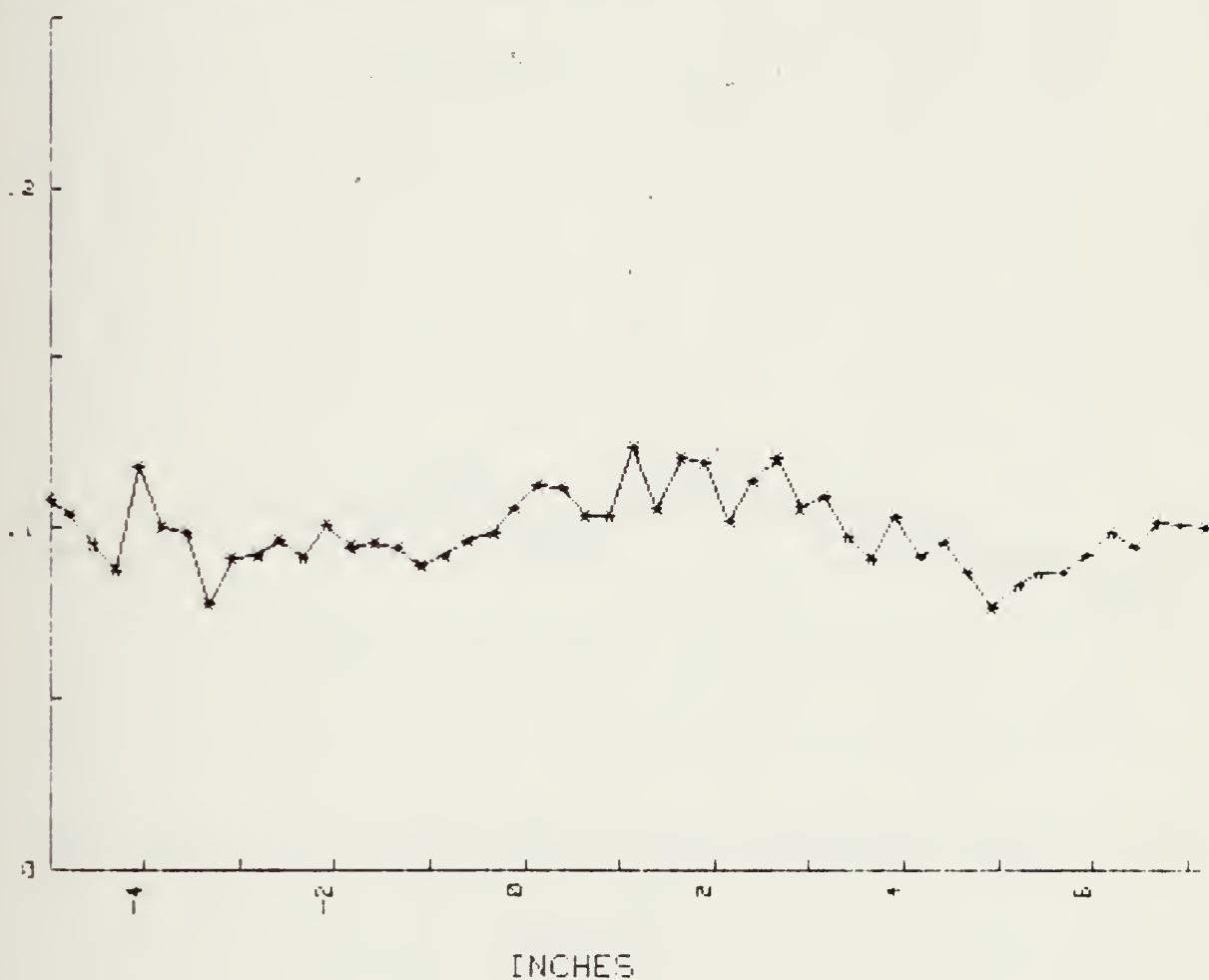


Fig. 21. Probe Survey Data at Midspan of Upper Plane
End Walls at 50°
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{Plenum}) - P_t / Q_{\text{ref}}$
 POINTS 1 TO 50 LOWER PLANE 50 DEG
 * FIRST RUN + SECOND RUN

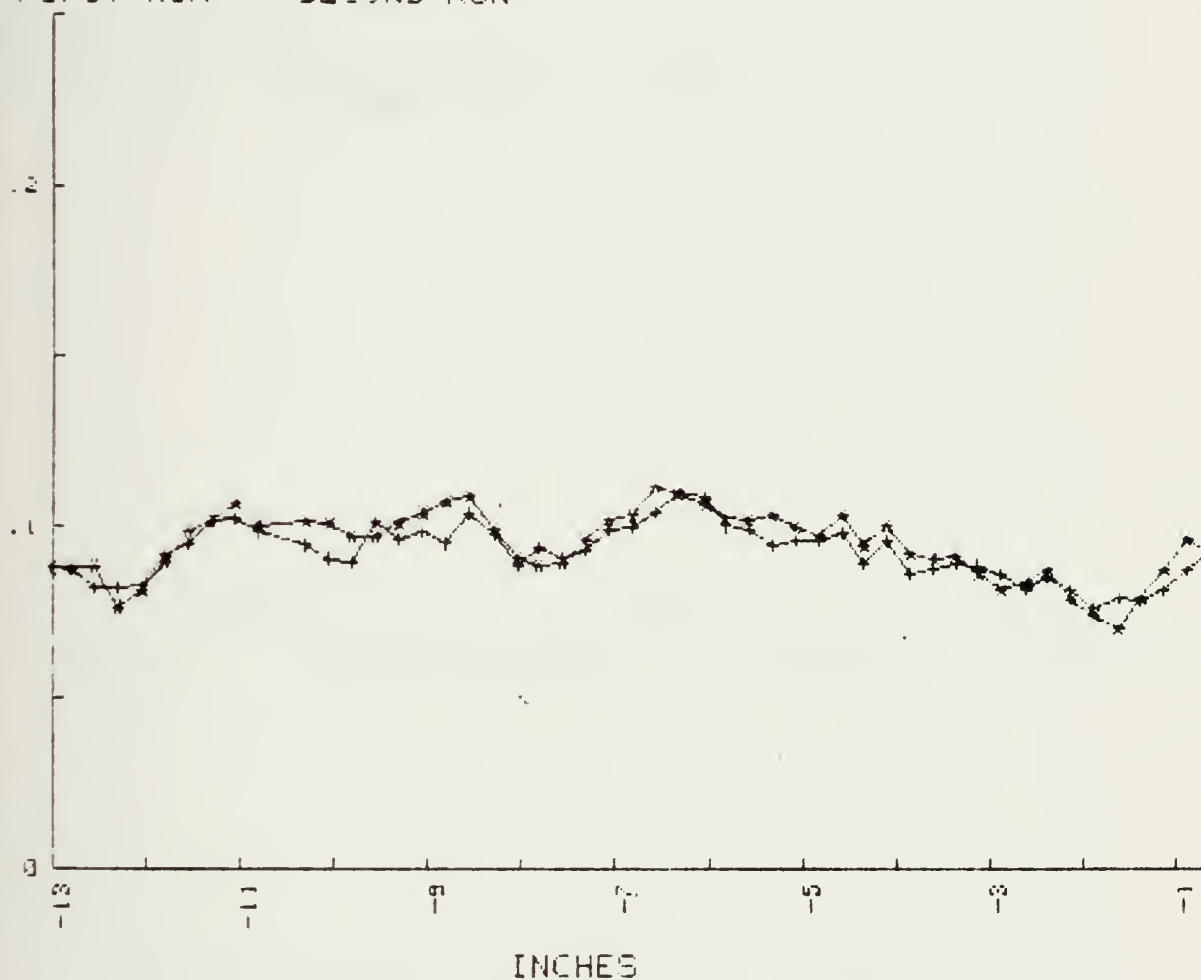


Fig. 22. Probe Survey Data at Midspan at Lower Plane
 End Walls at 50°, Two Runs, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{Plenum}) - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 LOWER PLANE 50 DEG

* FIRST RUN + SECOND RUN

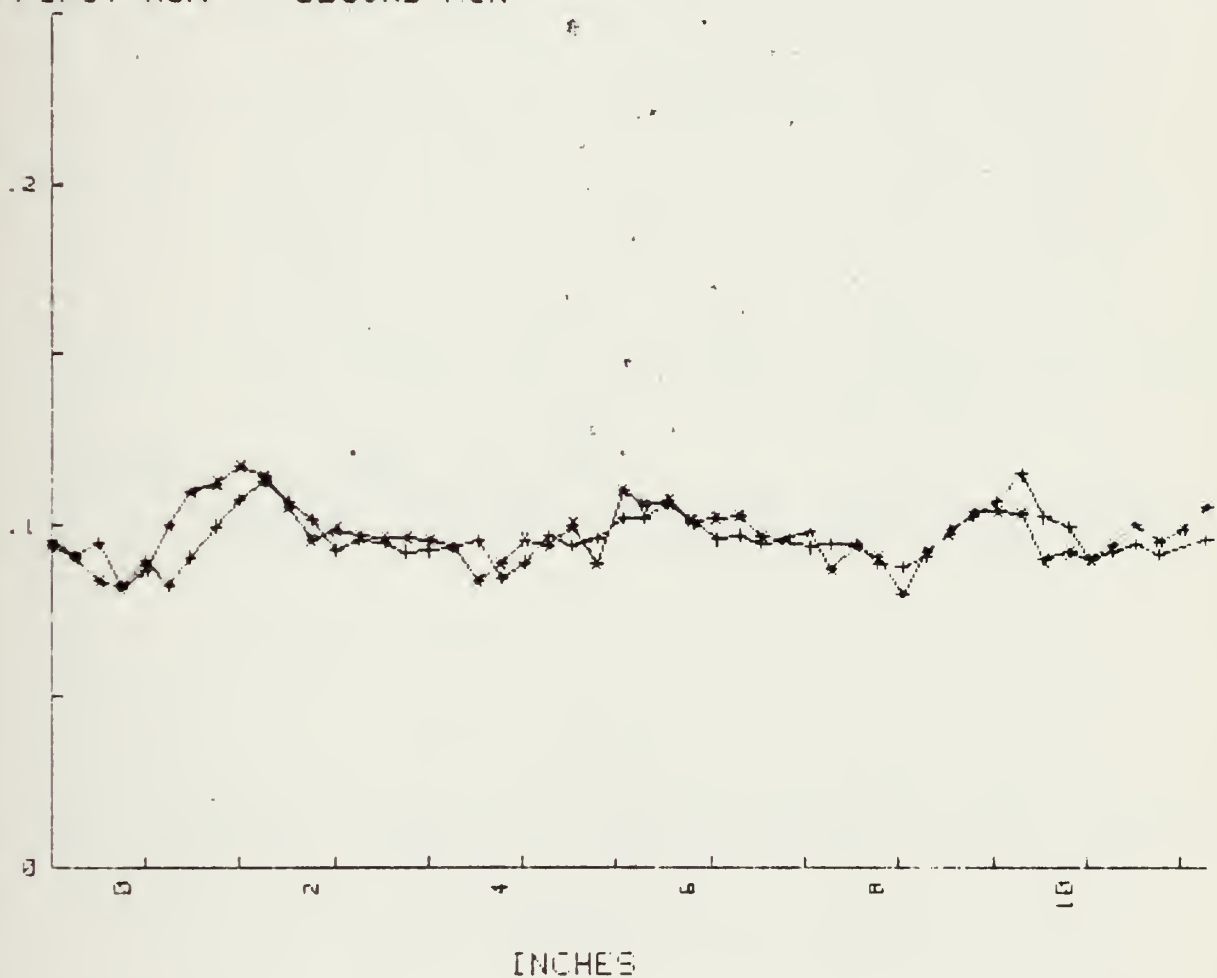


Fig. 23. Probe Survey Data at Midspan at Lower Plane
End Walls at 50°, Two Runs, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$(P_{\text{plenum}} - P_t)/Q_{\text{ref}}$

* FIRST RUN

+ SECOND RUN

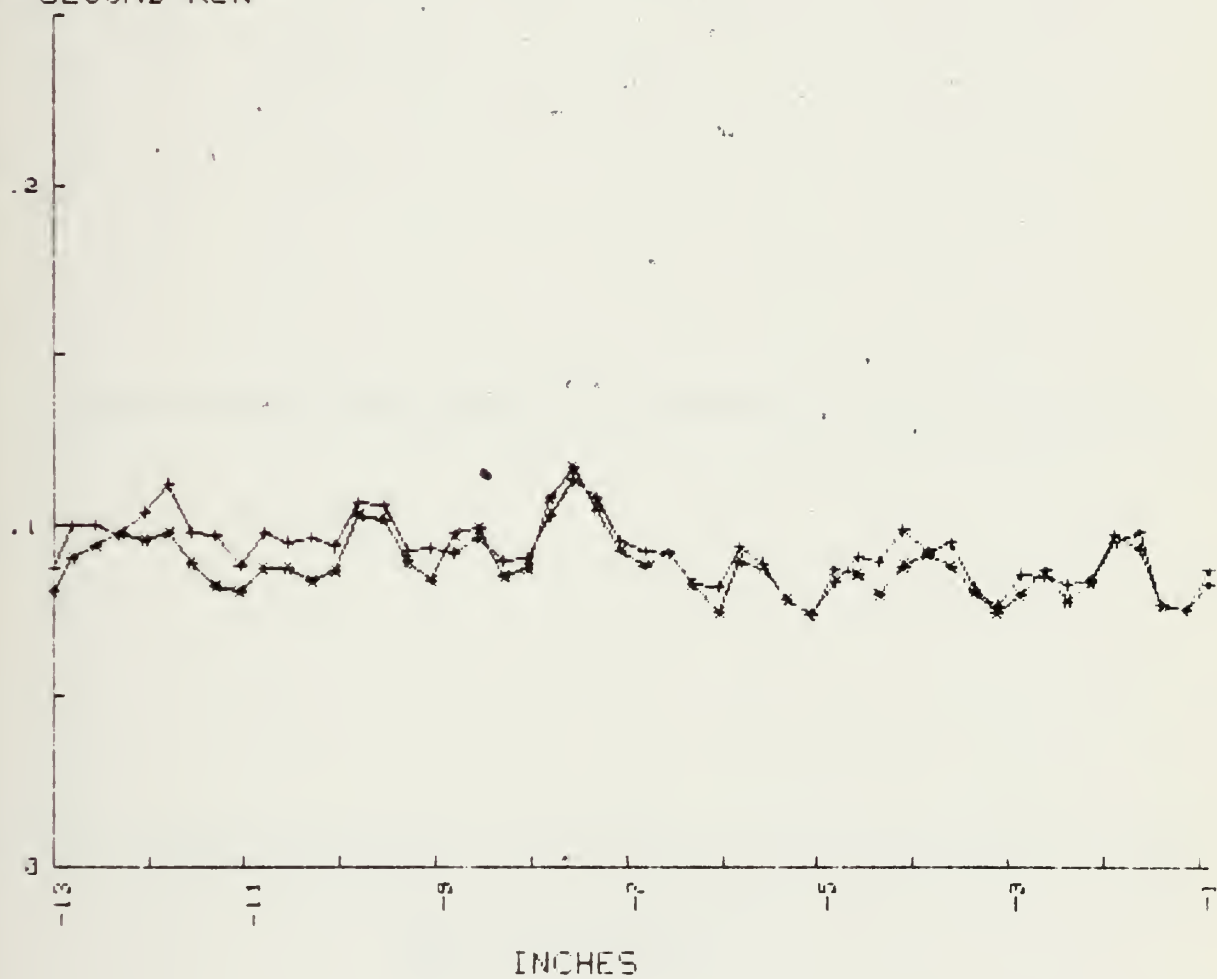


Fig. 24. Probe Survey Data at Midspan at Lower Plane
End Walls at 30°, Two Runs, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t)/Q_{\text{ref}}$

$P(\text{plenum}) - P(\text{amb}) / Q_{\text{ref}}$
 10 INCHES LEFT OF CTR 30 DEG LOWER.

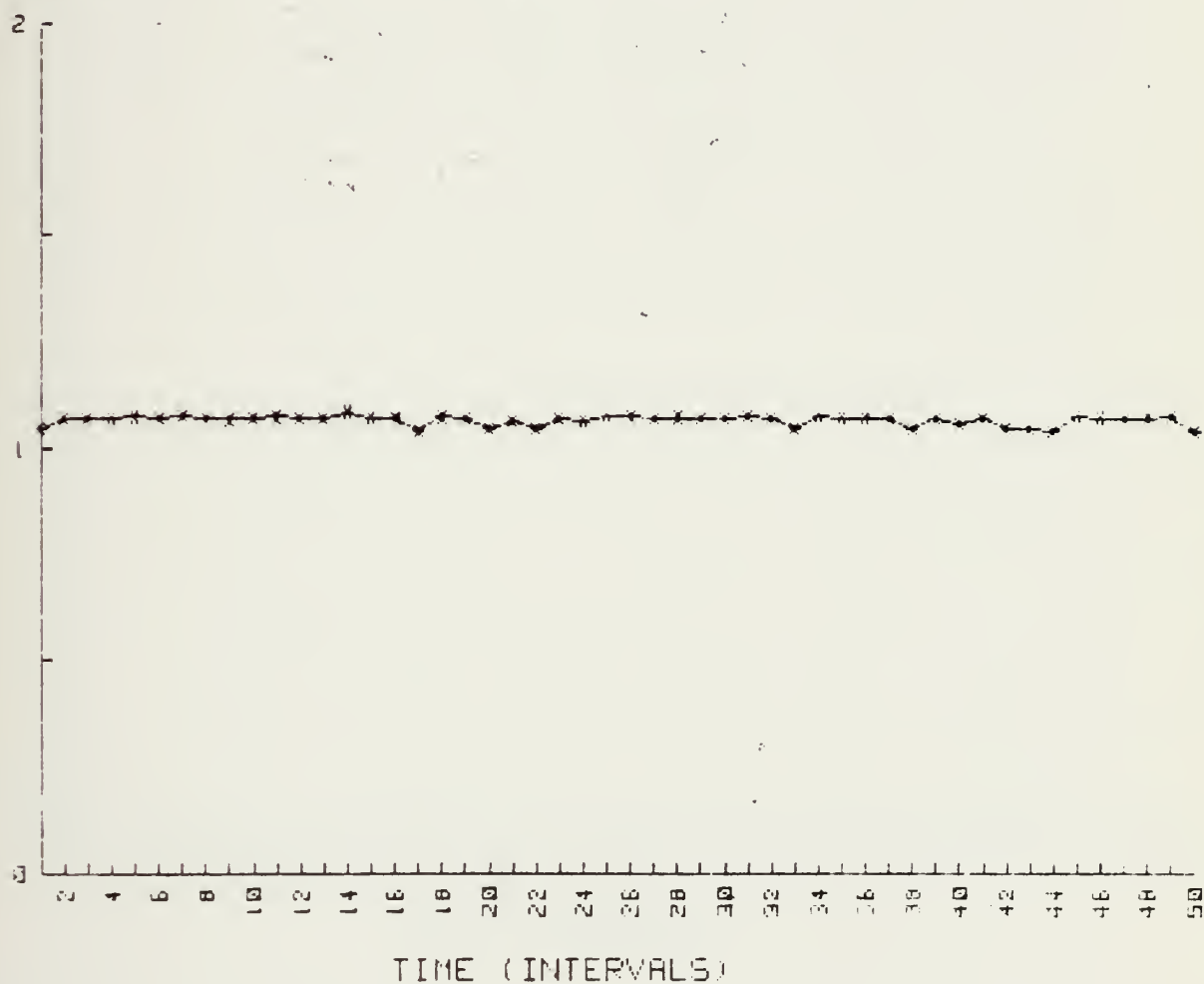


Fig. 25. Repetitive Samples with Fixed Probe Position
 (10" Left of CTR Midspan, End Walls 30°,
 Lower Plane ($P_{\text{PLENUM}} - P_{\text{AMB}} / Q_{\text{ref}}$)

$P_t - P_{amb}) / Q_{ref}$

10 INCHES LEFT OF CTR 30 DEG LOWER

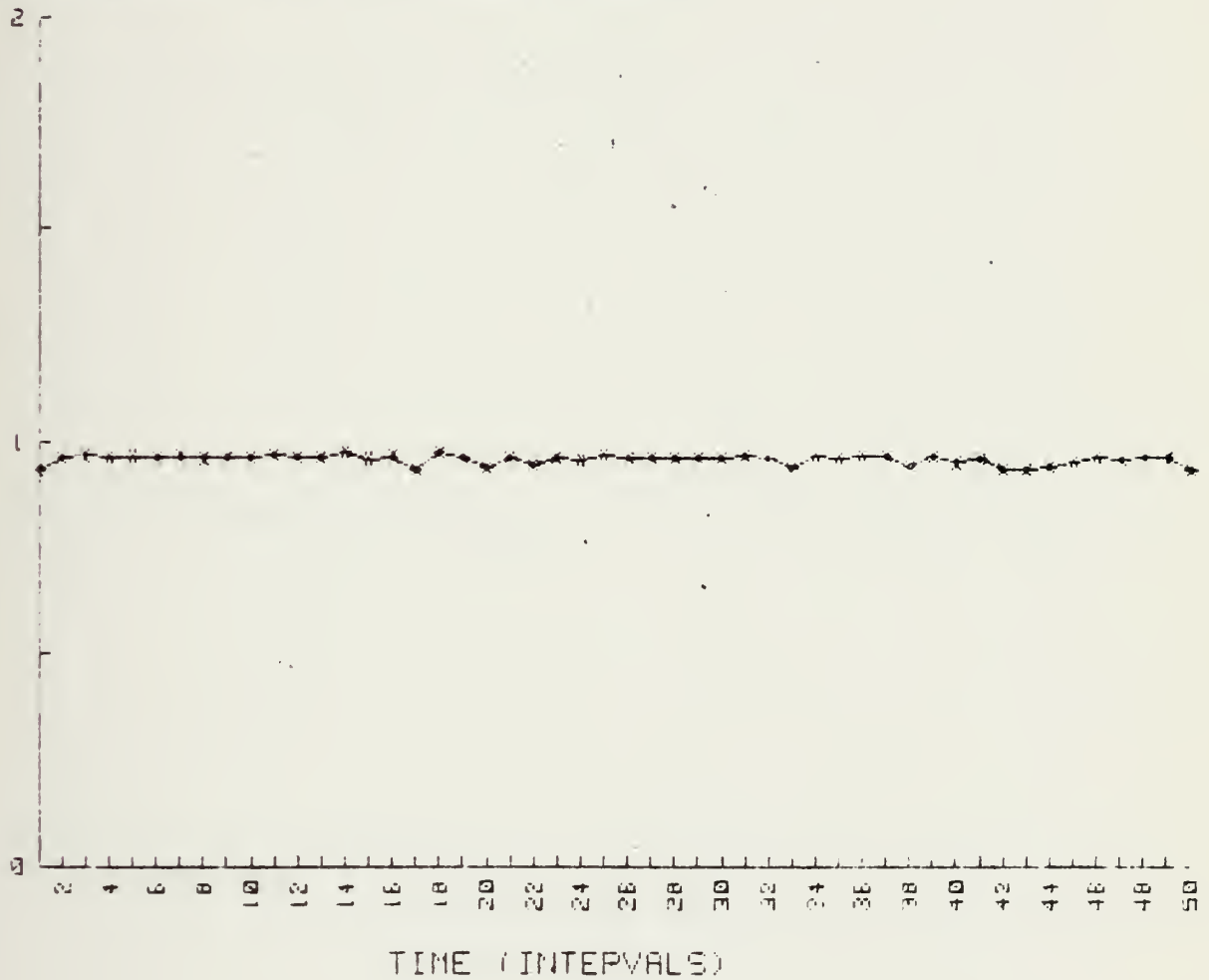


Fig. 26. Repetitive Samples with Fixed Probe Position
(10" Left of CTR Midspan, End Walls at 30°,
Lower Plane $(P_t - P_{AMB}) / Q_{ref}$)

P_{plenum} - P_t / Q_{ref}

10 INCHES LEFT OF CTR 30 DEG LOWER

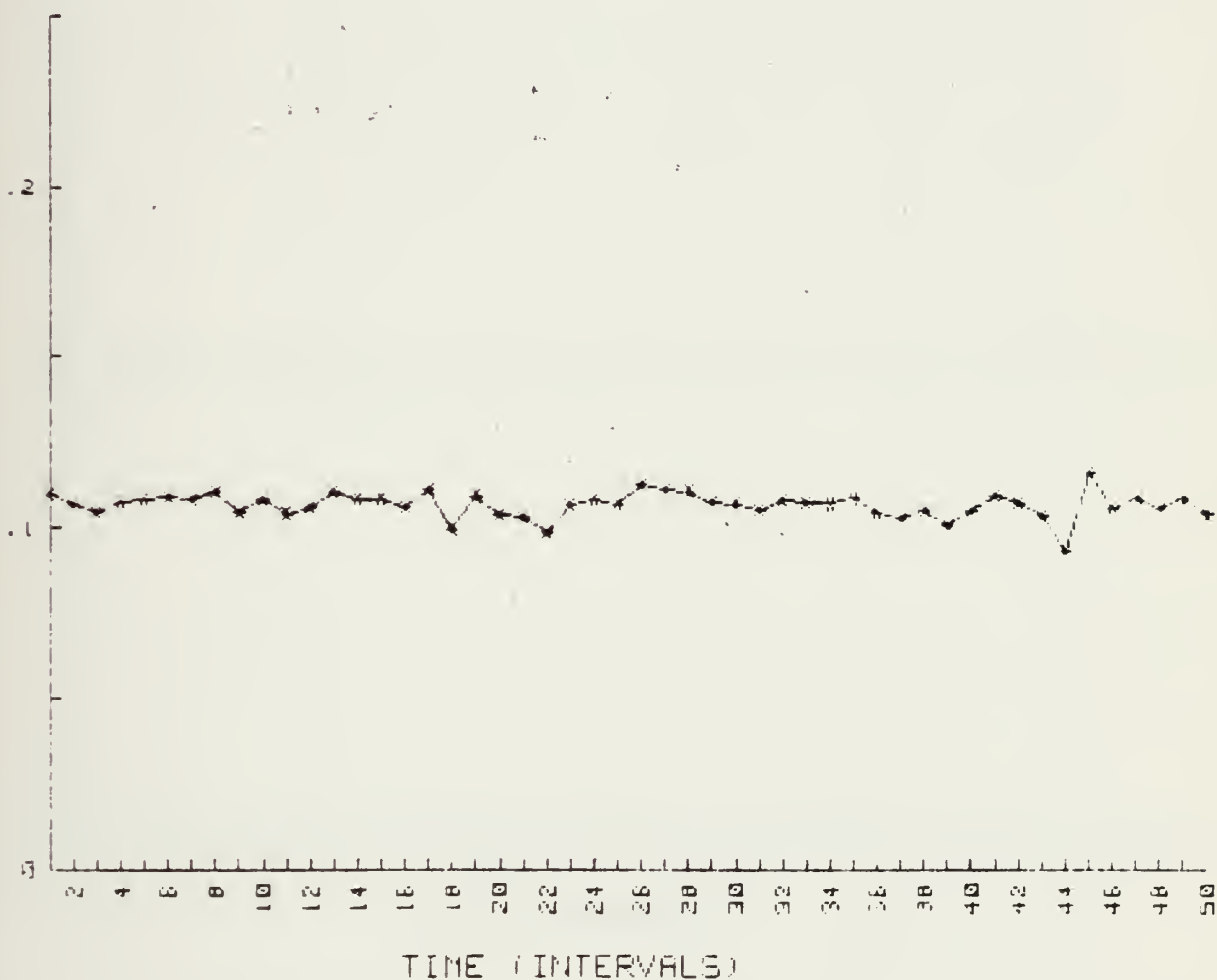


Fig. 27. Repetitive Samples with Fixed Probe Position
(10" Left of CTR Midspan, End Walls at 30°,
Lower Plane $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P(\text{amb}) / Q_{\text{ref}}$
 CENTER 30 DEG LOWER

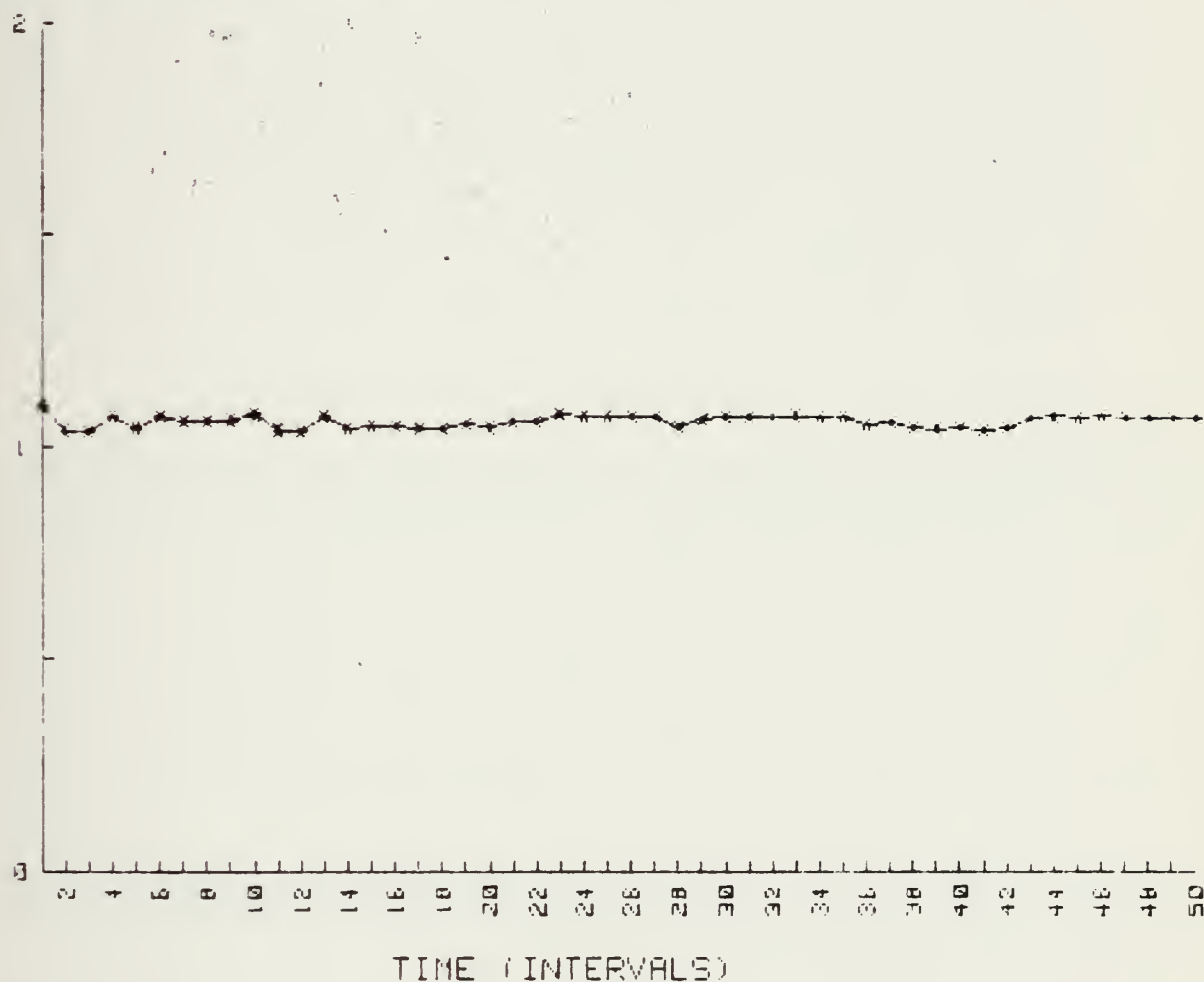


Fig. 28. Repetitive Samples with Fixed Probe Position
 (on Centerline at Midspan, End Walls at 30°,
 Lower Plane $(P_{\text{PLENUM}} - P_{\text{AMB}}) / Q_{\text{ref}}$)

$P_t - P_{amb}) / Q_{ref}$
 CENTER 30 DEG LOWER

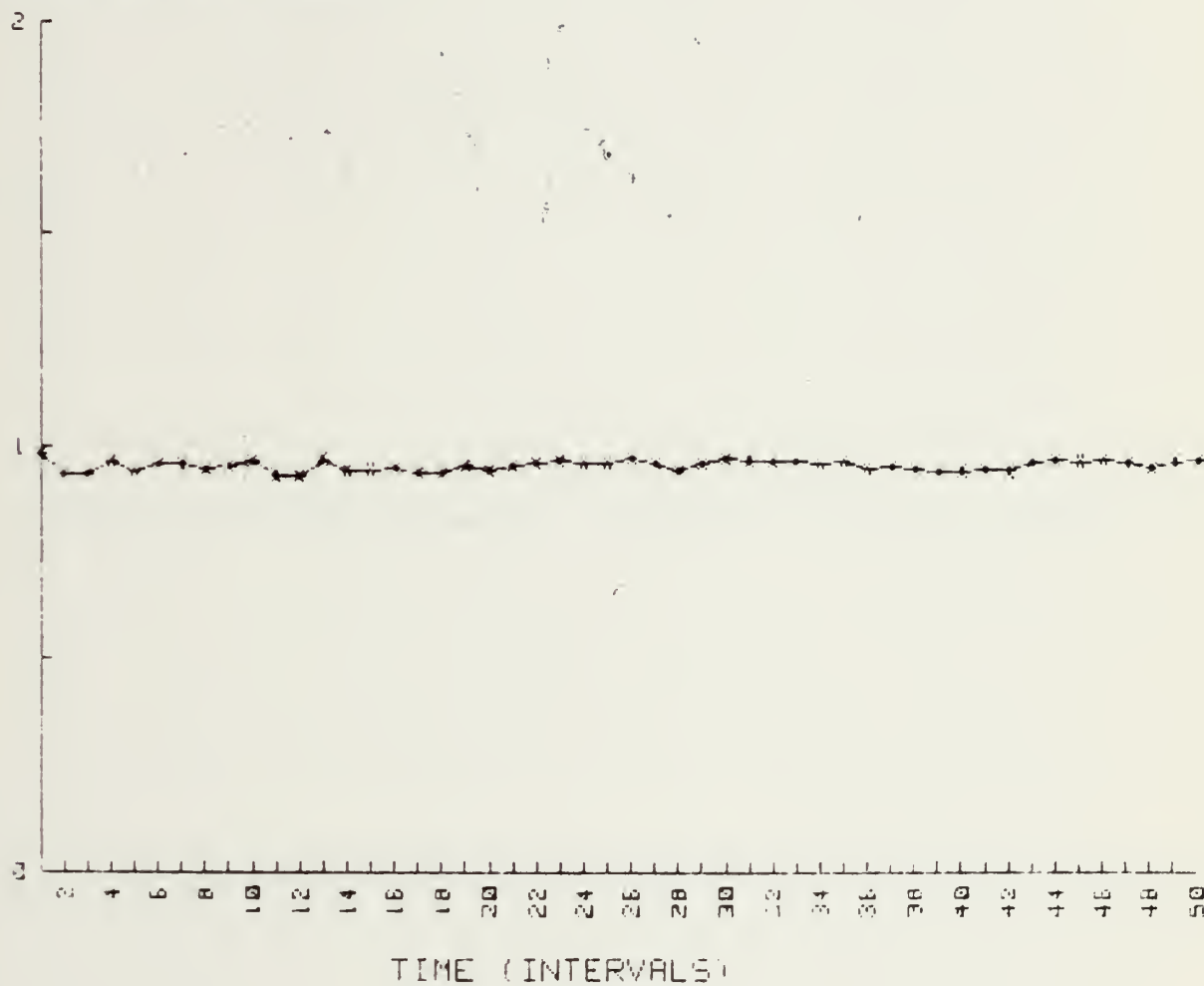


Fig. 29. Repetitive Samples with Fixed Probe Position
 (on Centerline at Midspan, End Walls at 30°,
 Lower Plane $(P_t - P_{AMB}) / Q_{ref}$)

$P(\text{plenum}) - P_t / Q_{\text{ref}}$
 CENTER 30 DEG LOWER

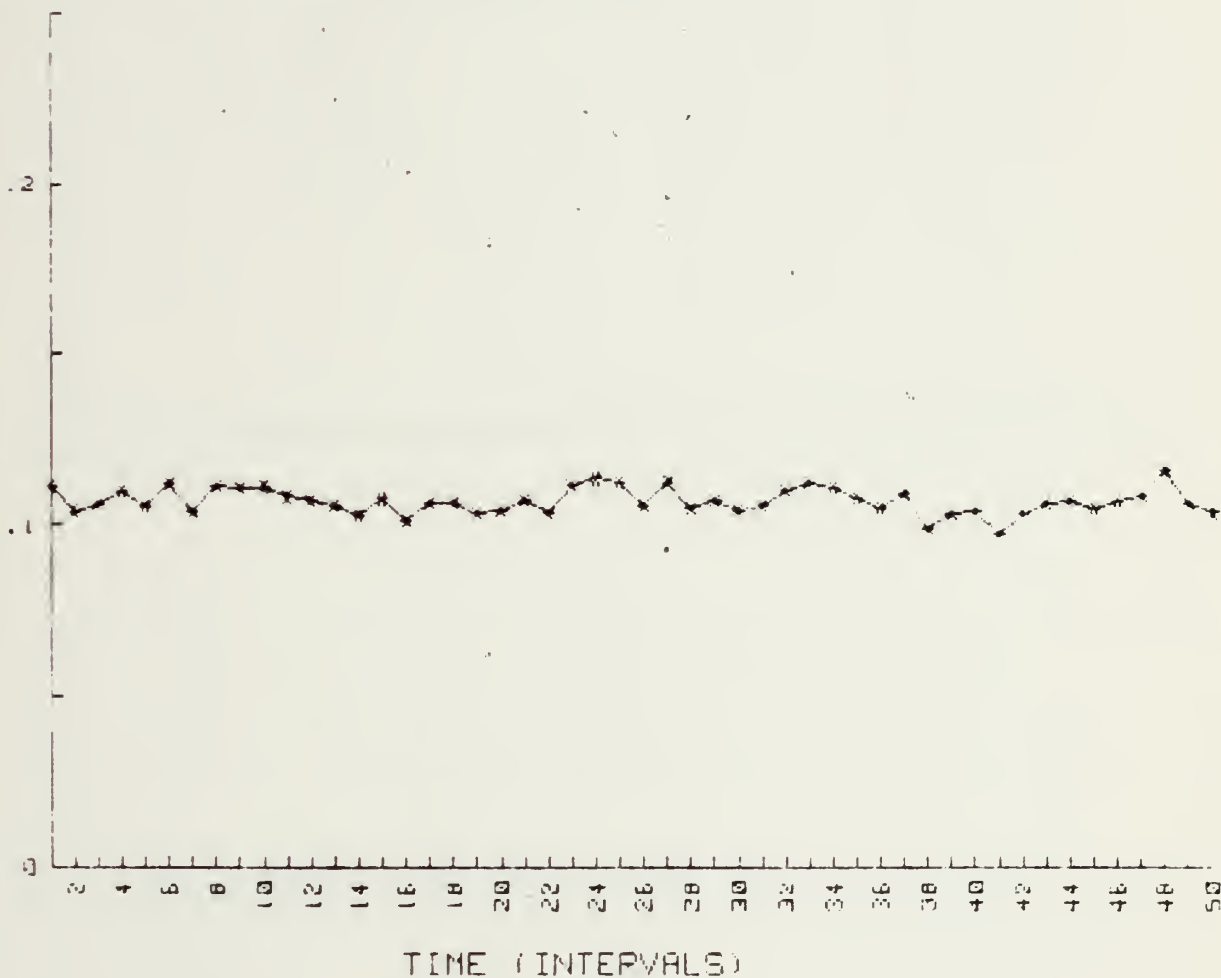


Fig. 30. Repetitive Samples with Fixed Probe Position
 (on Centerline at Midspan, End Walls at 30°,
 Lower Plane $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$)

$P(\text{plenum}) - P(\text{amb}) / Q_{\text{ref}}$
 10 INCHES RT OF CTR 30 DEG LOWER

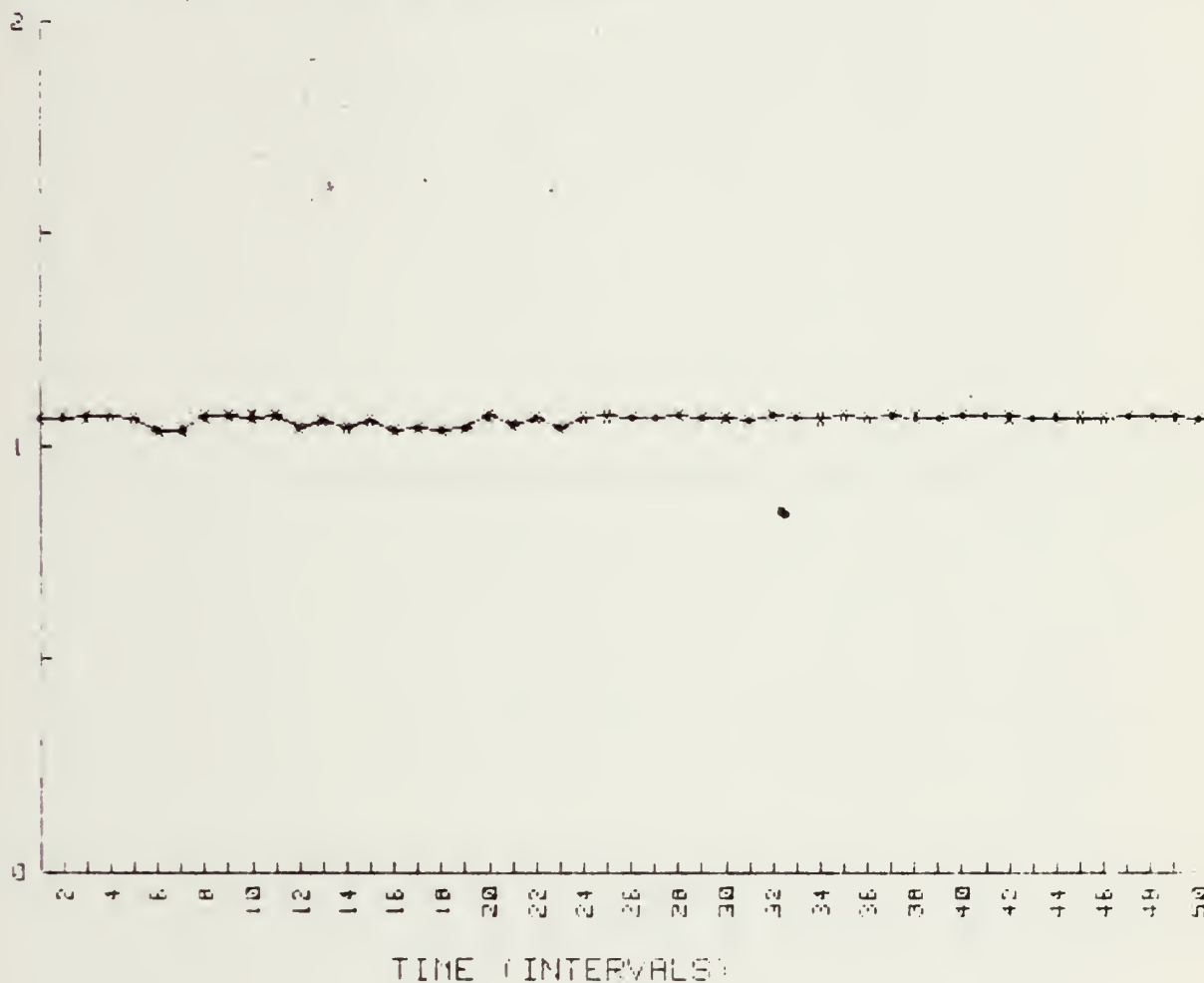


Fig. 31. Repetitive Samples with Fixed Probe Position
 (10" Right of CTR Midspan, End Walls at 30°,
 Lower Plane ($P_{\text{PLENUM}} - P_{\text{AMB}}) / Q_{\text{ref}}$)

$P_t - P_{amb} / Q_{ref}$
 10 INCHES RT OF CTR 30 DEG LOWER

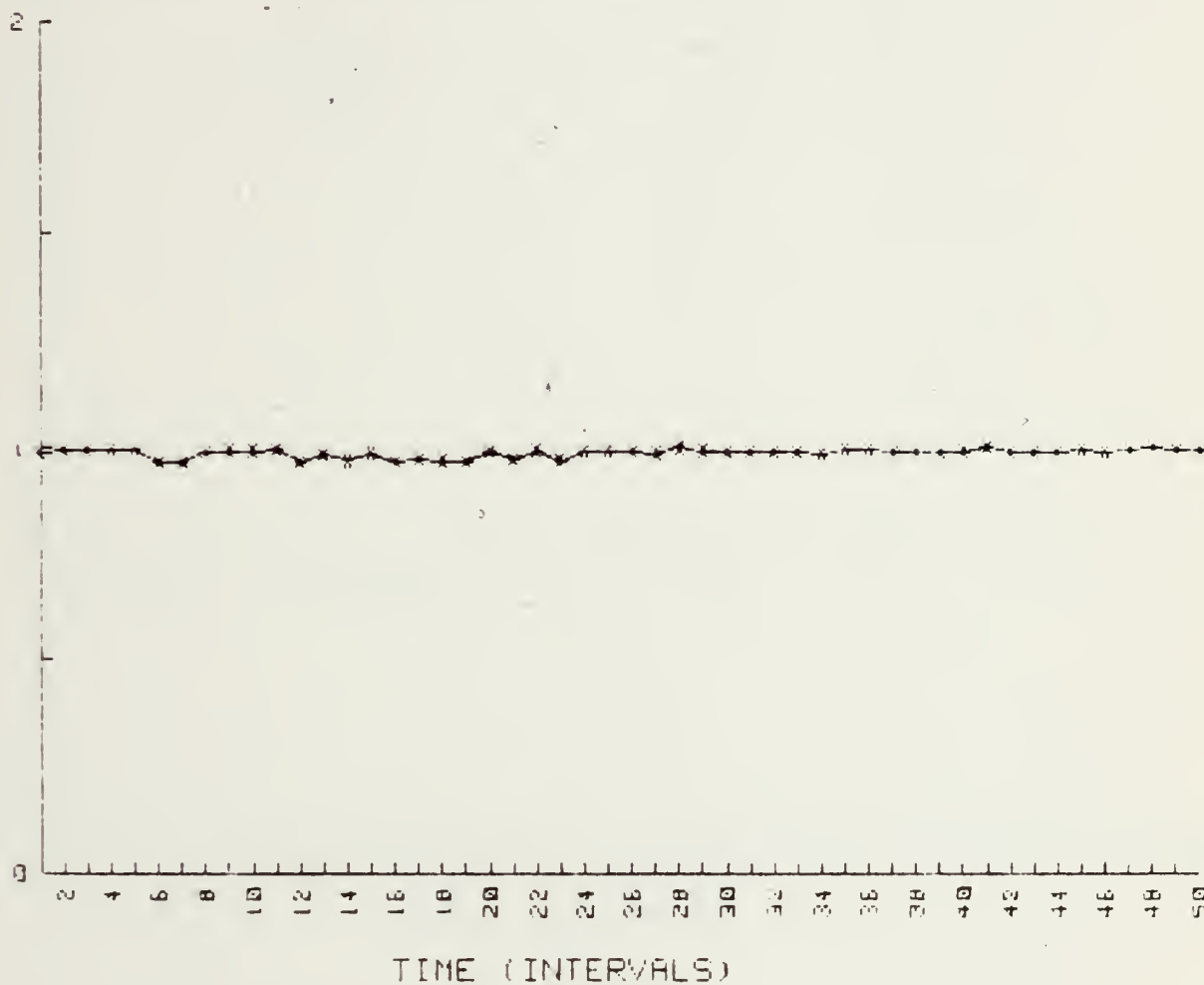


Fig. 32. Repetitive Samples with Fixed Probe Position
 (10" Right of CTR Midspan, End Walls at 30°,
 Lower Plane $(P_t - P_{AMB}) / Q_{ref}$)

$P(\text{plenum}) - P_t / Q_{\text{ref}}$
 10 INCHES RT OF CTR 30 DEG LOWER

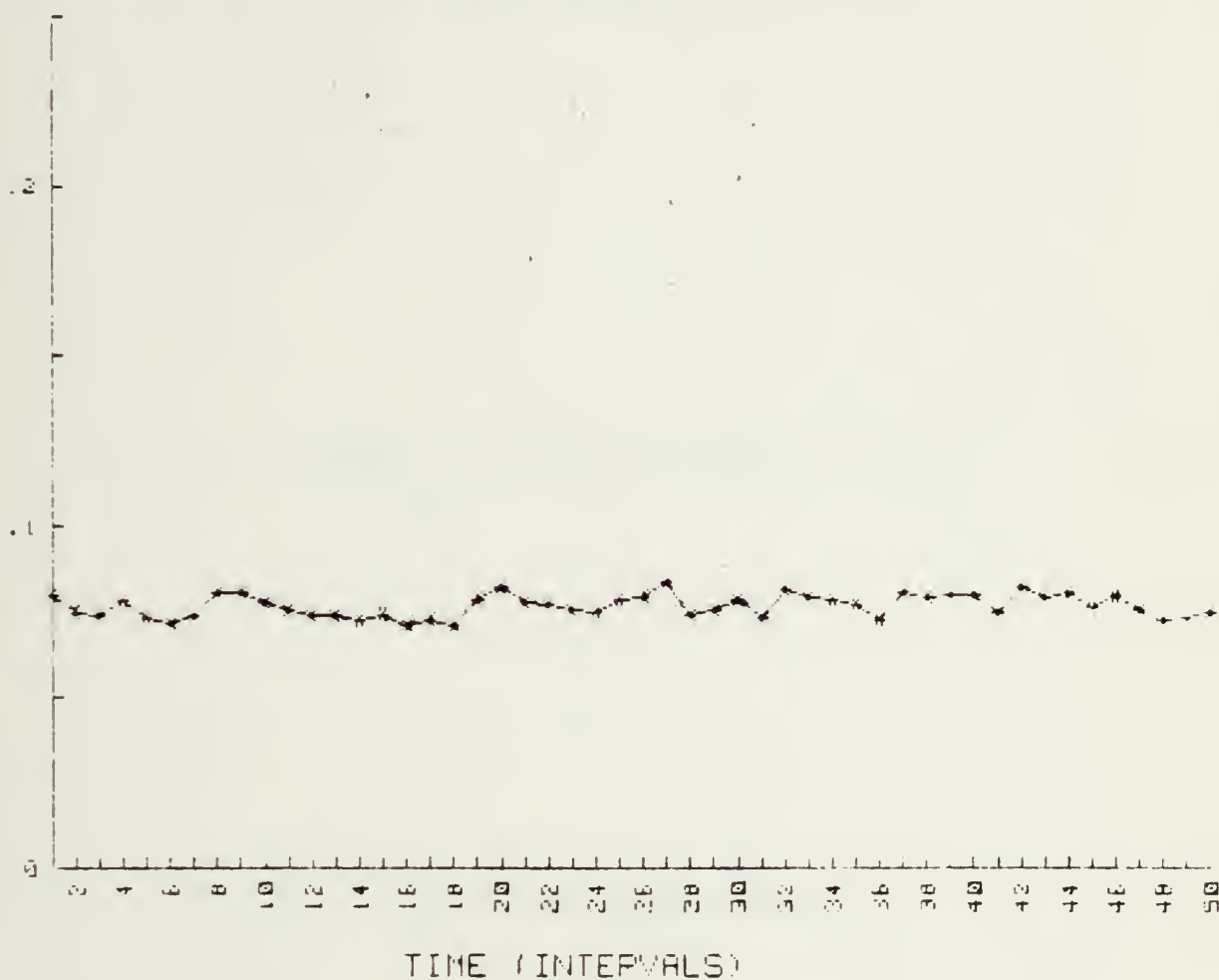


Fig. 33. Repetitive Samples with Fixed Probe Position
 (10" Right of CTR Midspan, End Walls at 30°,
 Lower Plane ($P_{\text{PLENUM}} - P_t$)/ Q_{ref})

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 1 TO 50 LOWER PLANE 35 DEG TEMP SCREEN

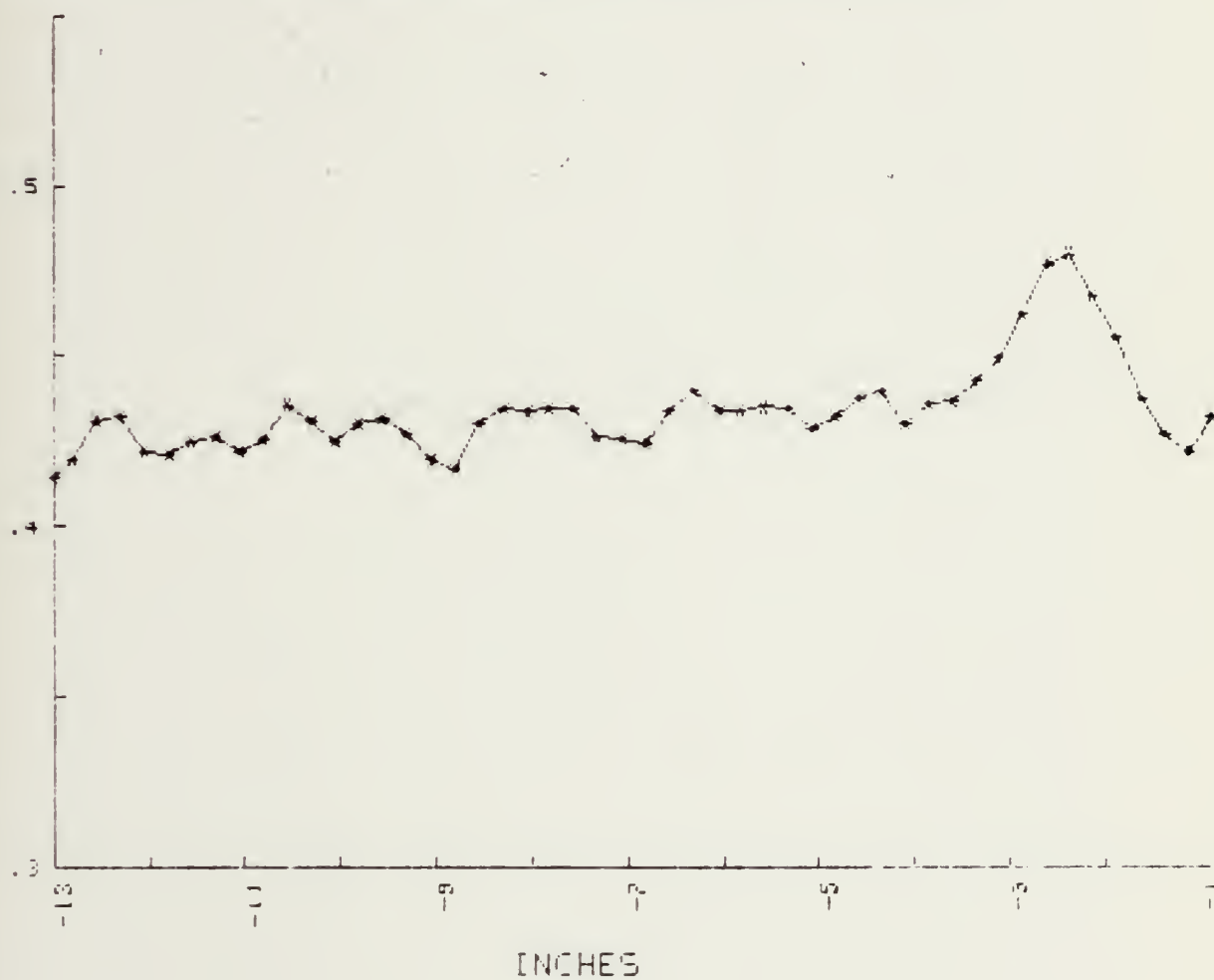


Fig. 34. Probe Survey Data at Midspan, Lower Plane
16 Mesh Screen, Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$(P_{\text{plenum}} - P_t) / Q_{\text{ref}}$

POINTS 51 TO 100 LOWER PLANE 35 DEG TEMP SCREEN

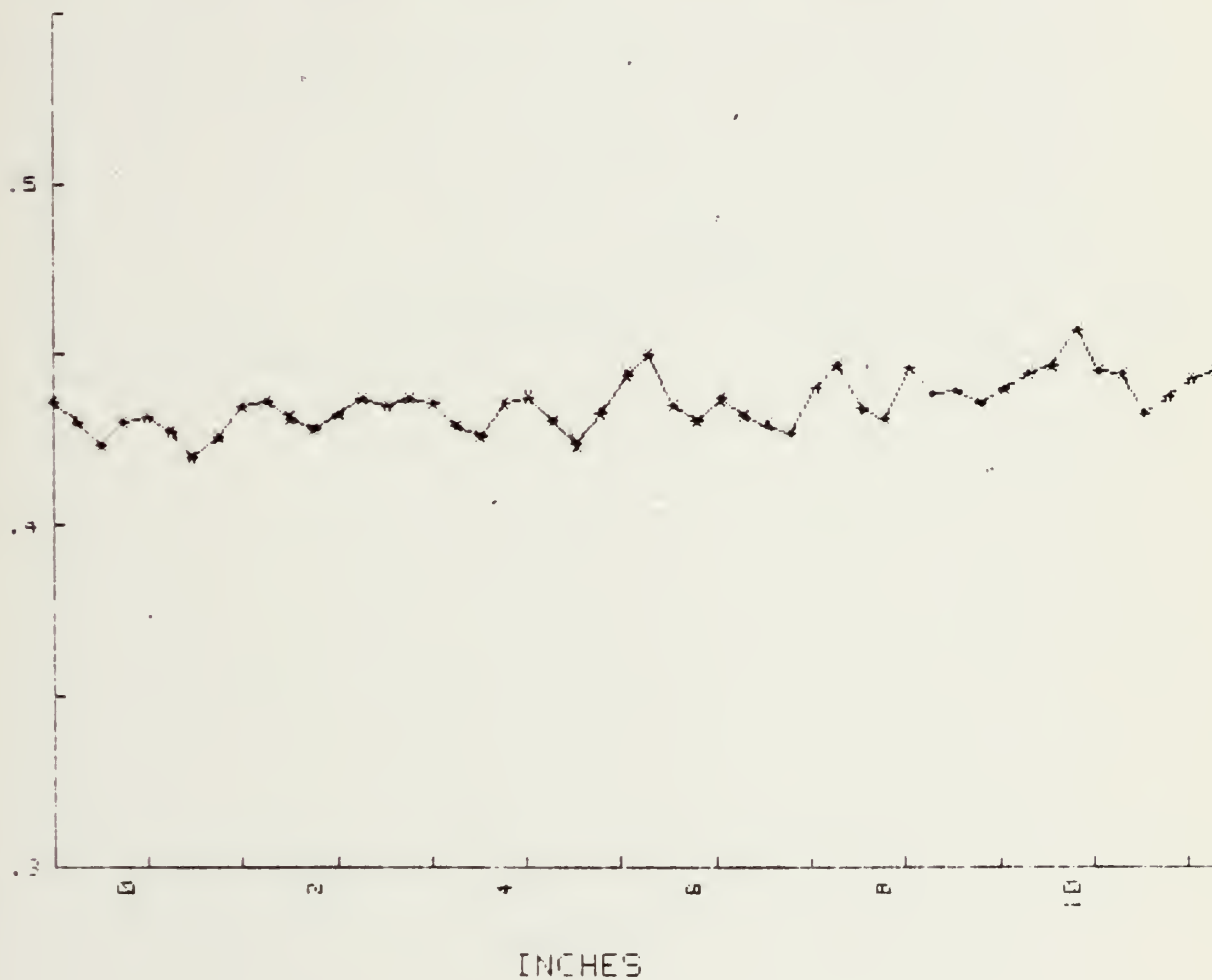


Fig. 35. Probe Survey Data at Midspan, Lower Plane
16 Mesh Screen, Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 1 TO 50 UPPER PLANE 35 DEG TEMP SCREEN

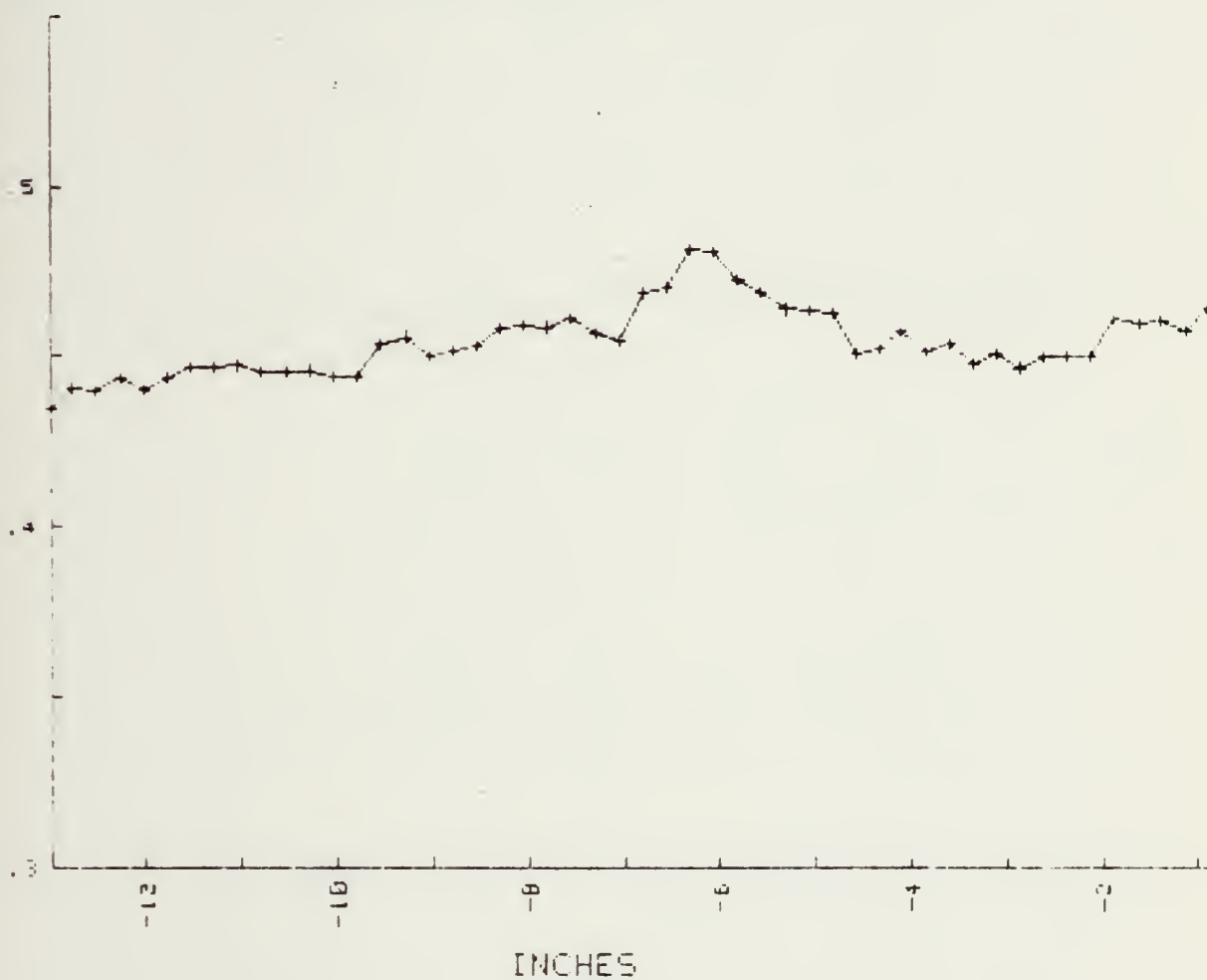


Fig. 36. Probe Survey Data at Midspan, Upper Plane
16 Mesh Screen, Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

POINTS 51 TO 100 UPPER PLANE 35 DEG TEMP SCREEN

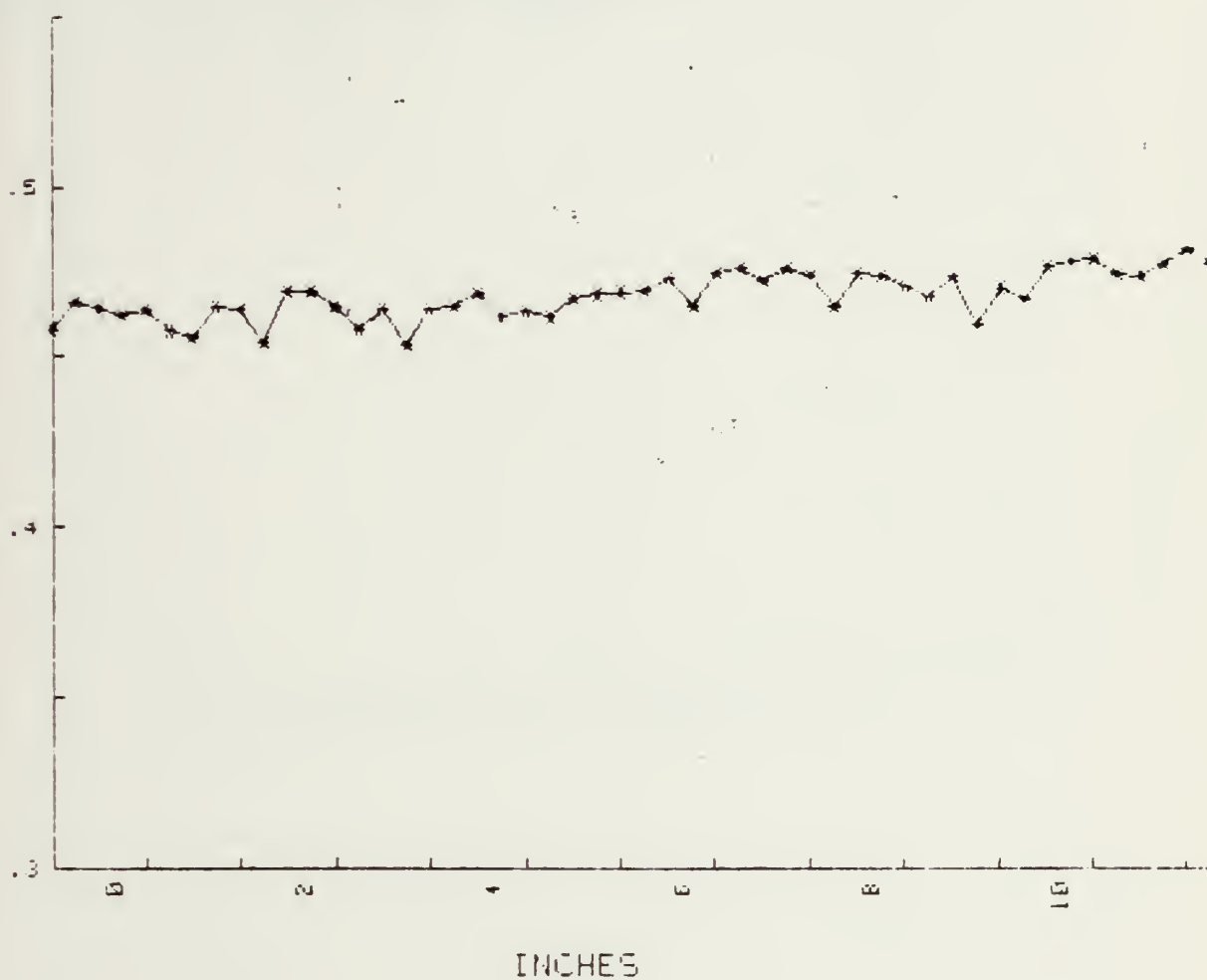


Fig. 37. Probe Survey Data at Midspan, Upper Plane
16 Mesh Screen, Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$(P_{\text{plenum}} - P_t)/Q_{\text{ref}}$
 10 in. LEFT OF CTR SPAN TRAVERSE
 35 DEG UPPER PLANE TEMP SCREEN

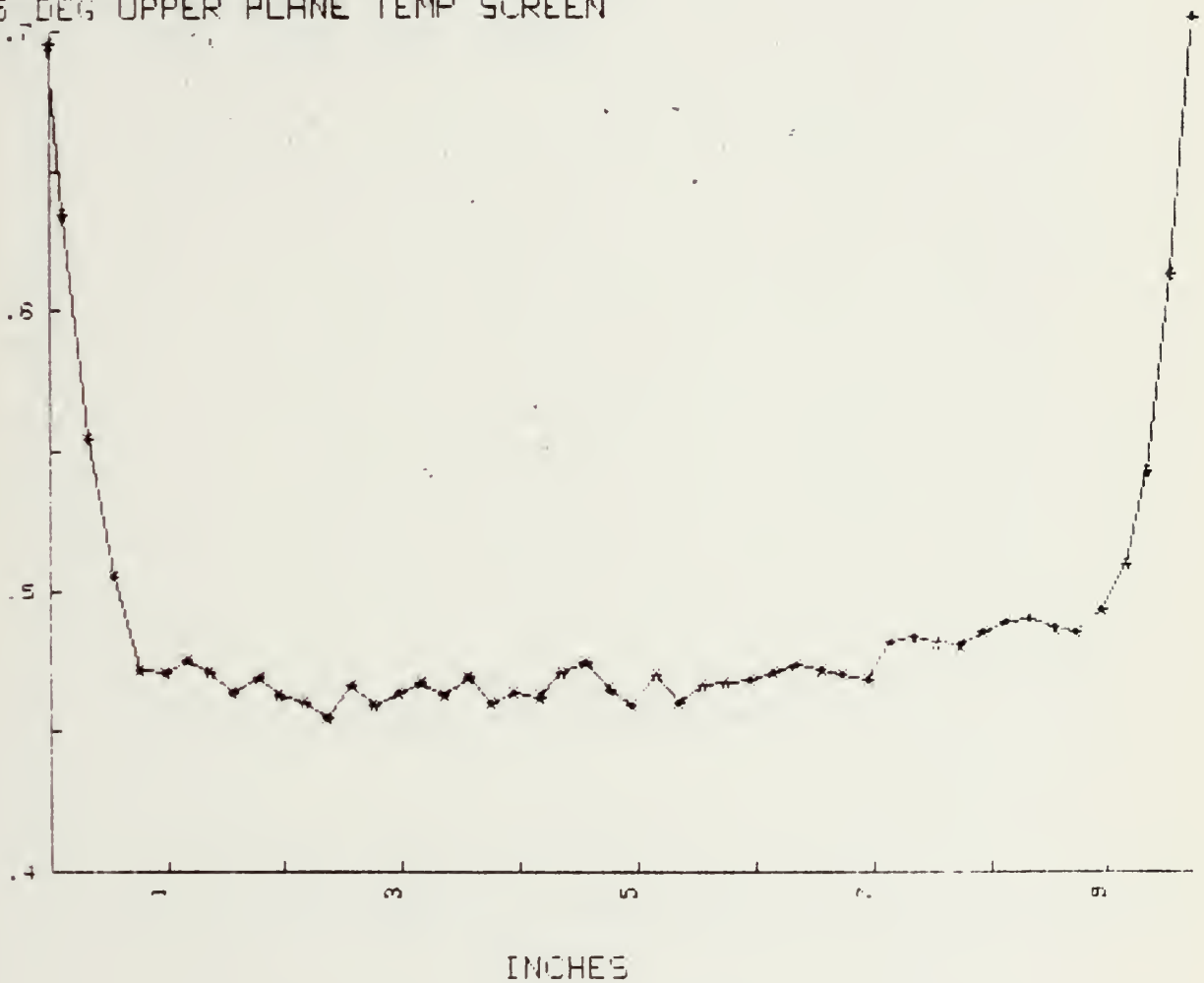


Fig. 38. Probe Survey Data Span Traverse, Lower Plane
 16 Mesh Screen, Walls at 35°, 10" Left of CTR
 $(P_{\text{PLENUM}} - P_t)/Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$
 CTR SPAN TRAVERSE
 35 DEG UPPER PLANE TEMP SCREEN

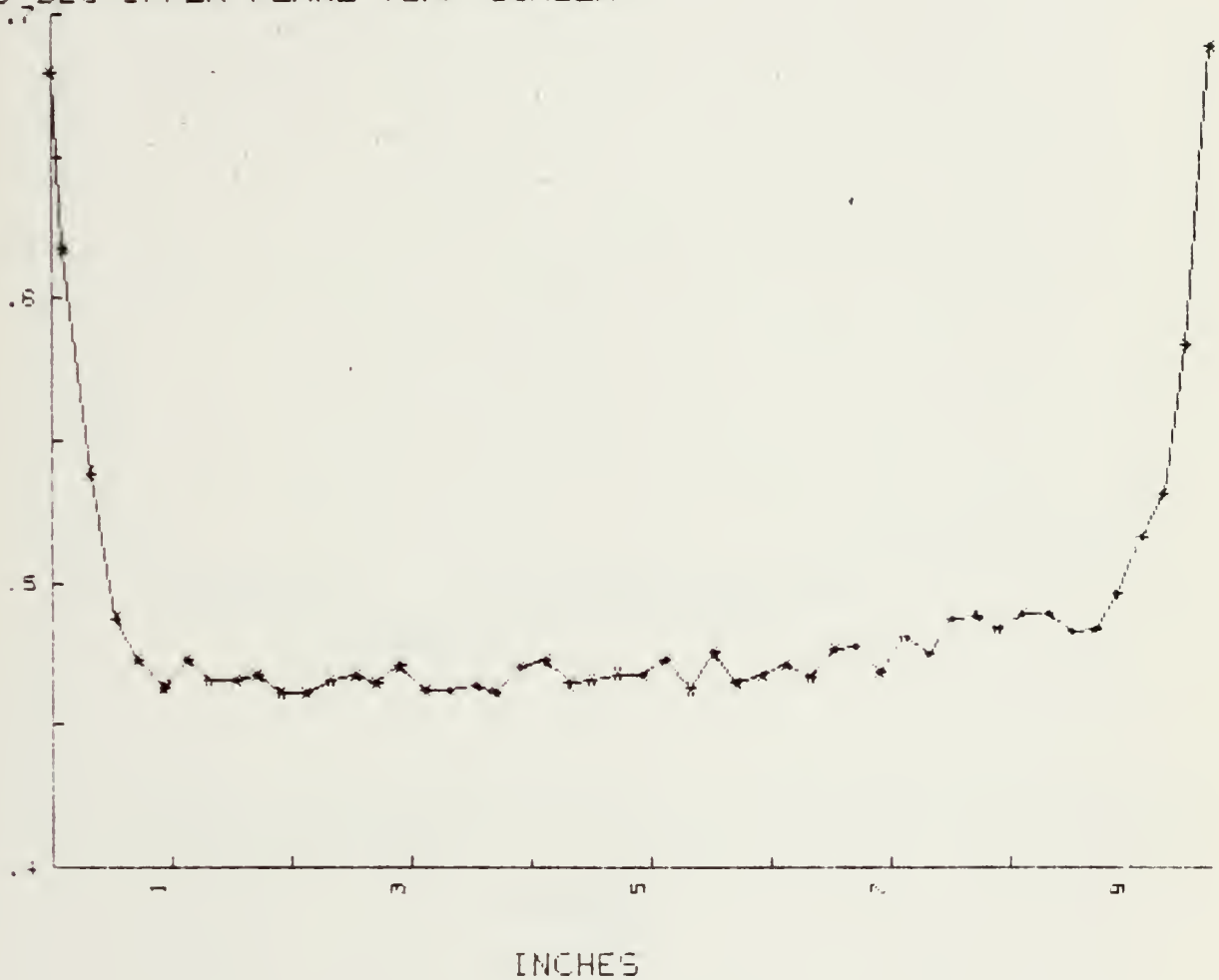


Fig. 39. Probe Survey Data Span Traverse, Lower Plane
 16 Mesh Screen, Walls at 35°, Center of Test
 Section $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

10 in. RT OF CTR SPAN TRAVERSE

35 DEG UPPER PLANE TEMP SCREEN

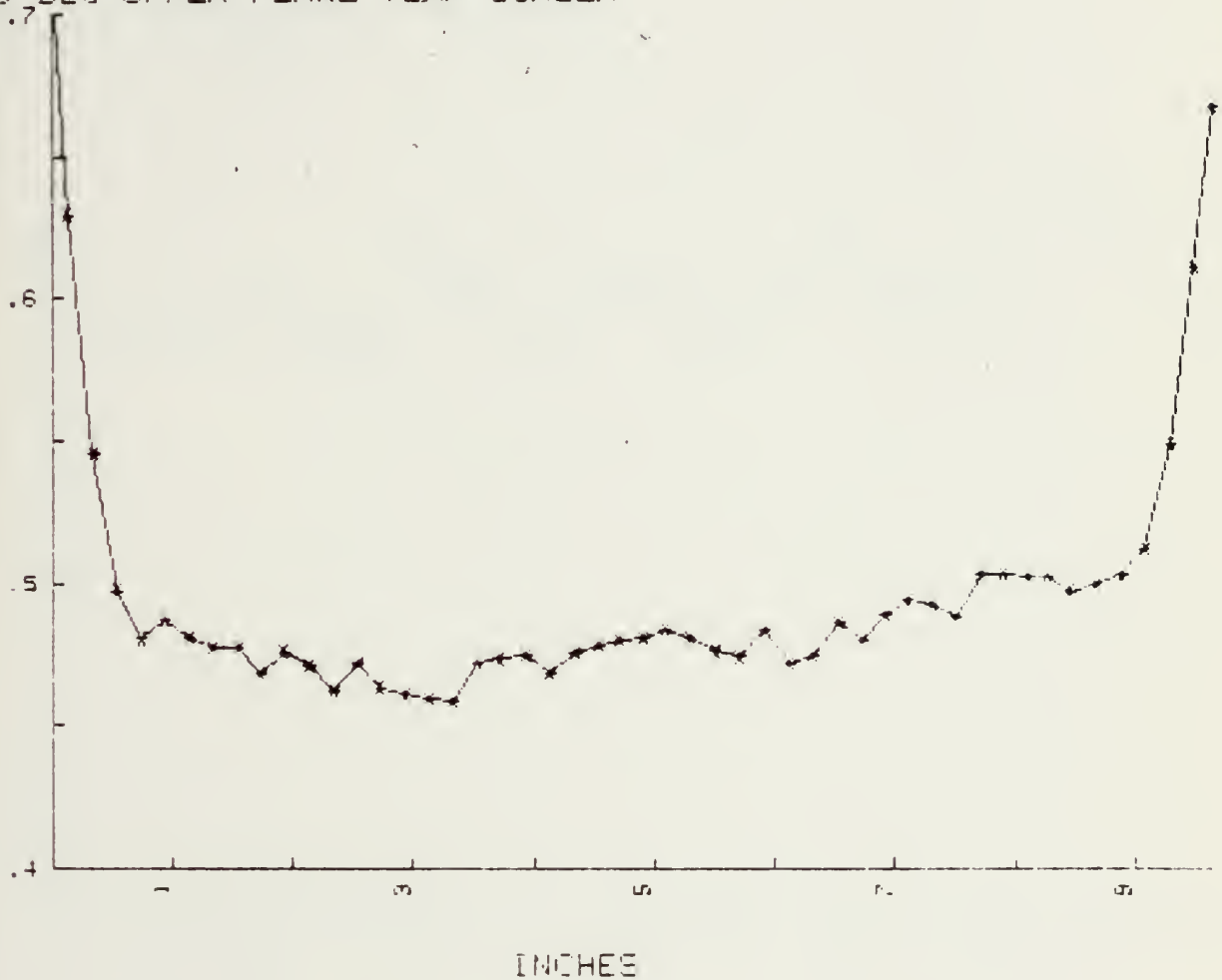


Fig. 40. Probe Survey Data Span Traverse, Lower Plane
16 Mesh Screen, Walls at 35°, Center of Test
Section $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$(P_{\text{plenum}} - P_t) / Q_{\text{ref}}$
 35 DEG LOWER PLANE 2 SCREENS
 POINTS 1 TO 50

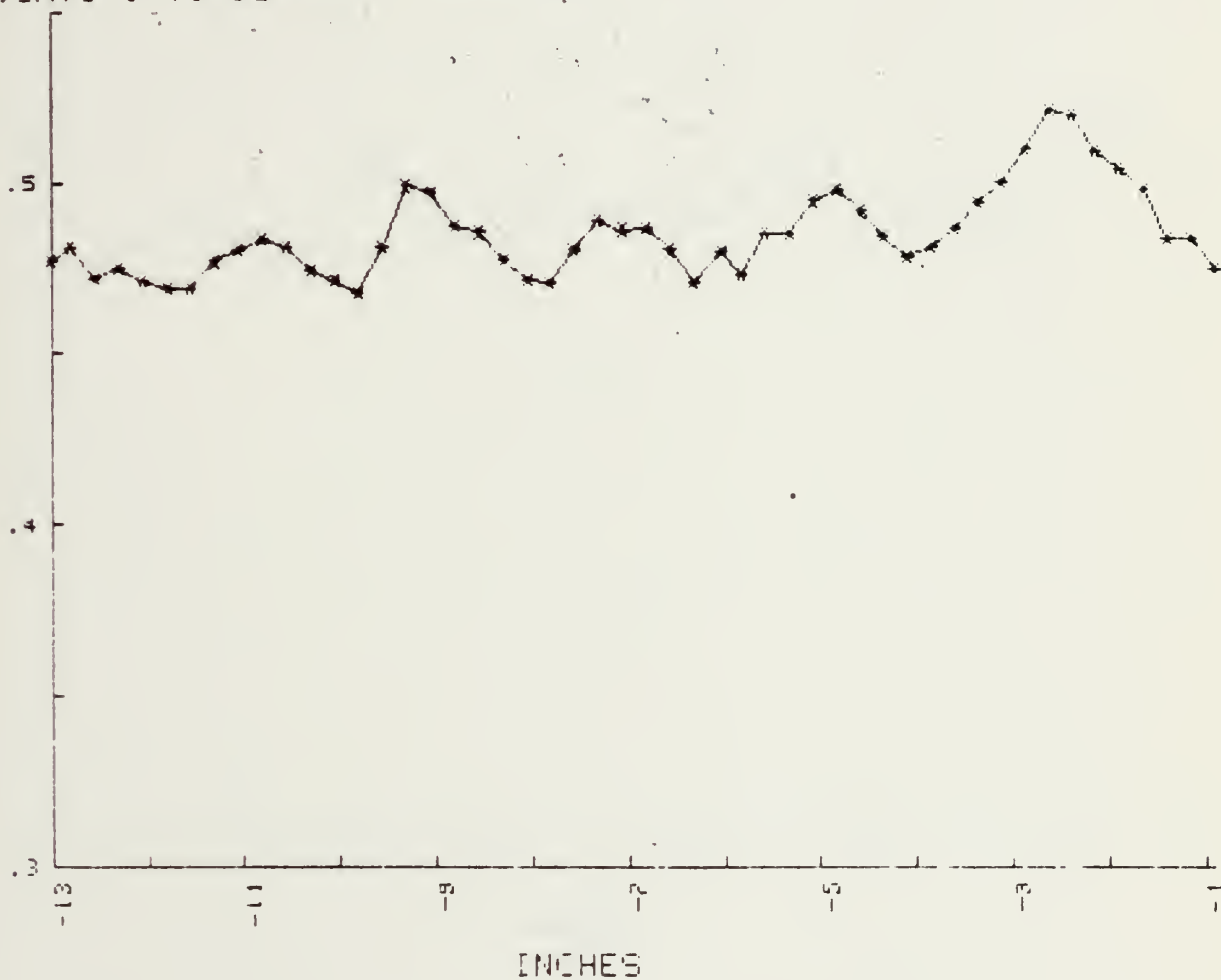


Fig. 41. Probe Survey Data at Midspan, Lower Plane
 16 Mesh and 2 Mesh, Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$
 35 DEG LOWER PLANE 2 SCREENS
 POINTS 51 TO 100

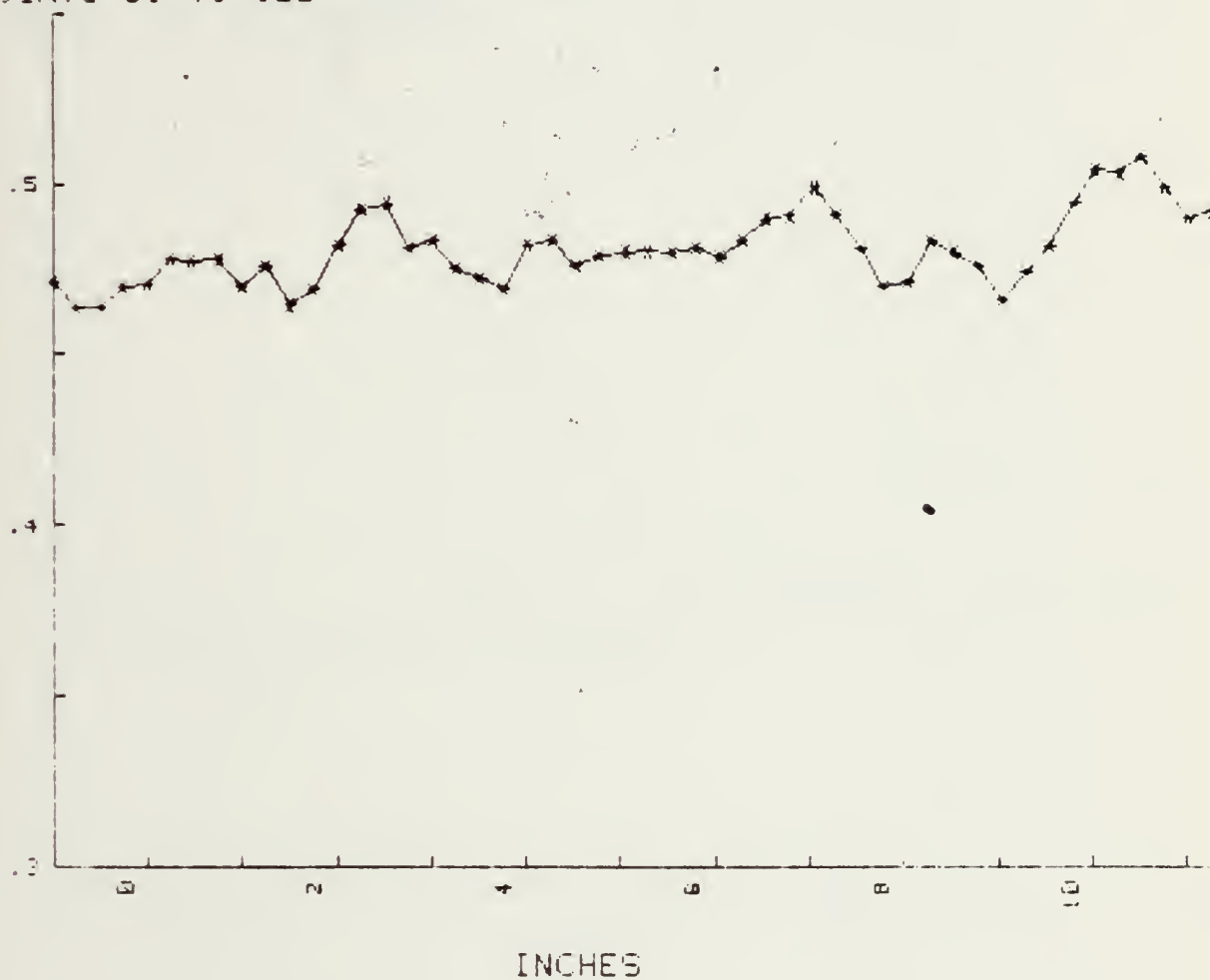


Fig. 42. Probe Survey Data at Midspan, Lower Plane
 16 Mesh and 2 Mesh, Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

PT 1 TO 50 LOWER PLANE 35 DEG

4 MESH .041 WIRE SCREEN

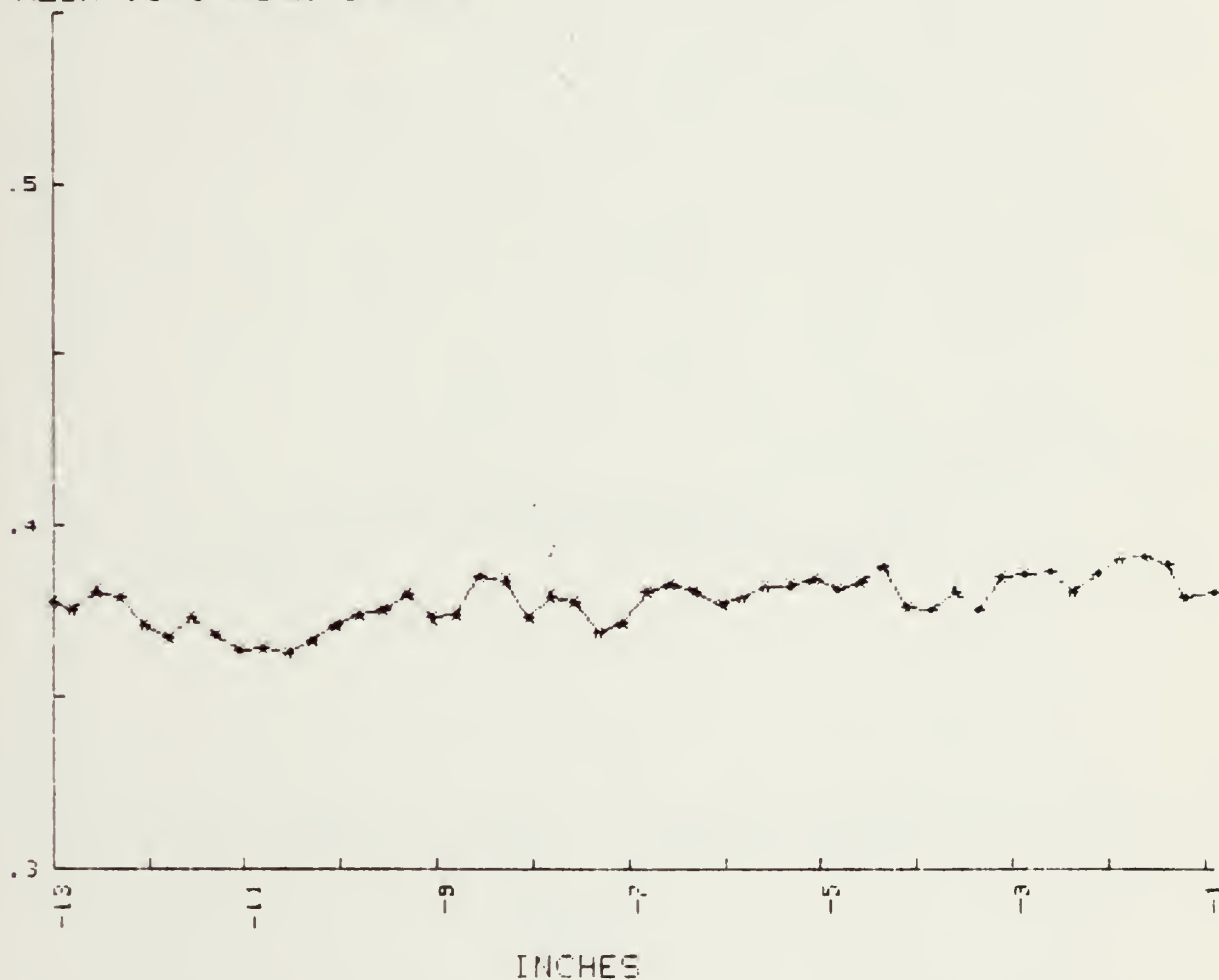


Fig. 43. Probe Survey Data at Midspan, Lower Plane
4 Mesh Screen, Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_1 / Q_{\text{ref}}$
 PT 51 TO 100 LOWER PLANE 35 DEG
 4 MESH .041 WIRE SCREEN

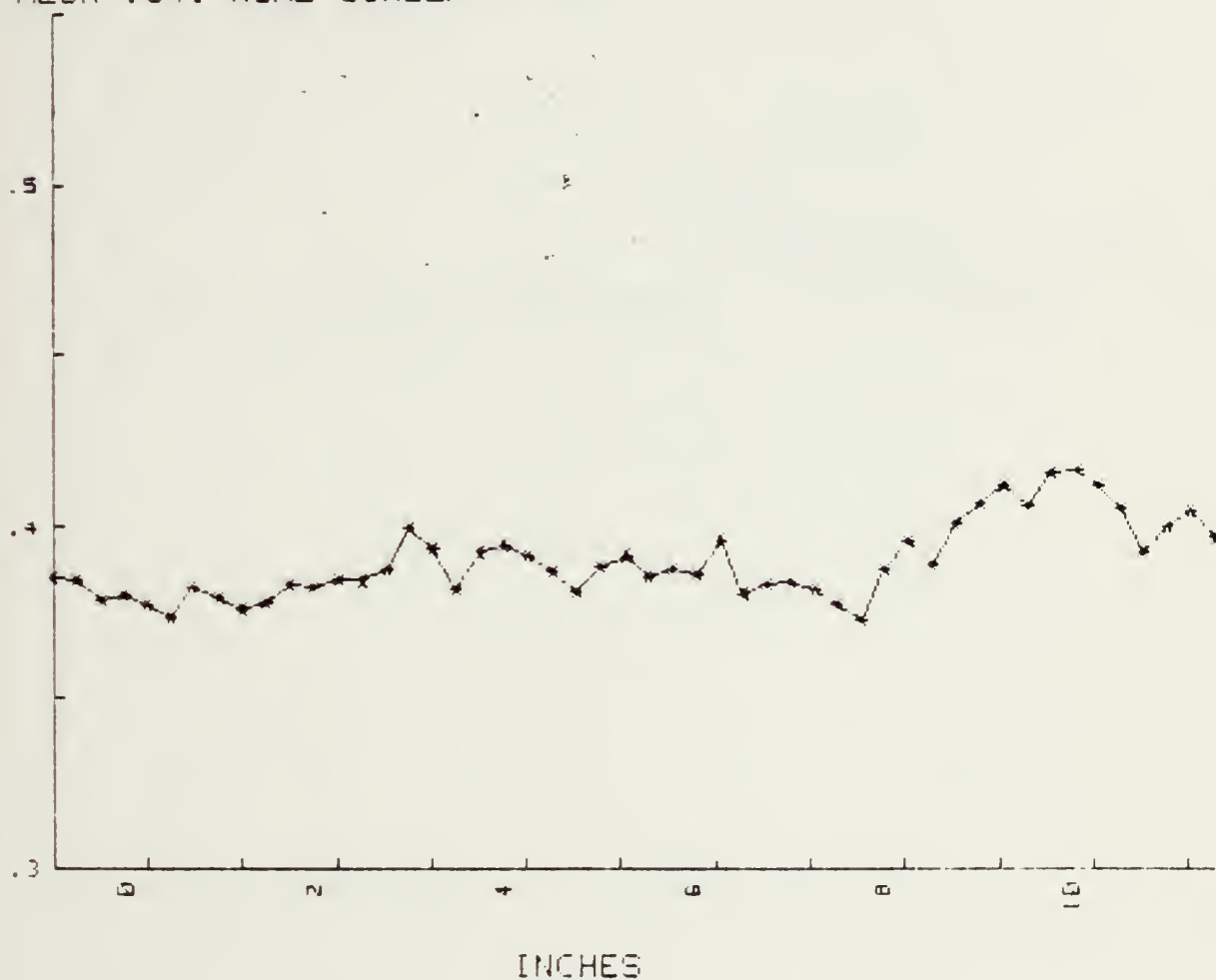


Fig. 44. Probe Survey Data at Midspan, Lower Plane
 4 Mesh Screen, Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$

PT 1 TO 50 LOWER PLANE 35 DEG

5 MESH .041 WIRE SCREEN

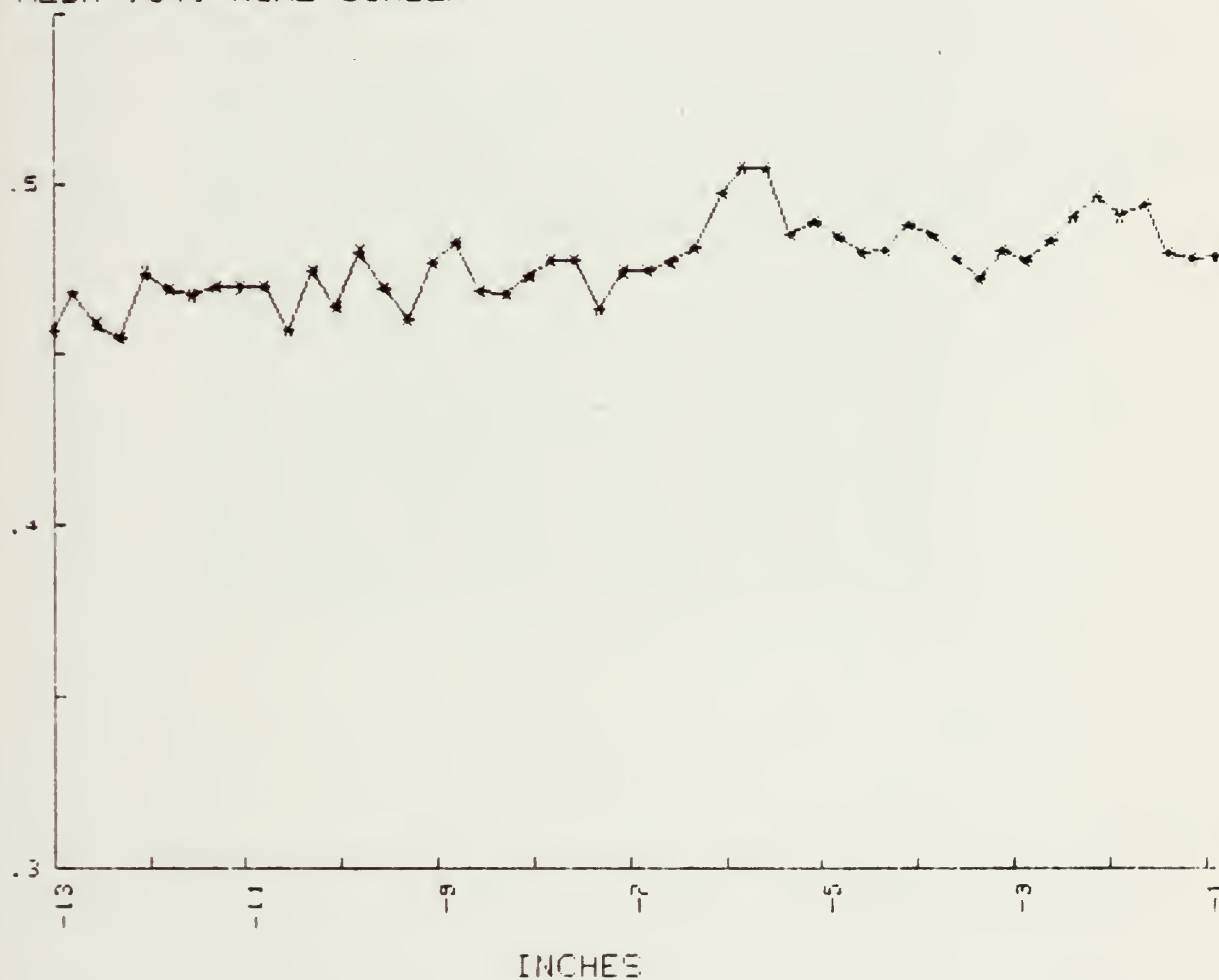


Fig. 45. Probe Survey Data at Midspan, Lower Plane
5 Mesh Screen, Walls at 35°, Points 1 to 50
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

$P(\text{plenum}) - P_t / Q_{\text{ref}}$
 PT 51 TO 100 LOWER PLANE 35 DEG
 5 MESH .041 WIRE SCREEN

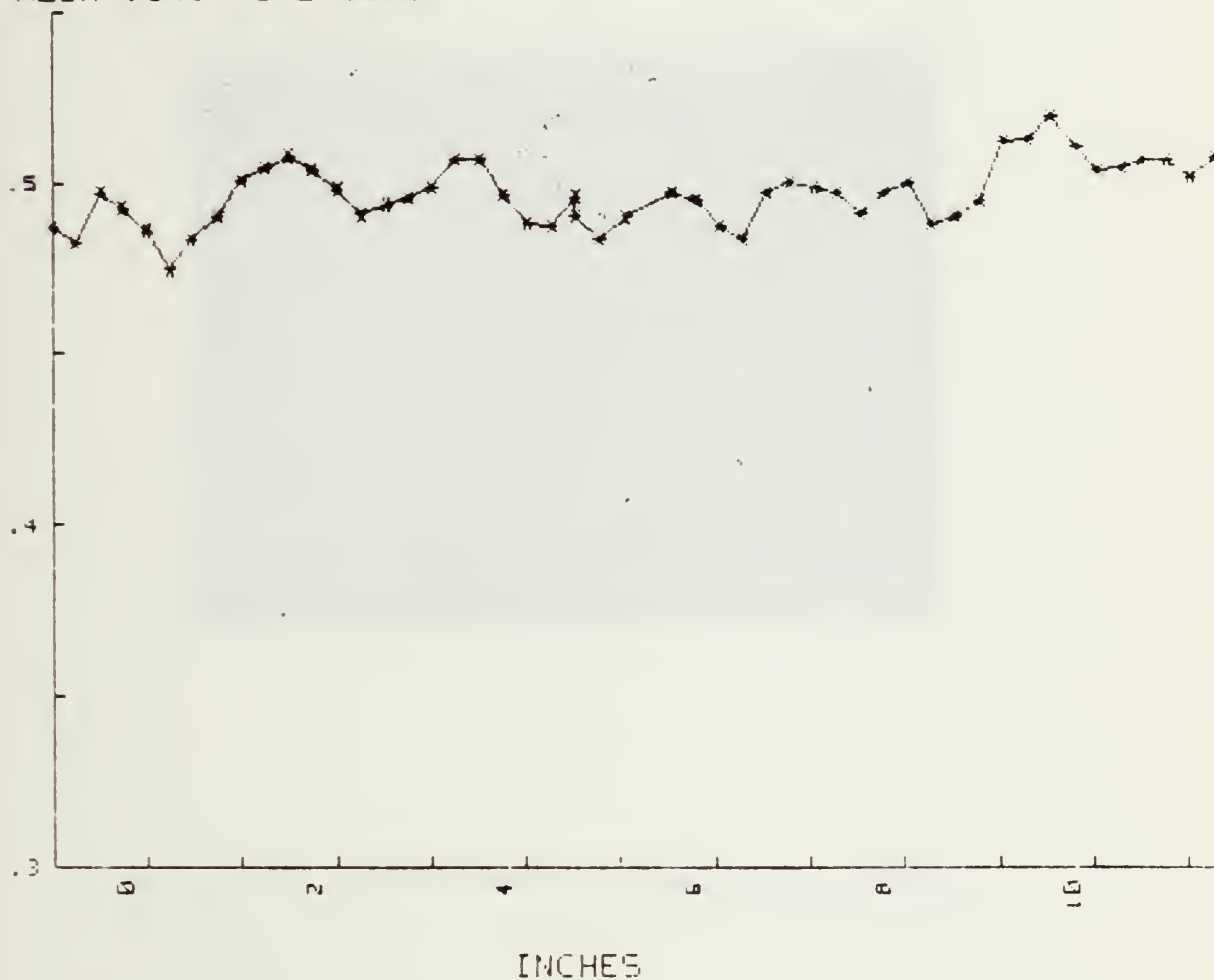


Fig. 46. Probe Survey Data at Midspan, Lower Plane
 5 Mesh Screen, Walls at 35°, Points 51 to 100
 $(P_{\text{PLENUM}} - P_t) / Q_{\text{ref}}$

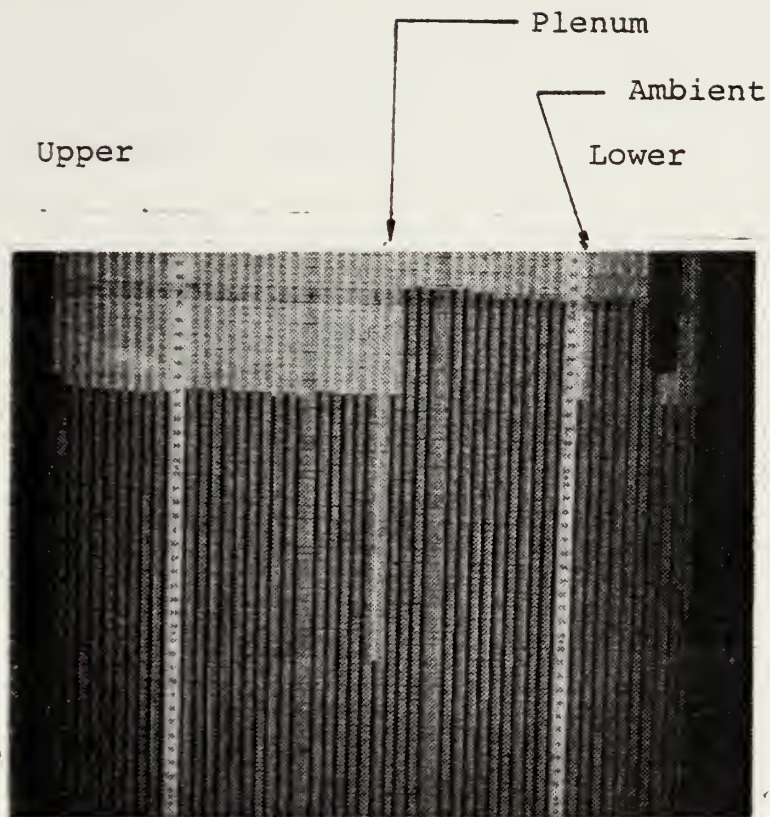


Fig. 47. Wall Static Pressure Distribution

($P_{\text{Plenum}} - P_t$) / \bar{Q}_1 bar
 LOWER PLANE MIDSPAN (i = 5.3)

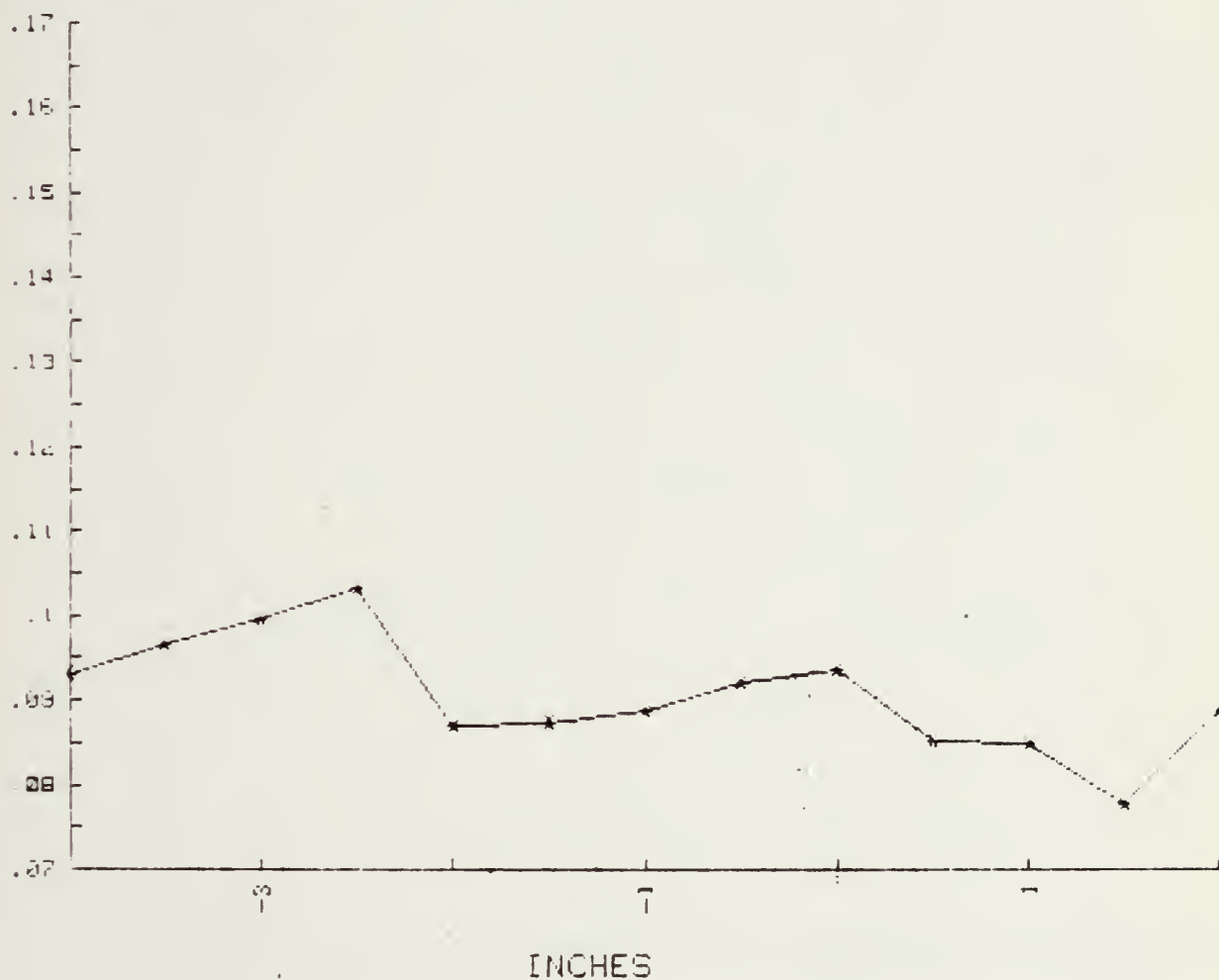
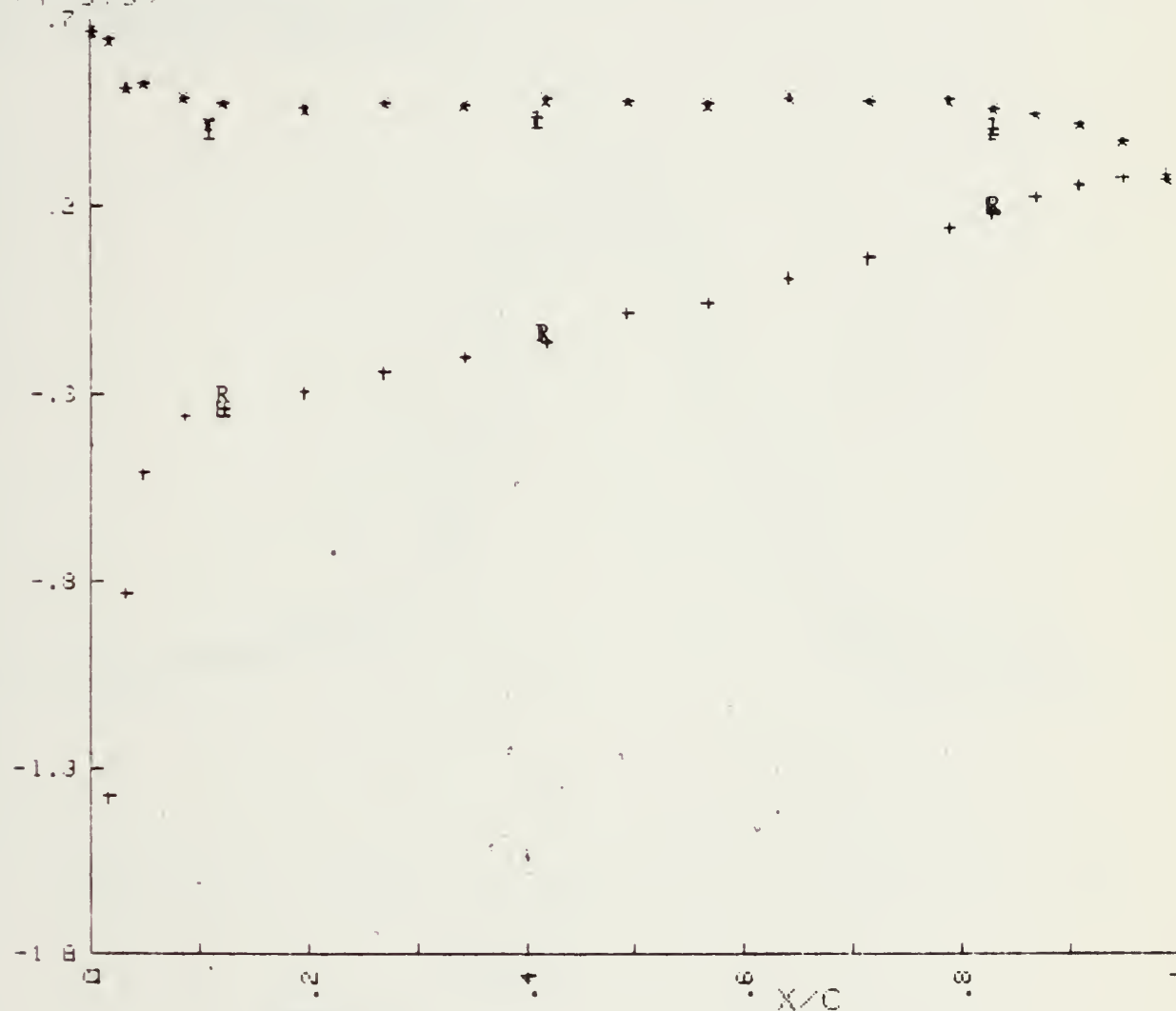


Fig. 48. Probe Survey Data at Upstream Midspan
 (i = 5.3, ($P_{\text{PLENUM}} - P_t$) / \bar{Q}_1 , Lower Plane)

C_{p1} vs X/C
 THREE CENTERMOST BLADES OVERLAYED
 $i = 5.3$



Symbols:

BLADE	LEFT	CENTER	RIGHT
Pressure Side	l	*	r
Suction Side	L	+	R

Fig. 49. Blade Surface Pressure Distribution on Three Centermost Blades ($i = 5.3$)

$(P_{\text{plenum}} - P_t) / Q_1 \text{ bar}$
 UPPER PLANE MIDSPAN ($i = 5.3$)
 (THREE PASSAGES OVERLAYED)

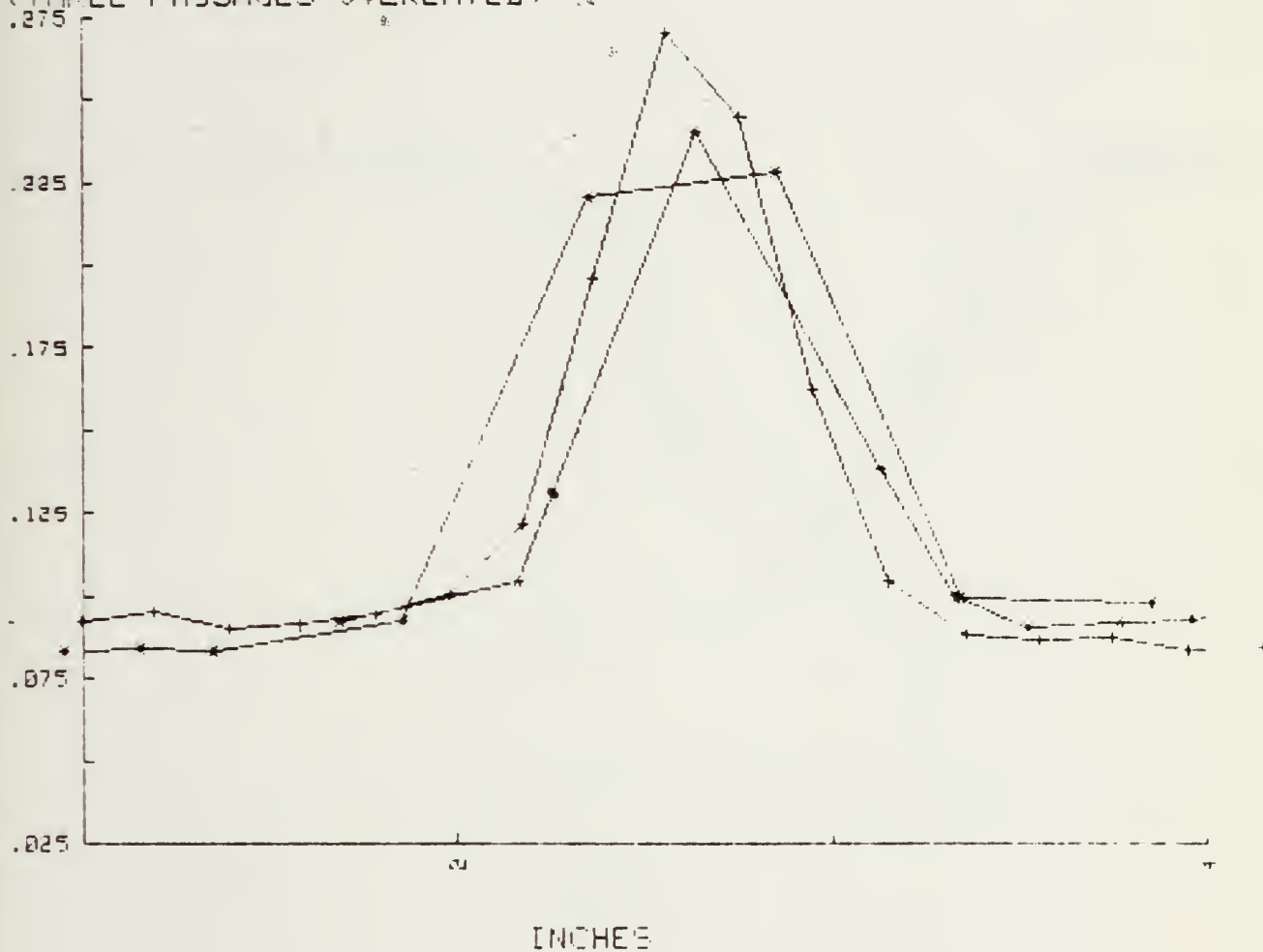


Fig. 50. Probe Survey Data at Midspan
 ($i = 5.3$, $(P_{\text{PLENUM}} - P_t) / Q_1$, Upper Plane)

X/\bar{X}
 UPPER PLANE MIDSPAN ($i=5.3$)
 (THREE PASSAGES OVERLAYED)

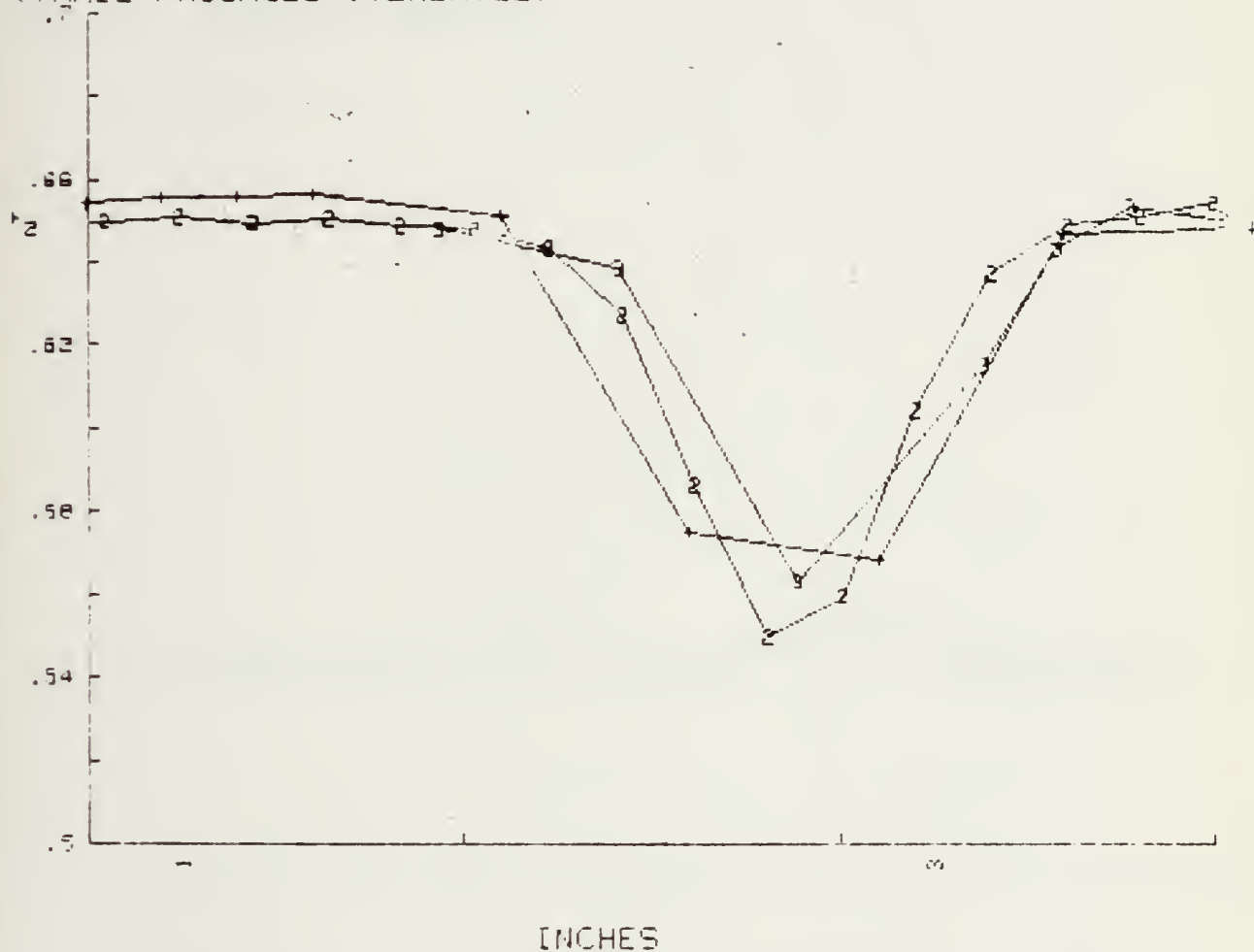


Fig. 51. Probe Survey Data at Midspan
 ($i = 5.3$, (X/\bar{X}) , Upper Plane)

$(P_s - P_{w1}) / Q_1 \text{ bar}$
 UPPER PLANE MIDSPAN ($i = 5.3$)
 (THREE PASSAGES OVERLAYED)

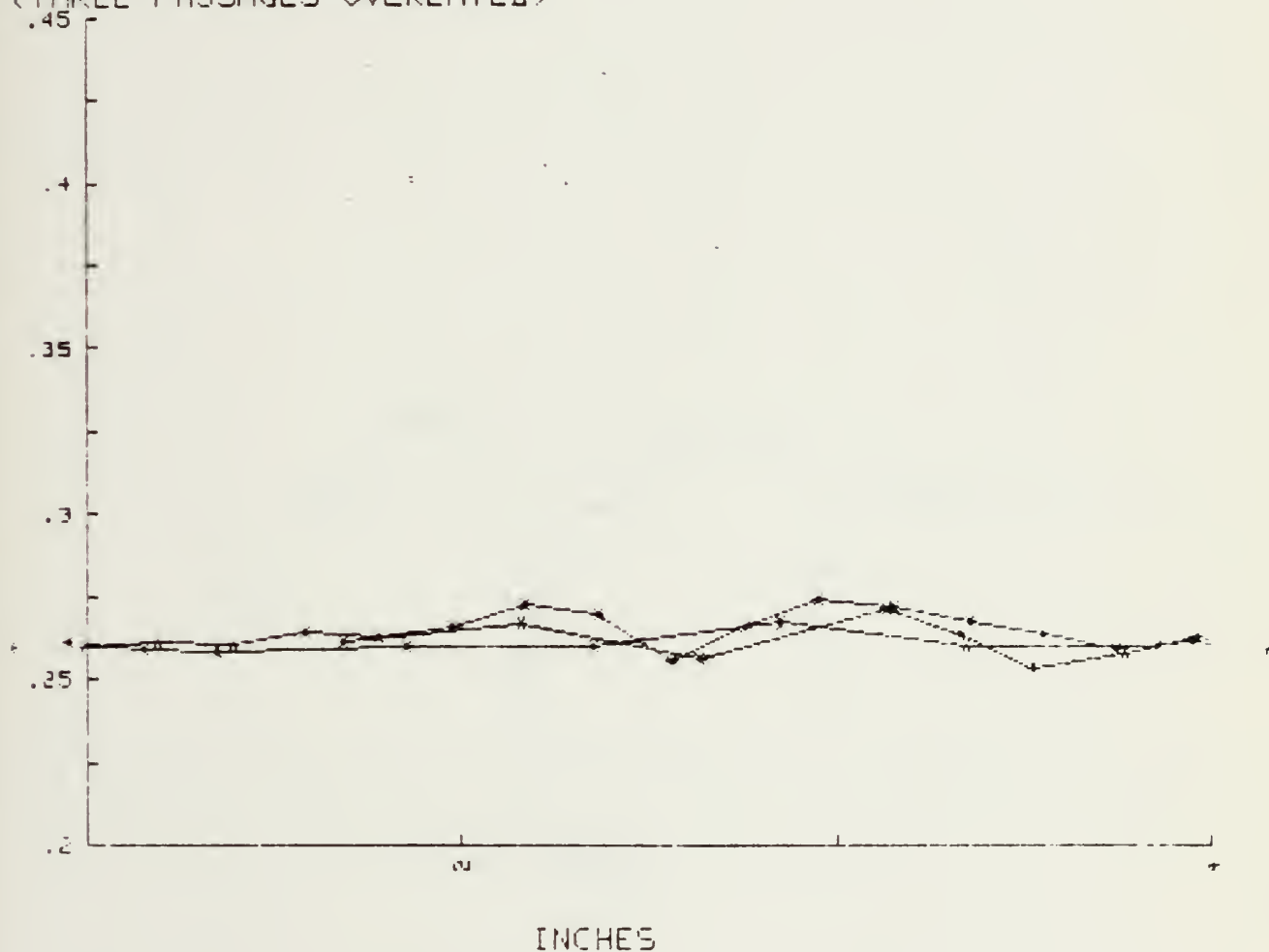


Fig. 52. Probe Survey Data at Midspan
 ($i = 5.3$, $(P_s - P_{w1}) / \bar{Q}_1$, Upper Plane)

OUTLET ANGLE
UPPER PLANE MIDSPAN (i=5.3)

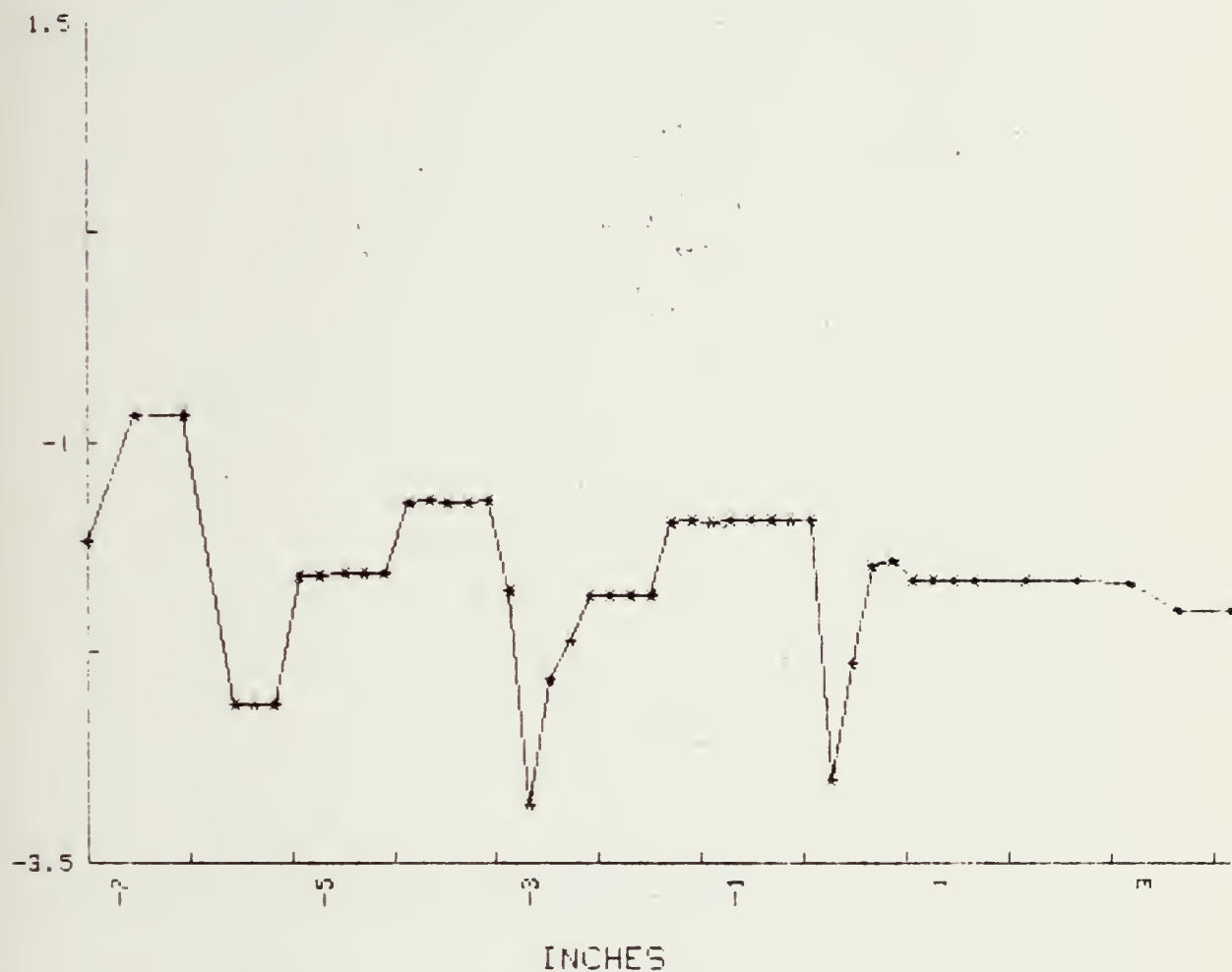


Fig. 53. Probe Survey Data at Midspan
(i = 5.3, Outlet Angle, Upper Plane)

$(P_{\text{plen}} - P_t) / Q_1 \text{ bar}$
 1 in FROM SUCTION SIDE
 CENTERMOST BLADE ($i = 5.3$)

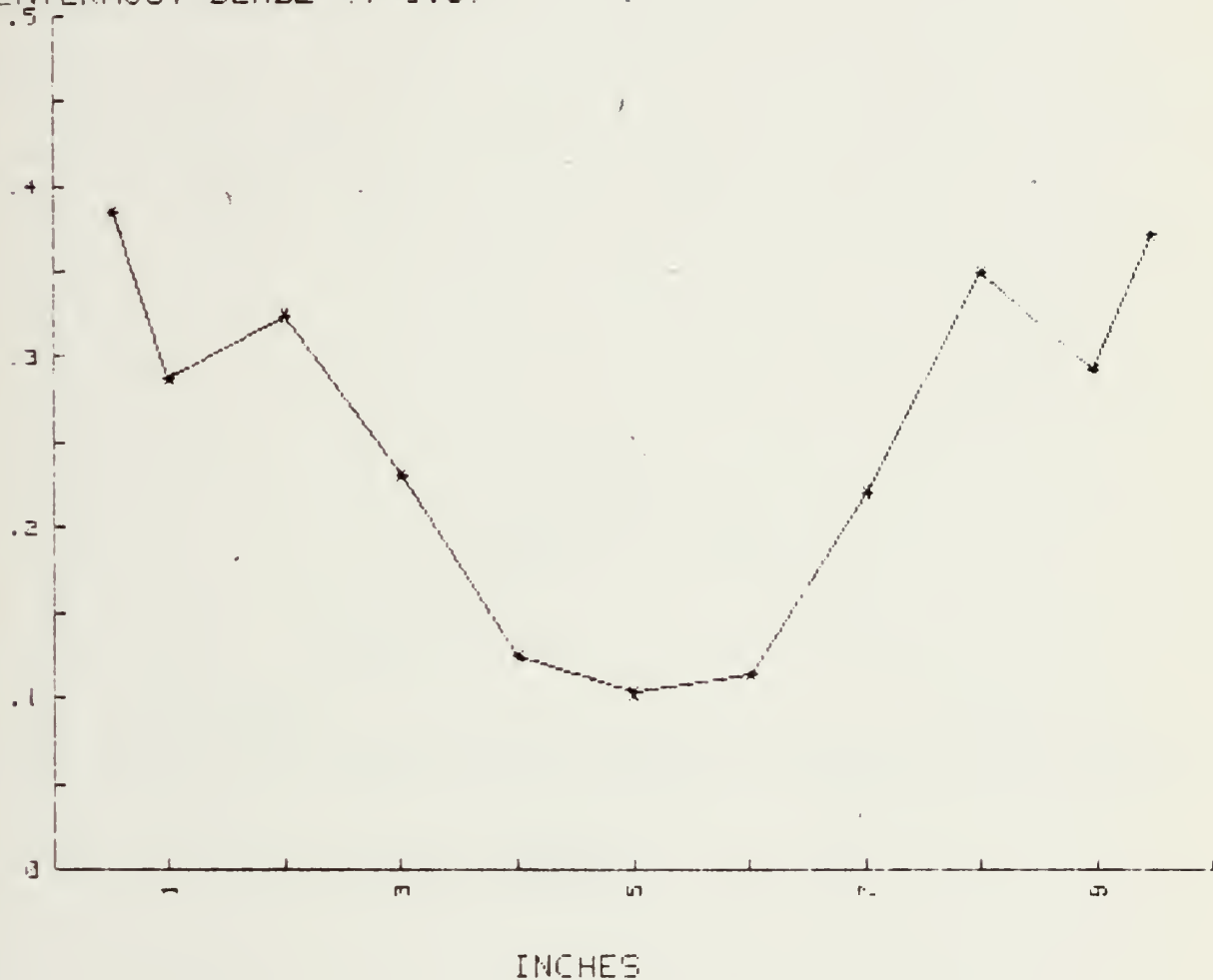


Fig. 54. Spanwise Probe Data Surveyed 1 in. from
 Suction Side of Centermost Blade
 ($i = 5.3$, $(P_{\text{PLENUM}} - P_t) / \bar{Q}_1$, Upper Plane)

X/\bar{X}

1.0 in FROM SUCTION SIDE

CENTERMOST BLADE ($i=5.3$)

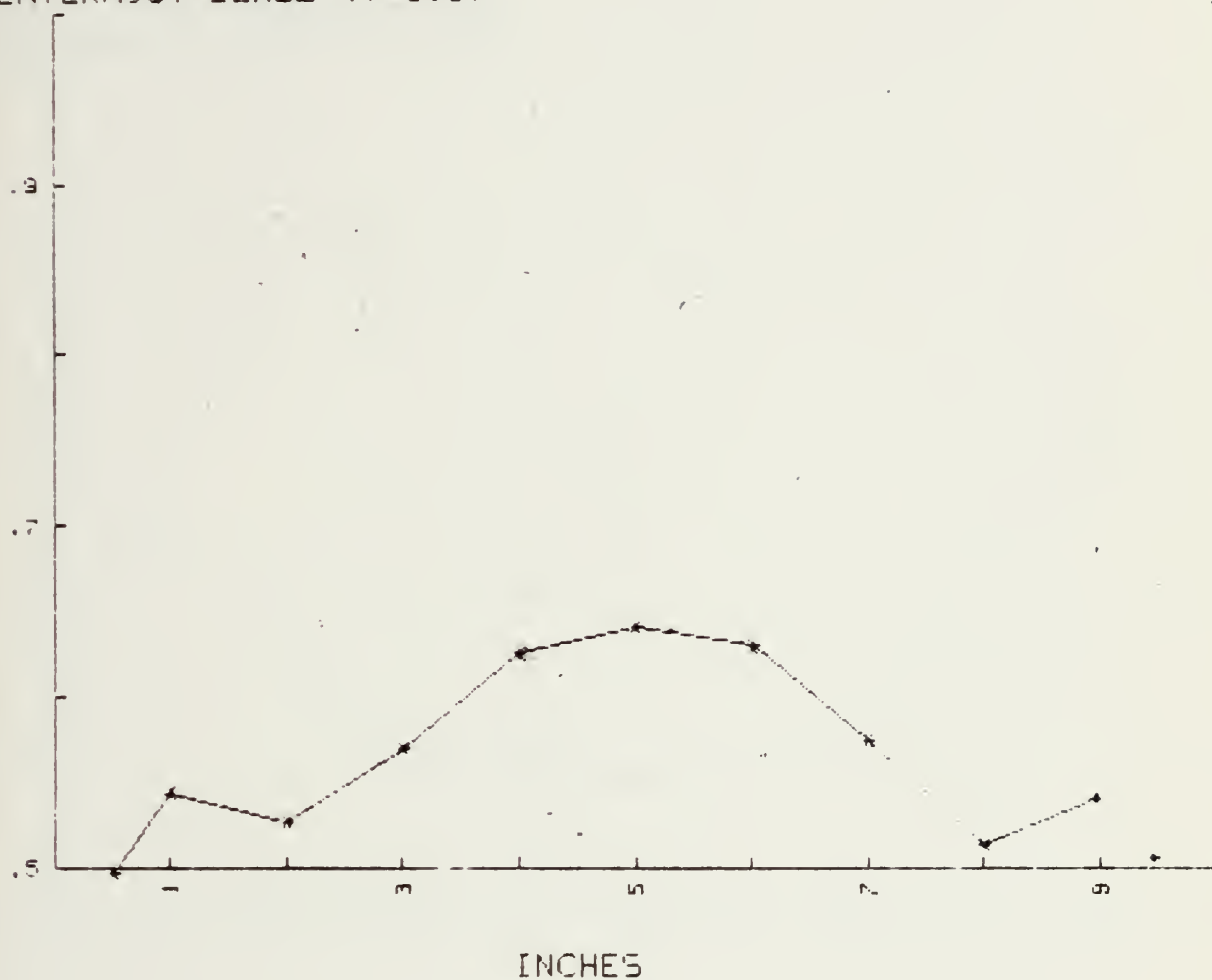


Fig. 55. Spanwise Probe Data Surveyed 1 in. from Suction Side of Centermost Blade ($i = 5.3$, X/\bar{X} , Upper Plane)

$(P_{\text{plen}} - P_t) / Q_1 \text{ bar}$
 1.0 in FROM PRESSURE SIDE
 CENTERMOST BLADE ($i=5.3$)

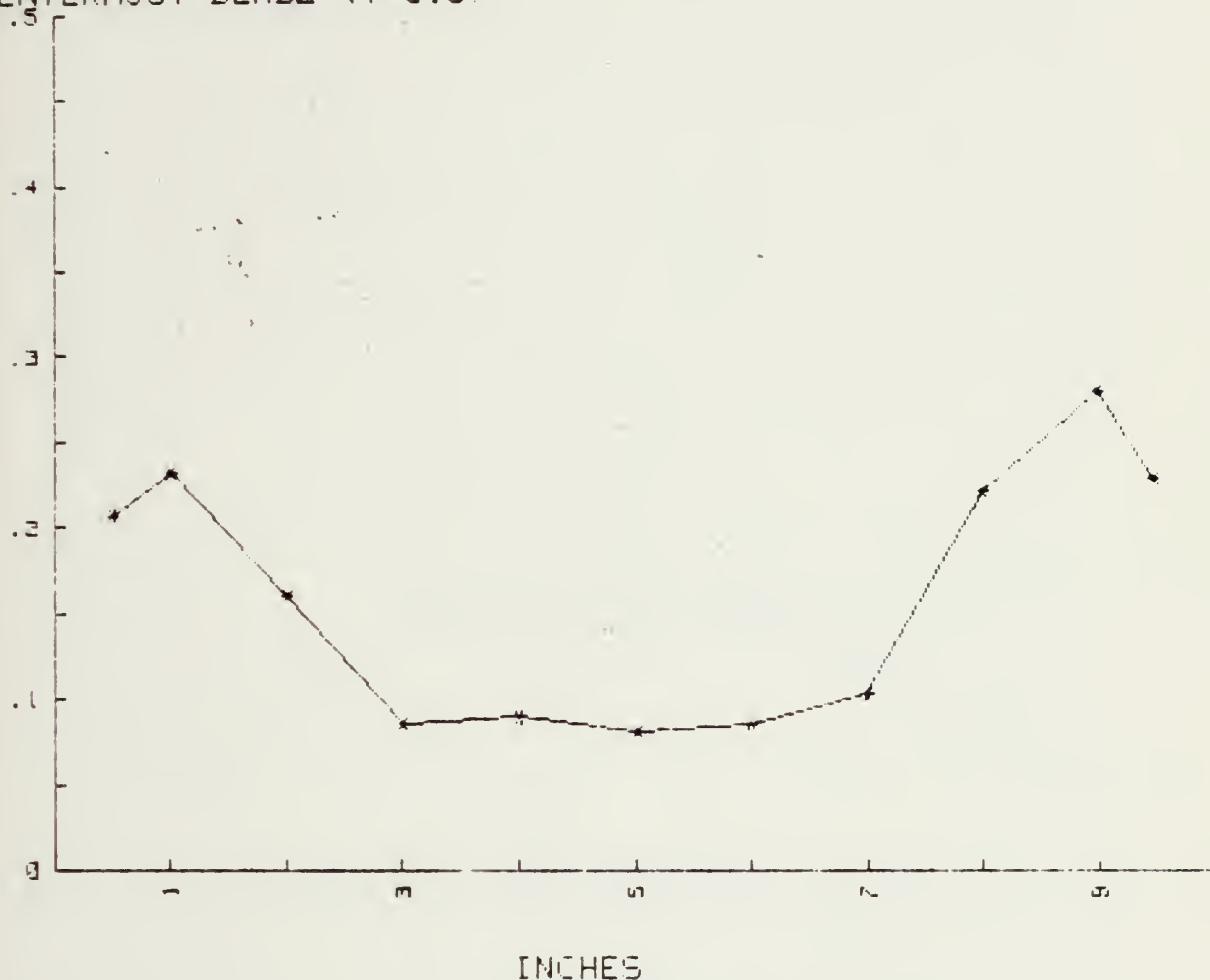


Fig. 56. Spanwise Probe Data Surveyed 1 in. from
 Pressure Side of Centermost Blade
 ($i = 5.3$, $(P_{\text{PLENUM}} - P_t) / Q_1$, Upper Plane)

X/\bar{X} bar
 1.0 in FROM PRESSURE SIDE
 CENTERMOST BLADE ($i=5.3$)

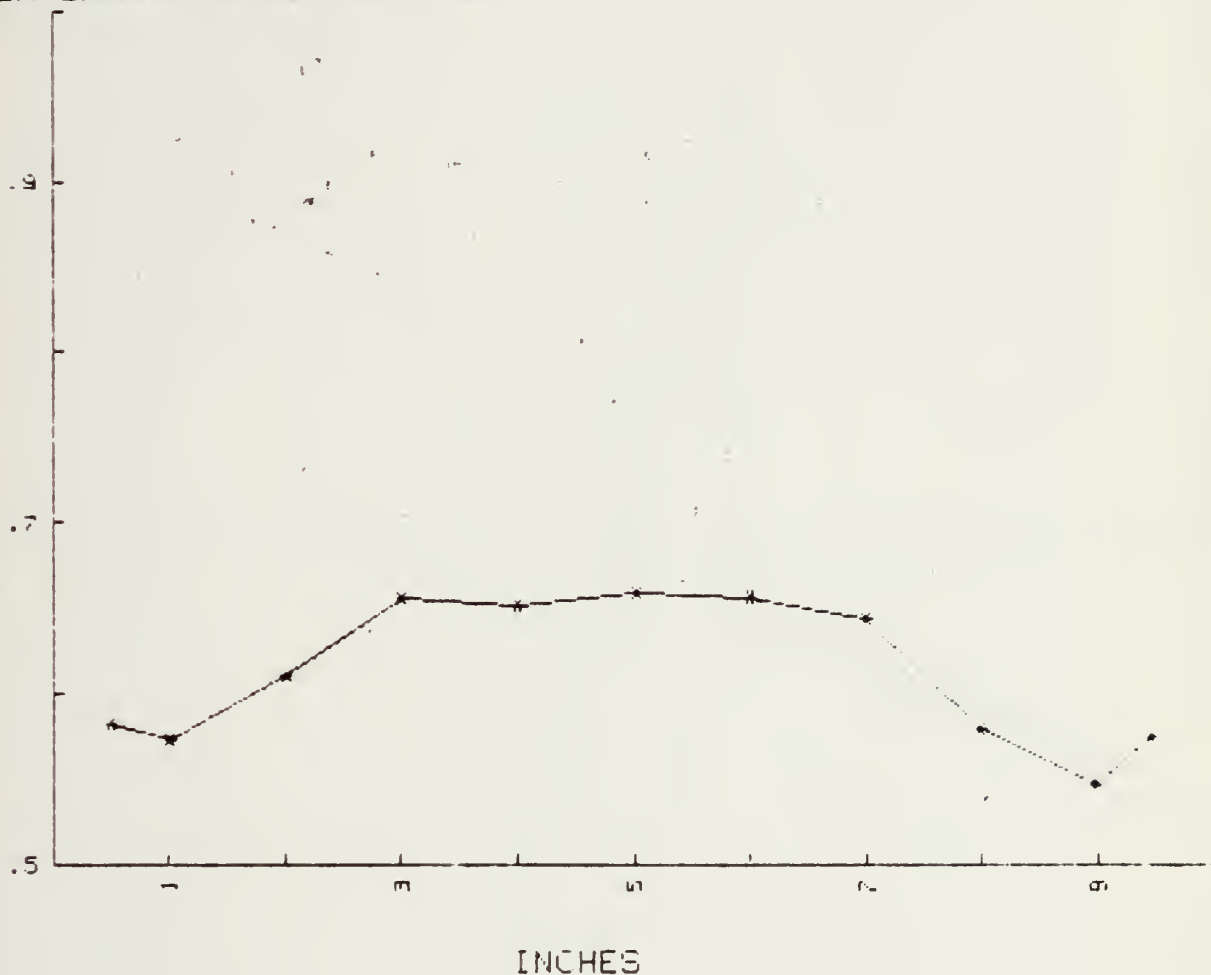


Fig. 57. Spanwise Probe Data Surveyed 1 in. from
 Pressure Side of Centermost Blade
 ($i = 5.3$, X/\bar{X} , Upper Plane)

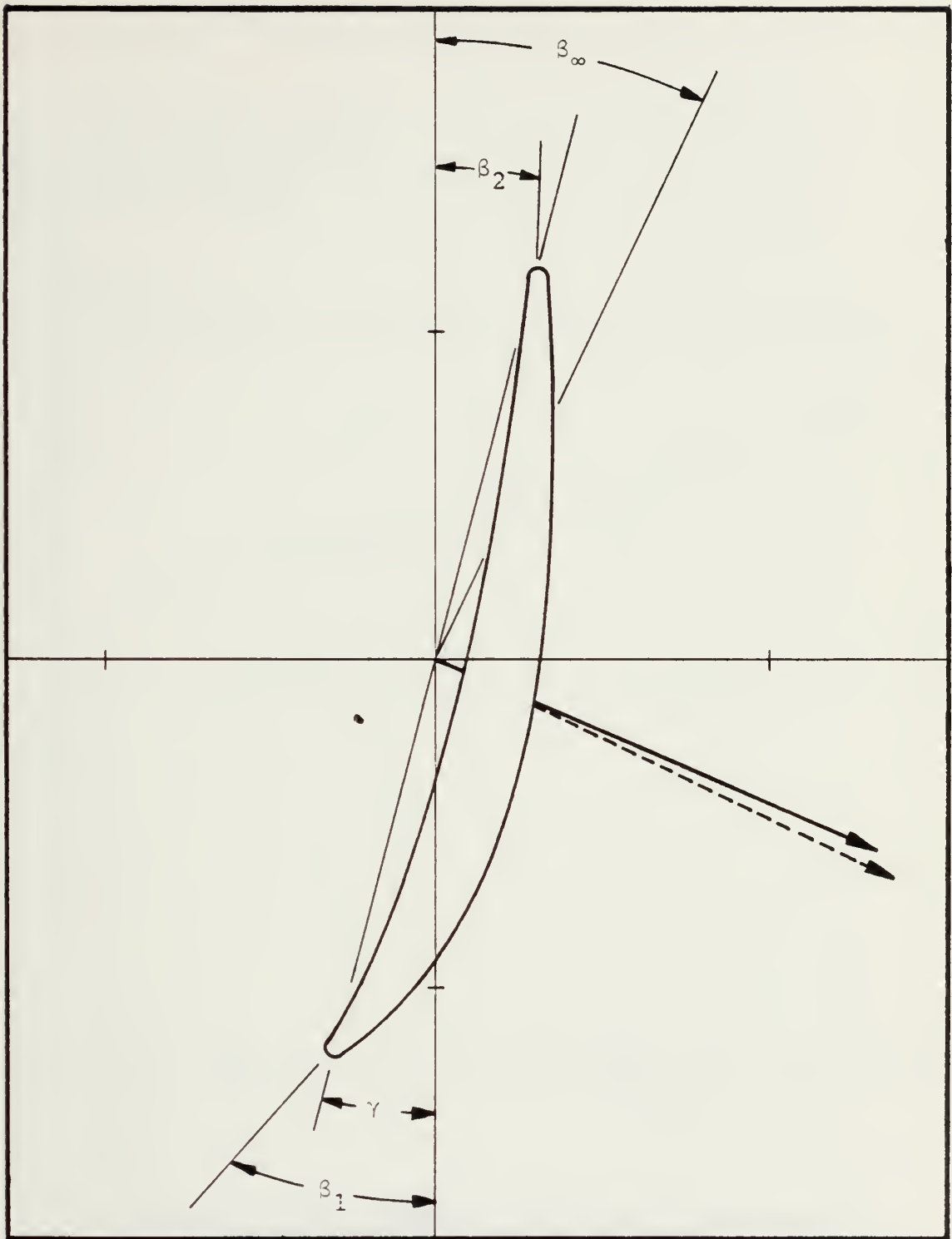


Fig. 58. Resultant Blade Force Vectors by Momentum Balance (-----) and from Surface Pressure Integration (——) $i = 5.3$

C_{p1} vs X/C ($i=5.3$)
 CENTERMOST BLADE

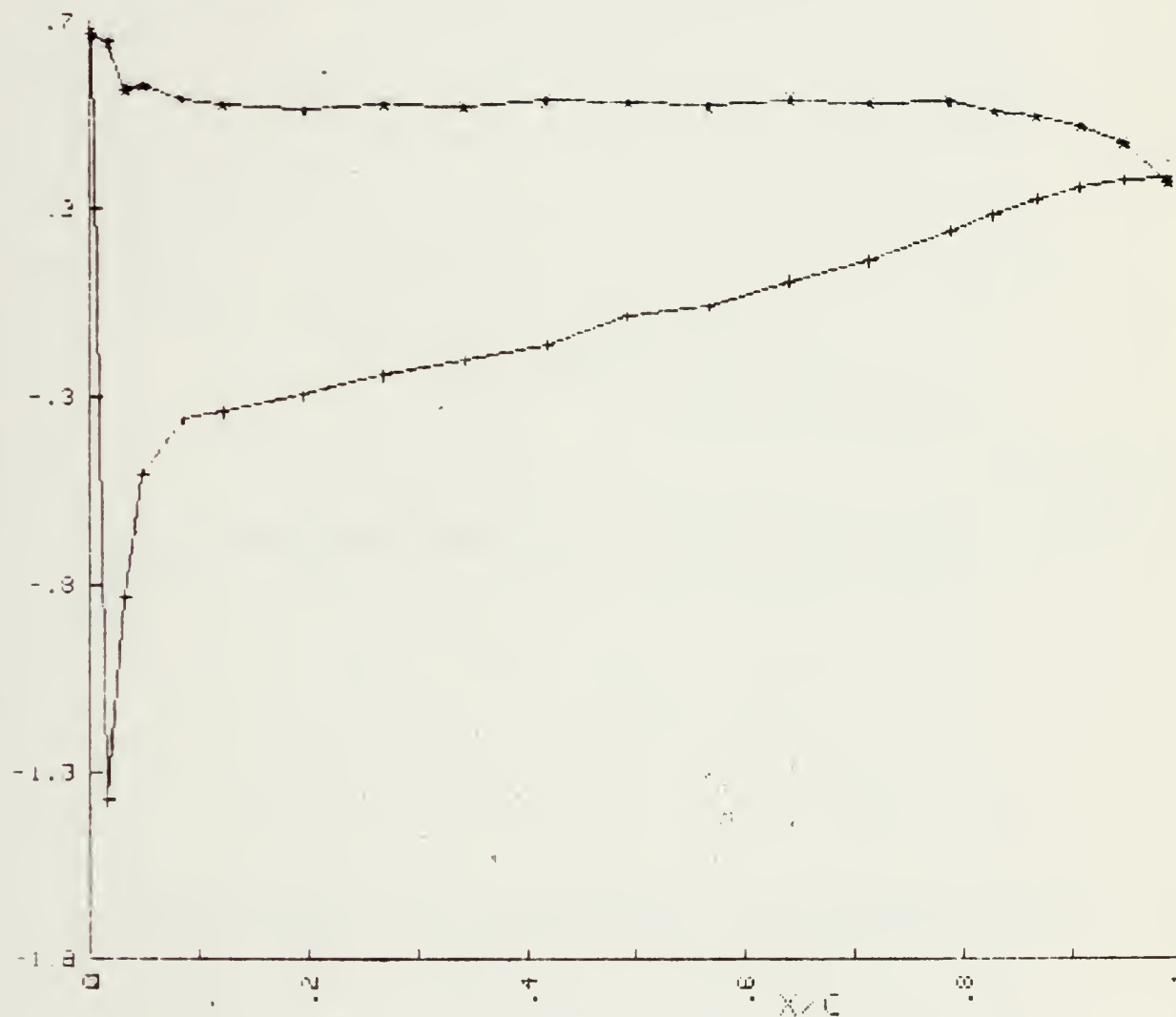


Fig. 59. Measured Blade Surface Pressure Distribution
 ($i = 5.3$, * = Pressure Side,
 + = Suction Side)

$\lambda = 1$ VS X/C ($i = 5.3$)
 CENTERMOST BLADE

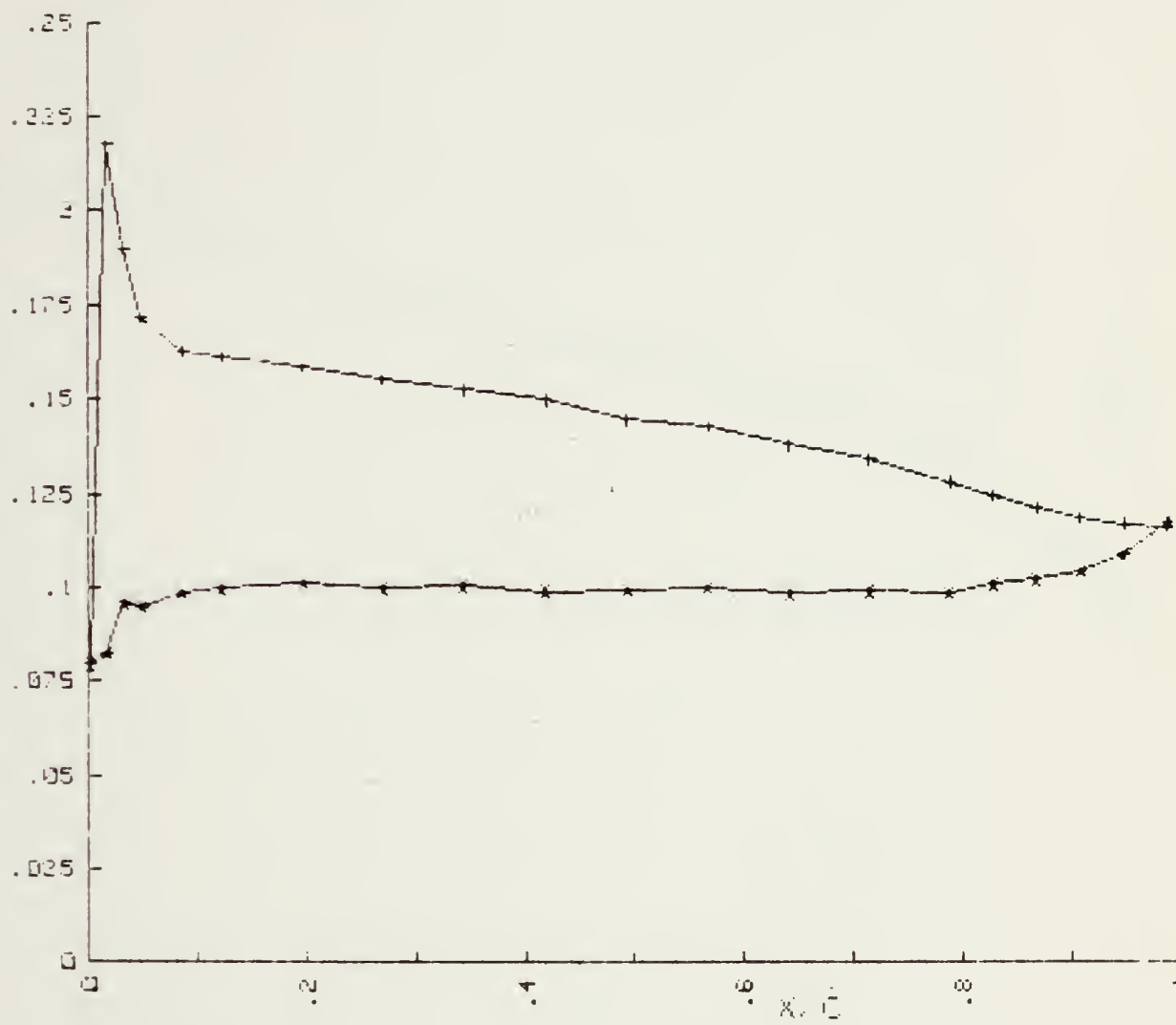


Fig. 60. Measured Blade Surface Velocity Distribution
 ($i = 5.3$, $*$ = Pressure Side,
 $+$ = Suction Side)

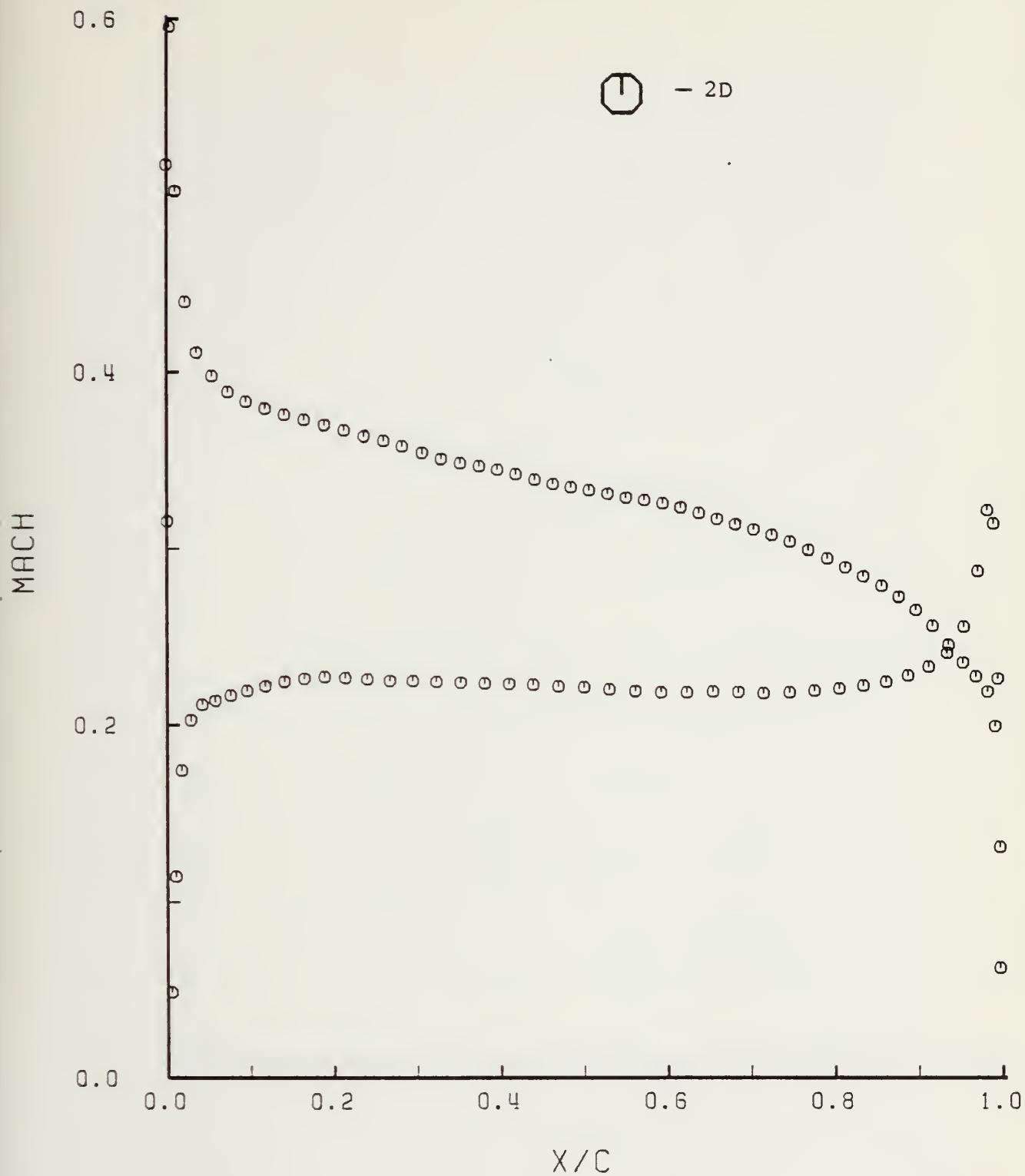


Fig. 61. 2D Code Blade Surface Mach Number Distribution
($i = 5.3$)

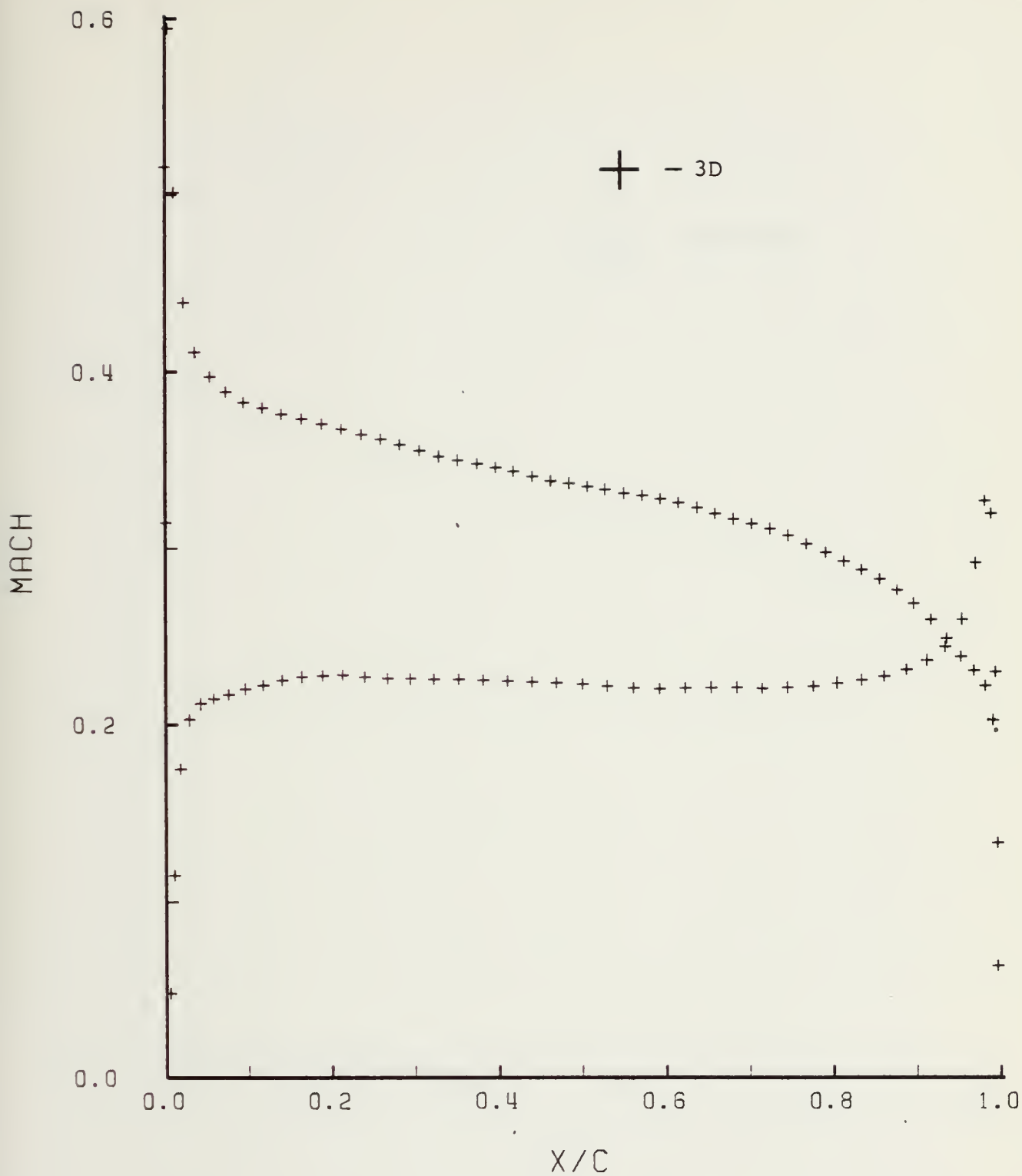


Fig. 62. 3D Code Blade Surface Mach Number Distribution
($i = 5.3$)

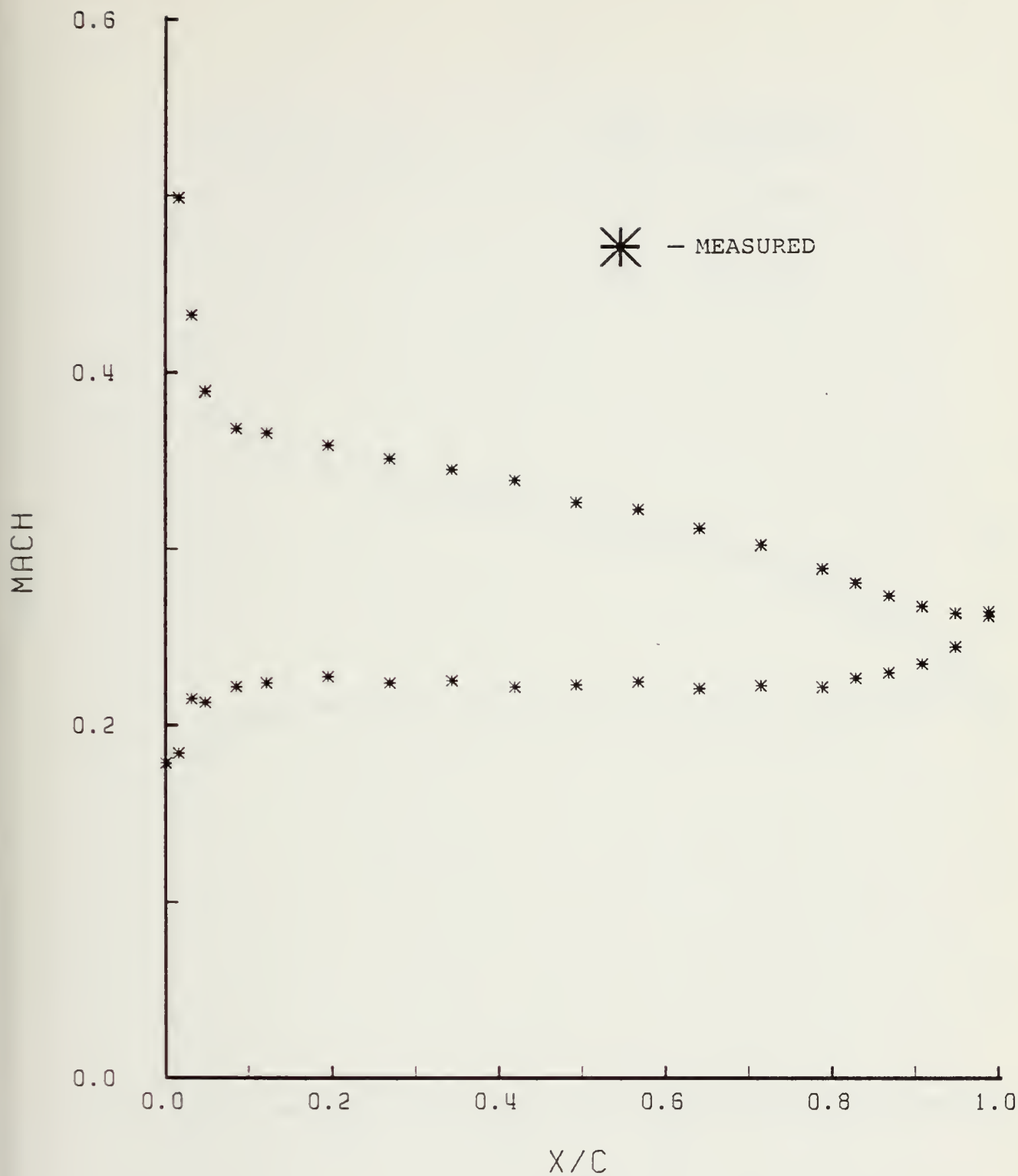


Fig. 63. Measured Blade Surface Mach Number Distribution
($i = 5.3$)

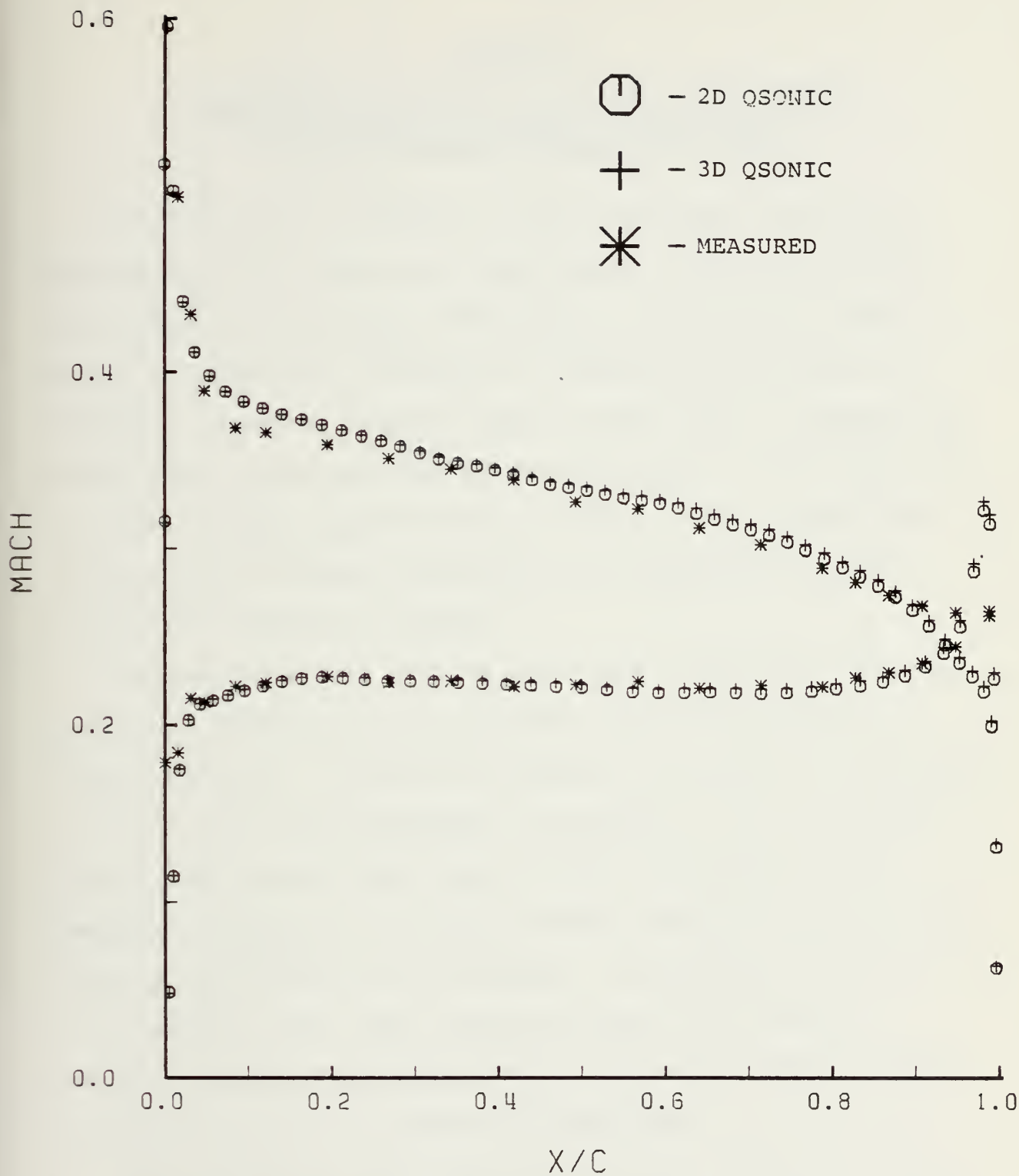


Fig. 64. Blade Surface Mach Number Distribution
($i = 5.3$)

APPENDIX A

MODIFICATION TO THE INLET GUIDE VANE SECTION OF THE SUBSONIC CASCADE WIND TUNNEL

As discussed in Section I, Cina discovered during his test program that while the inlet flow to the test section was uniform in direction and uniform in wall static pressure, it contained a variation in velocity and stagnation pressure resulting from the wakes of the IGV's. Because the inlet guide vanes were spaced at intervals of two inches and the test cascade blades spaced at three inches, departures from strictly periodic conditions were detected from one test blade passage to another.

To alleviate this problem, the inlet guide vane arrangement was modified so that the guide vanes were placed at 1 inch intervals. In order to preserve the option of reverting to a two inch IGV arrangement and because it was not possible to machine the south wall to hold additional blades, a separate structure was placed between the bell mouth contraction and the walls of the cascade. By mounting the IGV's in a separate unit which remained fixed once installed, hardware adjustments between tests associated with a change of end wall angle were greatly simplified.

The new inlet guide vane assembly was constructed using two lengths of 10 inch steel channel as shown in Fig. A.1.

One set of guide vanes was mounted on the south side of the unit at 2 inch spacings. A second set of vanes was mounted at 2 inch spacings on the north side of the unit. When the unit was assembled the guide vanes mounted from alternate sides meshed, resulting in an inlet guide vane spacing of 1 inch. The unit was provided with a single hand crank at the east end so that the vanes would be adjusted in unison. Once installed the complete structure could be left in place when the cascade north wall was removed to adjust air inlet angle. The one inch vane spacing ensured that periodicity at the test section would result for any test blade spacing which was a multiple of 1 inch. Equally important, the wakes remaining at the inlet to the test cascade would be greatly reduced as a result of closer spacing.

Figure A.1 shows the details of the inlet guide vane unit, while Fig. A.2 shows the assembly in relation to the bellmouth contraction and the side walls. Figure A.3 shows the mechanism to adjust the inlet guide vanes. Figure A.4 shows a view of the IGV assembly from the north side. A view of the Cascade Wind Tunnel partially assembled (north side wall off) is shown in Fig. A.5.

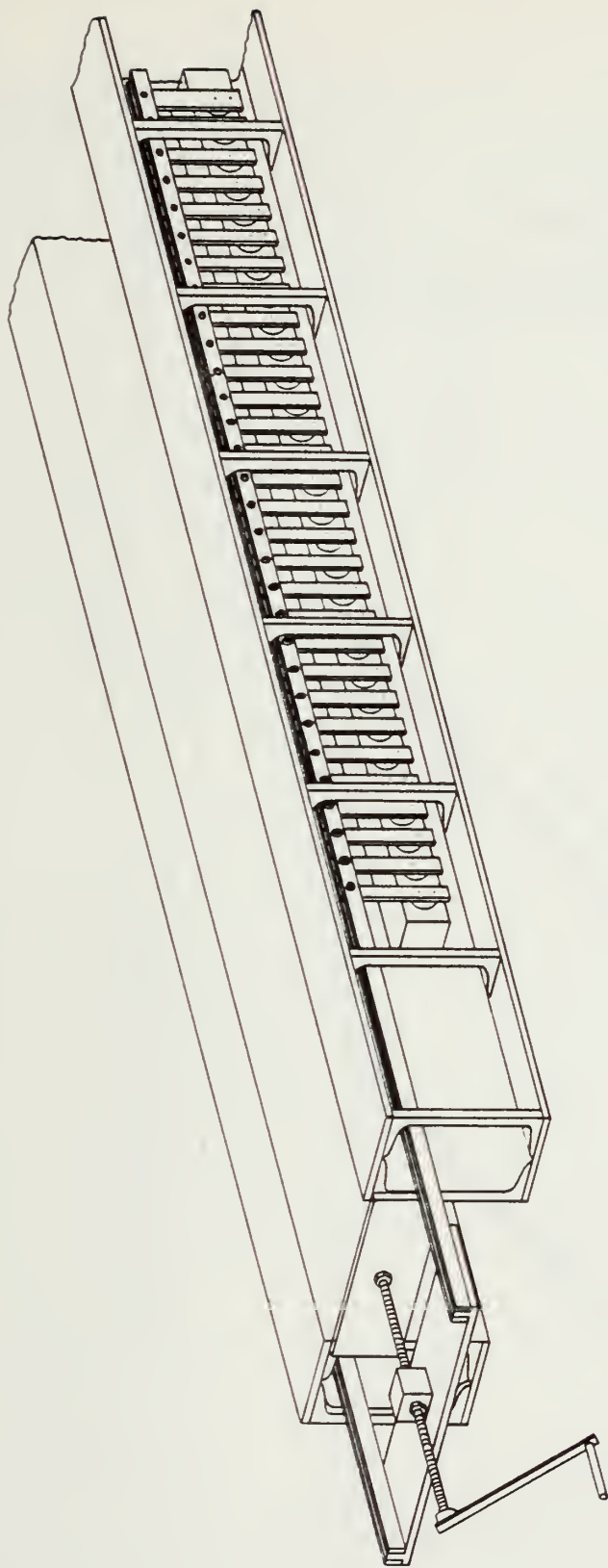


Fig. A.1. Inlet Guide Vane Assembly

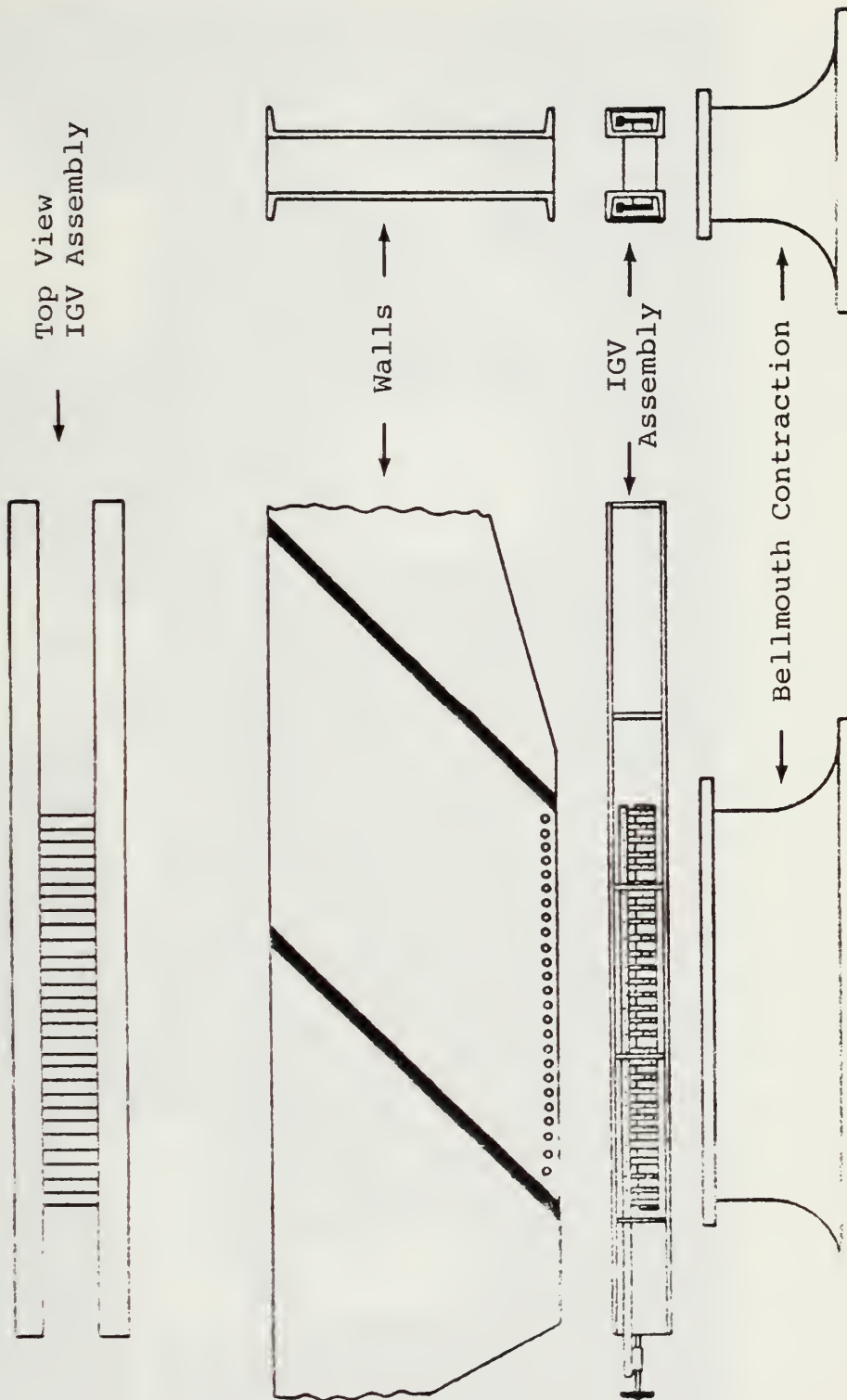


Fig. A.2. Cascade Wind Tunnel Sub-Assemblies

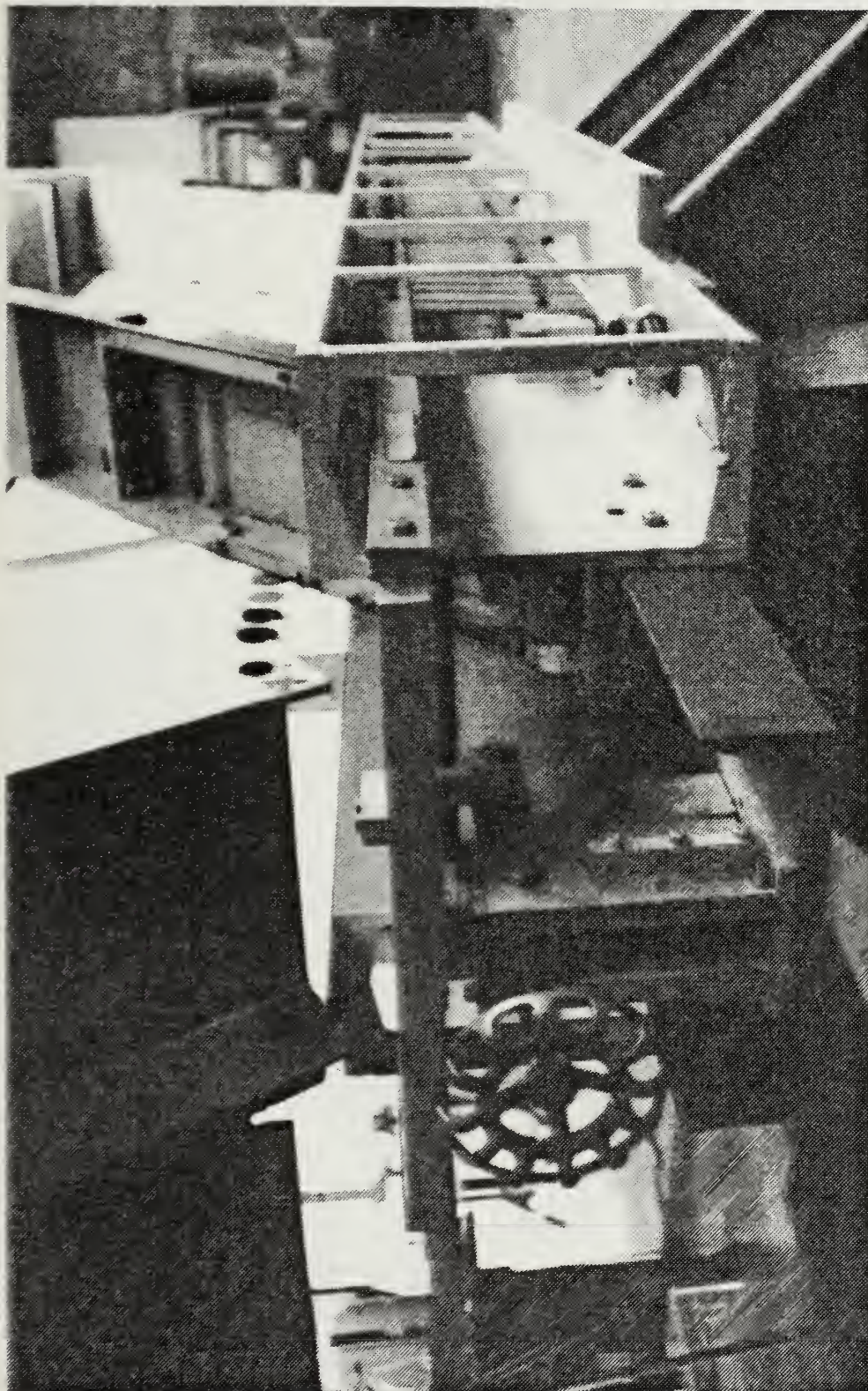


Fig. A.3. View of the IGV Adjustment Mechanism

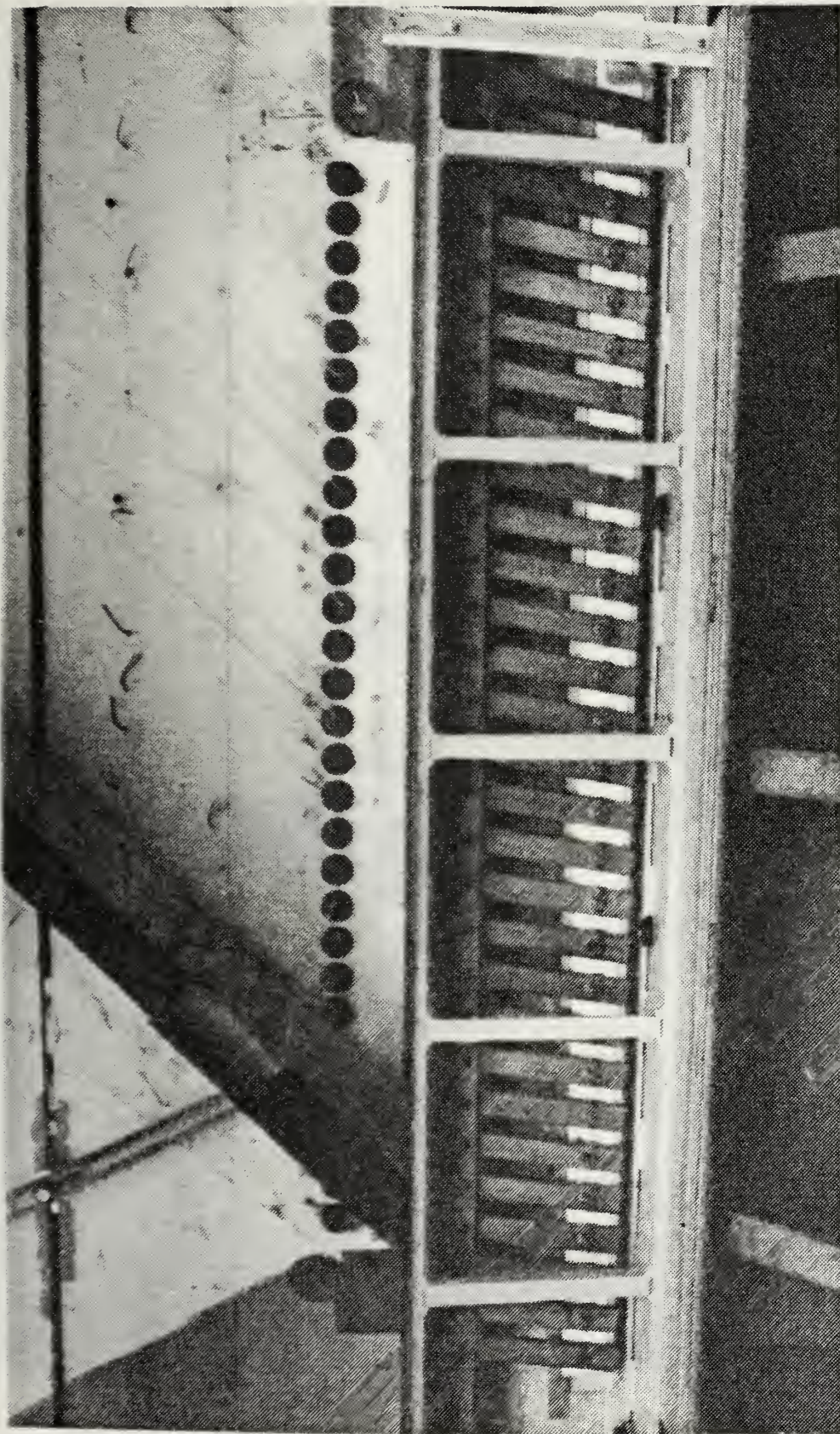


Fig. A.4. Side View of the IGV Assembly

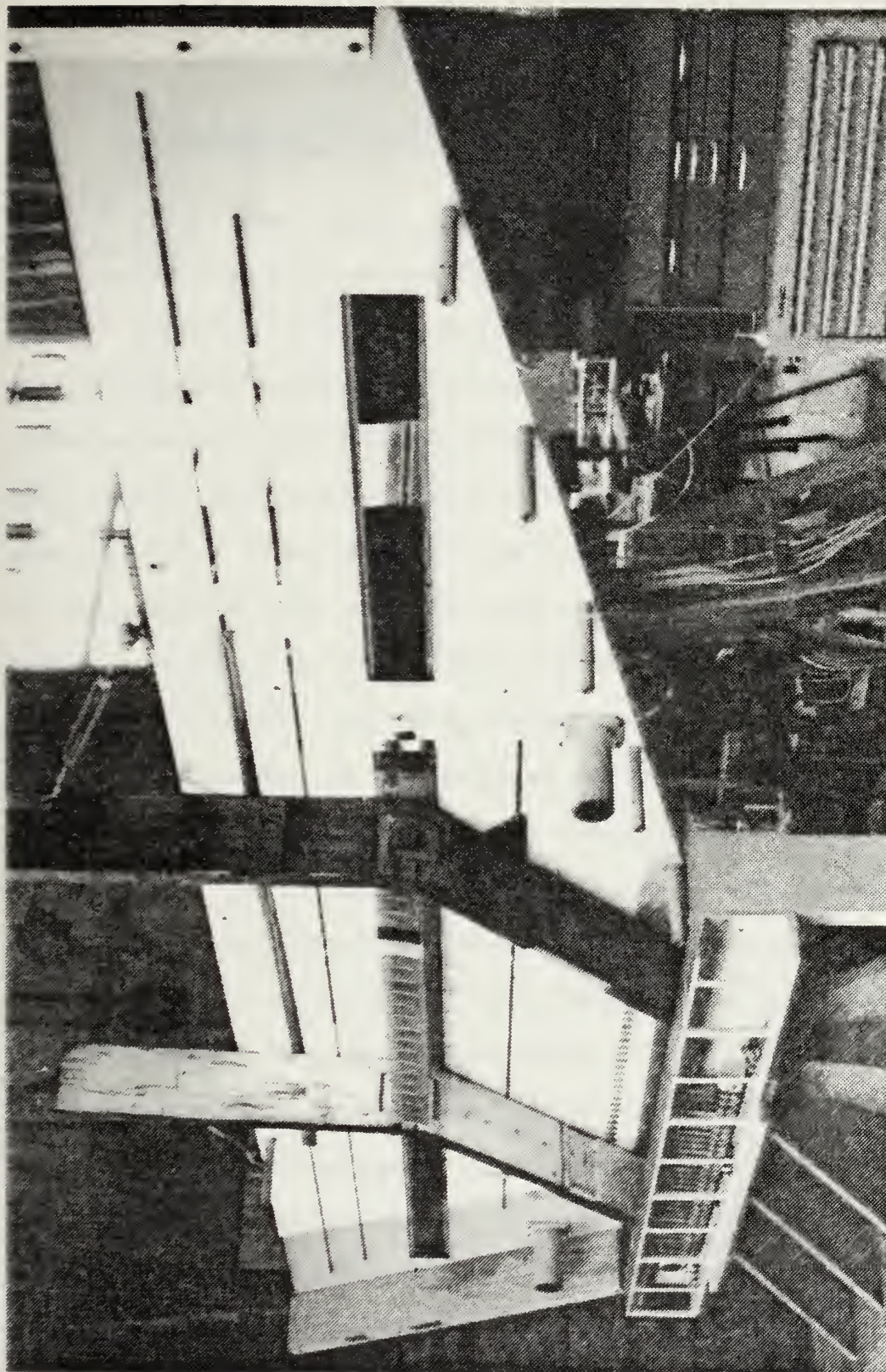


Fig. A.5. View of the Subsonic Cascade Wind Tunnel (North Wall Removed)

APPENDIX B

SELECTION AND INSTALLATION OF SCREEN MATERIAL

Pankhurst and Holder [Ref. 17] show that the turbulence of an airstream can be increased by placing a coarse mesh across the flow upstream of the test section. One of the most effective methods which is used for the reduction of turbulence and non-uniformities also consists of placing a mesh screen across the tunnel. Screens used for this purpose are of a finer mesh and are placed at a greater distance from the test section, and normally in the low-speed region upstream of the contraction in a conventional subsonic wind tunnel. By using such a screen the large scale eddies are removed at the expense of the introduction of a greater number of smaller eddies which decay rapidly.

McEligot [Ref. 16] investigated the possibilities of reducing non-uniformities in the test section of the subsonic cascade wind tunnel. His investigation and recommendations were completed while the inlet guide vanes were still at 2 inch spacings. McEligot concluded that some modification was necessary to achieve one percent uniformity for the mean velocity at the test cascade inlet plane and suggested several options. One of the options suggested was placing the turning vanes (inlet guide vanes) at a closer pitch. As explained in Appendix A, the pitch of the inlet

guide vanes was reduced from 2 inches to 1 inch. This new inlet guide vane arrangement did result in a one percent uniformity for the mean velocity at the test cascade inlet plane.

The other approach suggested was the use of wire gauze screens. McEligot showed that the velocity distribution appeared to be largely dependent on a pressure drop coefficient K , defined by the equation

$$K = \frac{p_1 - p_2}{\frac{1}{2} \rho V^2}$$

where p_1 and p_2 are the pressures upstream and downstream of the screen respectively. This pressure drop coefficient depends mainly on the blockage coefficient β defined by the equation

$$\beta = (1 - d/\ell)^2$$

where d is the diameter of wire used in the screen and ℓ is the distance between the wires. This blockage coefficient is commonly referred to as "percent open area" in catalogues of industrial wire cloth and woven wire screens.

For the velocities and flow angles used in the cascade wind tunnel, McEligot recommended using a wire gauze screen with a resistance coefficient, K , of 2.2 and a blockage coefficient, β , of 0.47. However, since the new inlet guide vane arrangement resulted in a one percent uniformity for

the mean velocity and the pressure drop across a screen with a blockage coefficient of 0.47 was expected to be higher than could be tolerated for the desired test conditions, screens with a slightly higher blockage coefficient (higher percent of open area) were selected to be tested.

The screens tested were of the following configurations:

MESH	WIRE DIAMETER (inches)	BLOCKAGE COEFFICIENT
4	.0410	.6989
5	.0410	.6320
16	.0105	.6922

Until the effectiveness of wire gauze screen in reducing non-uniformities in this facility was proven, a temporary installation of the screen material was considered adequate for testing purposes. The test screen was installed in the cascade wind tunnel by placing it between the inlet guide vane assembly and the north and south end walls. This arrangement placed the screen 7.25 inches downstream of the inlet guide vanes and 19.3 inches upstream of the lower test plane. Figure B.1 shows the installation of the wire gauze screen.

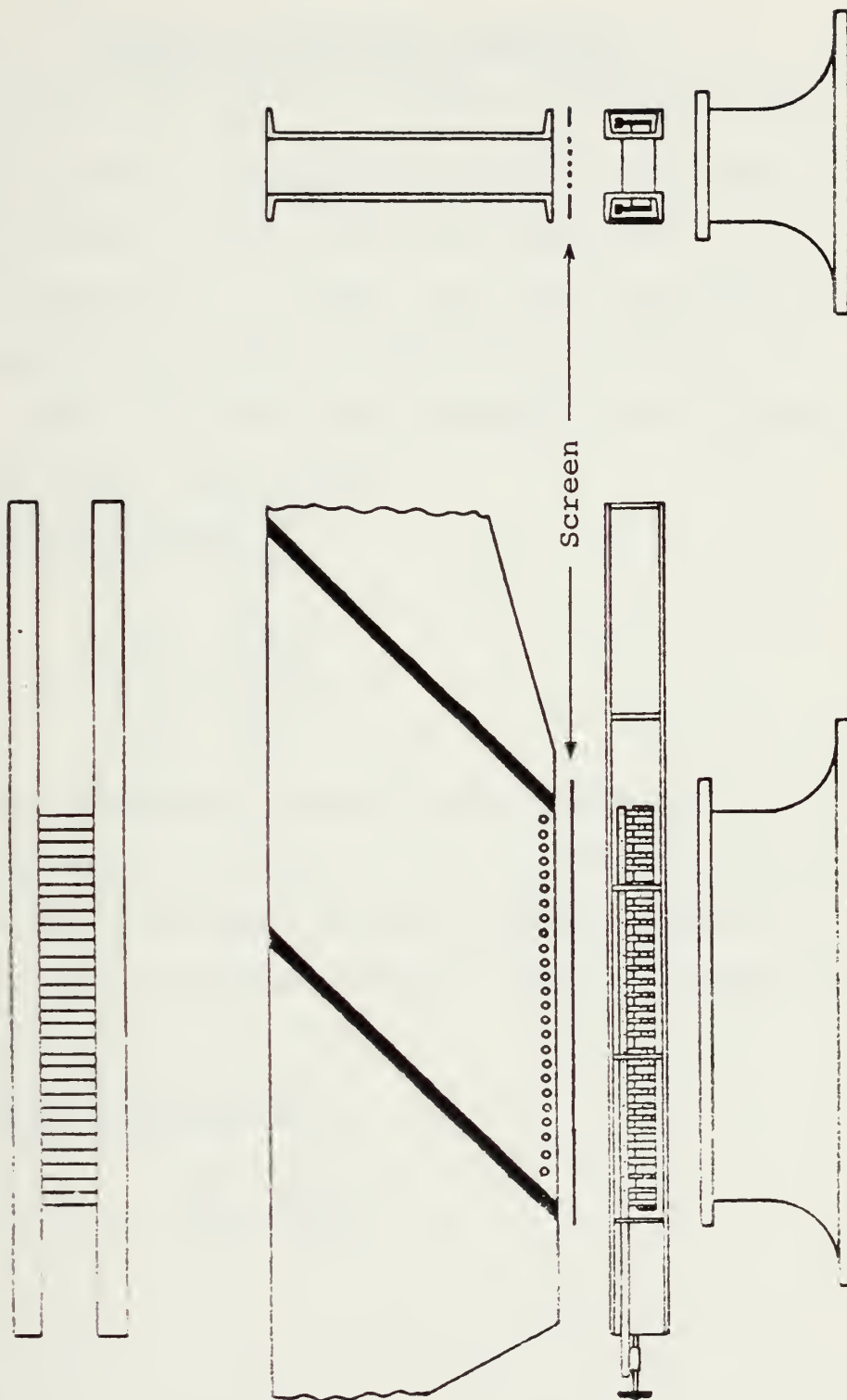


Fig. B.1. Screen Installation

APPENDIX C

CASCADE PERFORMANCE PARAMETERS

(by F. S. Cina; reproduced with minor changes from Ref. 7)

The performance of a cascade is specified in terms of the deviation angle (δ) and the loss coefficient ($\bar{\omega}$) for given inlet conditions. In Ref. 1 the loss coefficient is shown to correlate in terms of the Diffusion Factor (D). In the present work, the performance parameters were calculated using the following expressions:

1. Loss Coefficient ($\bar{\omega}$)

$$\bar{\omega} = \frac{\bar{C}_{p_{t_1}} - \bar{C}_{p_{t_2}}}{\bar{C}_{p_{t_1}} - \bar{C}_{p_1}} \quad (1)$$

where the mass averaged pressure coefficients in Eq. (1) are defined in Appendix C of Ref. 7. It is shown in Appendix C of Ref. 7 that the effect of time dependent supply conditions are removed and the effect of AVDR is included in the use of Eq. (1).

2. Diffusion Factor (D)

$$D = 1 - \frac{W_2}{W_1} + \frac{\Delta W_u}{2\sigma W_1} \quad (2)$$

3. Pressure Rise

$$C_{p\text{static}} = \frac{\bar{P}_2 - \bar{P}_1}{\bar{Q}_1} \quad (3)$$

4. Blade Surface Pressure Coefficients

$$C_{p1} = \frac{P_s - \bar{P}_1}{\bar{Q}_1} \quad (4)$$

$$C_{p2} = \frac{P_s - \bar{P}_2}{\bar{Q}_2} \quad (5)$$

5. Dimensionless Velocity

$$X = \frac{V}{V_t} = \frac{V}{\sqrt{2C_p T_t}}$$

where V is the local velocity, $V_t = \sqrt{2C_p T_t}$ is the "limiting" velocity and T_t is the stagnation temperature.

APPENDIX D

INSTRUCTIONS FOR PREPARING INPUT AND OPERATING QSONIC USING A RECTILINEAR CASCADE CONFIGURATION

D.1 BACKGROUND INFORMATION

QSONIC has the capability to calculate an axial, mixed or radial flow field and the test cascade can be rotating or stationary. The geometry of the streamsurface can be a 2D planar cascade or axisymmetric with varying channel thickness and radial position. The capabilities of QSONIC, beyond those of previous cascade analysis methods (such as described in Ref. 8) include the ability to calculate through weak shocks with a peak relative Mach number less than 1.4, and completely around both leading and trailing edge regions of a blade profile. The blade shapes in the leading and trailing edge regions are not restricted to circular arcs. Detailed instructions for preparing input for a configuration other than an axial flow, stationary and rectilinear cascade may be found in Ref. 9. What follows are instructions for preparing the input applicable to the Rectilinear Cascade facility and running QSONIC on the Naval Postgraduate School's computer and associated operating system. It is assumed that the reader has a working knowledge of the NPS computer operating system and is familiar with Refs. 13 and 14.

QSONIC operates in two parts. The first part generates a body (blade) centered mesh (geometry generation). The second part actually solves for the flow conditions at points in the mesh (flow solution). The data necessary to generate a mesh consists of a two-dimensional description of the blade shape. This is in the form of pairs of (X,Y) points on the surface, together with parameters that describe the cascade layout, such as chord and stagger angle. Additionally, parameters describing the density of mesh lines complete the input for the geometry generation.

For flow field calculations, the upstream flow conditions, convergence criteria and a schedule of meshes to be used should be input. If quasi-three dimensional effects are to be considered, a data file containing a description of the streamchannel's radial thickness and position as a function of distance along the stream surface is needed. For the case described herein, this was input by assuming a linear reduction in streamchannel thickness using a factor of $1/AVDR$. This gave excellent results. (The output of another NASA code, Meridl [Ref. 15], can be used to input data to QSONIC for compressor flow field calculations. This program has recently become operational on the NPS computer.)

The output of QSONIC consists of listings which contain an echo print of the input data, generated mesh coordinates on the blade surface, progress reports on the flow convergence and a list of the final velocities, pressures

and densities on the blade surface for each grid that was included in the schedule of solution meshes.

D.2 INPUT DESCRIPTION

The input for QSONIC falls into the following categories:

Logical and case control parameters (NAMELIST PARAMS)

Bulk data input:

For geometry generation runs (NAMELIST INSTUFF)

For flow solution runs:

Mesh point storage files

Streamchannel data file (for quasi-3D)

The following is a description of the logical and case control parameters for the Rectilinear Cascade. Except for TITLE, the format for all these variables is in namelist form. The namelist is PARAMS. This information is taken from Ref. 9 and adapted to the Cascade Wind Tunnel. Namelist variables can be entered in any order. If a default value is listed, it is not necessary to enter that particular variable. If the default value is listed as none, then a value for that parameter must be input.

The following parameters apply to both the mesh generation and the flow solution runs, but the values need not be the same.

<u>Variable Name</u>	<u>Type</u>	<u>Default Value</u>	<u>Description</u>
TITLE	Alphameric	None	This is a one-line name for the case being run. TITLE must appear on the first line of the data file that will be referred to as NAMELIST DATA.
NOFLOW	Logical	False	NOFLOW = .TRUE. if a run is to stop after generating a mesh, such as the mesh generation run. NOFLOW = .FALSE. for the flow solution run.
MS	Integer	None	MS is an array (max. dimension 10) of values (max. value = 25) for the number of grid lines in the mesh that will enclose the blade. 25 is a satisfactory number for blades of solidity near unity. As solidity increases the maximum value in MS should decrease.
NOZES	Integer	None	NOZES is an array (max. dimension 10) of values (max. value = 49) for the number of grid lines in the mesh radiating from the blade on one surface. If a value of NOZES is greater than zero, a mesh with that many lines will be developed and stored in the file MESHGEN DATA. If the value is negative, QSONIC assumes that this MESH already exists in the file MESHGEN DATA and will be read in. For Geometry Generation runs NOZES > 0 and for flow solution runs NOZES < 0. For electrostatic analog grid generator, NOZES must be odd.

BETA1	Real	None	<p>BETA1 is the flow angle at the upstream boundary, in degrees. BETA1 is measured from the aerodynamic chordline to the direction of flow; clockwise is negative. This can be obtained from the output of the cascade tunnel data reduction program 'CX4431'. It is listed as "inlet air angle." Because of a difference in definition, it is necessary to use the usual inlet air angle minus the stagger angle for BETA1.</p>
-------	------	------	--

Example: The output of CX4431 lists an inlet air angle of 42.429°. The cascade is configured with a stagger angle of 14.27°.

$$\begin{array}{r}
 42.429^\circ \\
 - 14.27 \\
 \hline
 28.16 = \text{BETA1}
 \end{array}$$

BETA2	Real	None	<p>BETA2 is the flow angle at the downstream boundary in degrees. It is measured from the aerodynamic chordline to direction of flow. Clockwise is negative. This can be obtained from the output of the cascade tunnel data reduction program 'CX4431'. It is listed as outlet air angle. Because of a difference in definition, it is necessary to use the outlet air angle minus the stagger angle for BETA2.</p>
-------	------	------	--

GAMMA	Real	1.4	<p>This is the ratio of specific heats. For the Subsonic Cascade Wind Tunnel the default value works well.</p>
-------	------	-----	--

TOLS	Real	None	<p>This is an array of dimension 10 of tolerances corresponding to MS and NOZES. Each grid solution will proceed until its TOLS value is satisfied.</p>
------	------	------	---

MESH1	Integer	1	This is an index in the arrays MS and NOZES of the first mesh to be generated and/or used for the flow solution. For geometry generation runs, MESH1 selects one of the grids to be stored, provided NOZES(MESH1) > 0.
MESHN	Integer	None	<p>This is an index in the arrays MS and NOZES of last grid to be calculated for geometry generation runs or used for the flow solution. For geometry generation runs, MESHN = MESH1. Subsequent flow solution runs then solve the case for all grids listed in MS and NOZES between index MESH1 and MESHN. For flow solution MESH1 normally points to the coarsest mesh.</p> <p>To insure equal spacing of grid lines over the entire mesh,</p> $\frac{\text{NOZES}(I) - 1}{K(I - \text{MESH1})} = \text{Integer},$ <p>where $\text{MESH1} \leq I \leq \text{MESHN}$ and $K = 2, 3, 4, \dots$ ($K = 2$ if grid lines are doubled between successive grids).</p>
LAMDA0	Real	None	Stagger angle of the blade row in degrees measured from the throughflow direction to the blade chord line. (Clockwise is negative.)
CHORD	Real	None	True chord of the blade, in the same units as the blade coordinates.
S	Real	None	Blade spacing in the same units as the blade coordinates.

The following parameters are required only for the geometry generation run. QSONIC gives the user a choice of two grid (mesh) generators. The Electrostatic Analog grid generator is applicable to any blade shape and any value of stagger or turning. The interpolation scheme grid generator works for most blades except those with sharp leading edges where the edge radius is less than .5% of chord. The interpolation scheme allows the user to concentrate grid lines in areas of high interest around the blade. With the Electrostatic Analog grid generator no concentration of grid lines is available. For the cascade configuration used in this study, the interpolation scheme provided gross errors in the flow solutions, so the Electrostatic Analog grid generator was used with good results.

<u>Name</u>	<u>Type</u>	<u>Default</u>	<u>Description</u>
NED	Integer	None	Total number of body definition coordinates that are input. These are the X,Y points that describe the profile of the blade, with the first point repeated as the last point.
KN	Integer	None	KN is used to indicate which grid generator is to be used. KN = 0 will call the electrostatic analog grid generator. For interpolation scheme, KN = number of body points on upper surface from the minimum to maximum X points, inclusive.

NED and KN are required for either grid generator. If the electrostatic analog grid generator is used, no other

parameters are used. If this grid generator is used the value from NOZES that is used must be odd.

The following parameters are used only if the Interpolation Scheme is used to generate the mesh.

<u>Name</u>	<u>Type</u>	<u>Default</u>	<u>Description</u>
RLE	Real	None	RLE is the leading edge radius of the blade, with units the same as the coordinates defining the blade profile.
RTE	Real	None	RTE is the trailing edge radius of blade.
THETL	Real	0	THETL is the camber angle of the leading edge in degrees. It is measured from the aerodynamic chord to the line tangent to the mean camber line at the leading edge; clockwise is positive.
THETT	Real	0	THETT is the camber angle at the trailing edge in degrees. It is measured from the chord line to the mean camber line at the trailing edge. Clockwise is positive.
CAMPER	Integer	6	For blades whose chordline lies outside the blade profile, such as the DCA blading discussed in this report, extra grid lines surrounding the blade are needed to interpolate the blade position. The truncated value of $MS()/CAMPER$ is added to $MS()$. The maximum allowed value of $MS() + MS()/CAMPER$ is 30 grid lines. These are the grid lines that enclose the blade profile.
STABAC	Real	0.999	STABAC is used only for test cases where no blade shape is to be input. Default value is usually adequate.

CHOP	Real	0.99	If leading edge or trailing edge radius is less than 2% of chord consult Ref. 9 for clarification. Normally, $0.9 < \text{CHOP} < 1.0$.
SMOOTH	Logical	False	For automatic addition of more blade definition points in the region of the leading and trailing edges set $\text{SMOOTH} = \text{.TRUE.}$. This should be done for all blades except cusps and wedges.
LEONLY	Logical	False	$\text{LEONLY} = \text{.TRUE.}$ for smoothing about the leading edge only; this is used if the trailing edge is a cusp or a wedge. SMOOTH must also be .TRUE. .
SLP1	Real	1	These parameters control the concentration of grid lines, if desired. The default values worked well for the DCA blades reported herein. For controlling the amount and location of the concentration consult Ref. 9.
SLP2	Real	2	
SLP3	Real	1	
SLP4	Real	1	

The following logical and case control parameters are required only for flow solution runs.

<u>Name</u>	<u>Type</u>	<u>Default</u>	<u>Description</u>
MINF	Real	None	This is the Mach number at the upstream boundary. This can be determined from the non-dimensional velocity X output from the cascade tunnel data reduction program 'Redd 5' and the relationship,

$$\frac{\gamma - 1}{2} M^2 = \frac{X^2}{1 - X^2} \quad \text{which yields}$$

$$M = \left\{ \frac{X^2}{1 - X^2} \cdot \frac{2}{\gamma - 1} \right\}^{\frac{1}{2}}$$

TOLS(I) is the tolerance for MS(I) and NOZES(I). There are three forms of input permitted.

- A) $-1.0 < \text{TOLS}(I) < 0.0$: Calculations of the flow solution will proceed until the relative circulation error

$$\left| \frac{C_{\text{CALC}}^N - C_{\text{EXACT}}}{C_{\text{EXACT}}} \right| < |\text{TOLS}(I)|$$

TOLS values between -10^{-3} and -10^{-6} are typical values for grids. This method of input is appropriate only for lifting (non-symmetric blades) cases.

- B) $0.0 < \text{TOLS}(I) < 1.0$: Calculations of the flow solution will proceed until the average relative change in potential is less than the absolute value of TOLS(I).

$$\left(\frac{\delta \phi}{\phi} \right)_{\text{AVE}} < |\text{TOLS}(I)|$$

Typical values should be between 10^{-3} and 10^{-5} .

- C) $1.0 < \text{TOLS}(I)$: Calculations proceed until the number of iterations equals TOLS(I).

Regardless of TOLS input, the solution for each grid will stop after 300 iterations if the TOLS criteria has not yet been made. All three forms were used for the cascade configuration reported herein with no discernible differences in results.

OVEREL	Real	1.5	The default values of these parameters are adequate for flow conditions in the subsonic cascade wind tunnel.
UNDERL	Real	1.0	
SUPREL	Real	1.0	
NOWREL	Integer	20	
NOTYET	Integer	2	
TEGARD	Real	2.0	
DAMP	Real	1.0	
CII	Real	0.2	
IT	Integer	10	Number of iterations between intermediate printouts of residuals and Mach number. The information controlled by this parameter is of limited value in comparing with measured data, so a value greater than 10 reduces the amount of computer printout. For the study reported herein 40 was used.
ALLOUT	Logical	.FALSE.	To list the flow quantities at all grid points in the last mesh set ALLOUT = .TRUE.. Unless a very coarse grid is used, the output resulting from ALLOUT = .TRUE. would be extremely voluminous and of limited value. Until the cascade is configured so it is possible to take data from between the blades, ALLOUT should be .FALSE..
QUASI3	Logical	.FALSE.	QUASI3 = .TRUE. to activate streamchannel thickness and/or radius variations. The cascade wind tunnel has no radius variations, but to simulate 3-D effects the streamchannel thickness is reduced at the exit boundary by a factor of 1/AVDR. This data is placed in a file used by QSONIC if a quasi 3-D solution is desired.
NSTRM	Integer	1	This is the position of desired streamsurface data on the streamchannel file used if QUASI3 = .TRUE.. Currently the default value of 1 identifies the proper streamsurface data

in the streamchannel file. If the output from the NASA code 'Meridl' is used for the streamchannel data, then by using different values of NSTRM, different streamsurface data may be used.

RINF Real 1.0

This is the spanwise radius at the upstream boundary divided by aerodynamic chord. Radius effects are activated if $RINF \neq 1.0$. The current version of QSONIC allows the following cases.

	<u>QUASI</u>	<u>RINF</u>	<u>Results</u>
1)	.FALSE.	1.0	Planar 2D flow
2)	.TRUE.	$\neq 1.0$	Thickness on file; radius on file.
3)	.TRUE.	1.0	Thickness on file; constant radius.

Only 1) and 3) apply to the cascade wind tunnel.

WAKE Real 0.0
 MINF2 Real 10.0
 OMEGA Real 0.0
 VAXIAL Real 999.0
 FLOCO Real 999.0

These parameters apply only if the test cascade is rotating and/or the downstream Mach is near 1.0.

At this point all of the logical and case control parameters necessary to use QSONIC for the flow conditions possible in the subsonic cascade wind tunnel have been discussed. The following is a description of the Bulk Data input for the geometry generation run and the flow solution run.

The format for all variables in the bulk data for mesh generation (geometry) is namelist form. The namelist is INSTUFF.

<u>Name</u>	<u>Type</u>	<u>Default</u>	<u>Description</u>
H2	Complex	None	This is a table of points defining the blade profile. The real part = X, and imaginary part = Y coordinate. The table begins at the point of maximum X value at the trailing edge and proceeds clockwise back around to the first point, which is repeated. The blade must be at the stagger angle and the origin at the point of minimum X. For Electrostatic Analog grids, the stagger angle must be positive (leading edge low, trailing edge high). The maximum number of points in H2 is 99 for the interpolation scheme or 63 for the Electrostatic Analog.
BUG2	Logical	.FALSE.	BUG2 = .TRUE. for a more detailed output of geometry generation. This will include the X,Y coordinates that define the mesh as well as second derivatives at grid points on the body. Except for trouble shooting this data is of limited value at the present time since there is no graphic output.

The bulk data for flow solutions consists of a mesh file and the streamchannel data file if quasi-3D effects are to be calculated. The mesh file is created by QSONIC during the mesh (grid) generation run. No further inputs are required from the user for the mesh file.

The streamchannel data file must contain a table of streamtube thicknesses, radial positions and corresponding X values along the streamsurface.

<u>Name</u>	<u>Type</u>	<u>Default</u>	<u>Description</u>
CHO	Real	None	CHO is the aerodynamic chord multiplied by the cosine of LAMDA0. (LAMDA0 = stagger angle)
NRSP	Integer	None	NRSP is the total number of data points in each of the tables of thickness, radial position, and X location. If NRSP is 2, a linear distribution is obtained between the endpoints given. NRSP = 2 was used for the study reported herein with good results.
RM	Real	None	Array of corresponding X locations for thickness and radius data values. X = 0 represents the leading edge of blade, with the blade at stagger angle. The units can be any consistent length scale common to CHO, RM, RMSP and BESP. Inches were used in this study.
RMSP	Real	None	Spanwise radial positions of streamsurface at the X locations given in RM. RMSP was not used in the current study.
BESP	Real	None	Array of streamtube thickness values at the X locations specified in RM. For the study reported herein, at X = 0 a streamtube thickness of 1.0 was arbitrarily selected. The streamtube contraction through the test section was simulated by reducing the thickness at X = 0, by a factor of 1/AVDR at the trailing edge. Duval [Ref. 3] explains AVDR.

D.3 PREPARING INPUT FILES

QSONIC was originally configured to use several input/output devices while reading data and generating output. The input/output devices are listed below as used by QSONIC.

<u>I/O Unit</u>	<u>Usage</u>
2	File containing streamchannel data. This is used only if QUASI = .TRUE..
5	Standard card input; NAMELISTS PARAMS, INSTUF.
6	Standard printed output.
13	For mesh generation runs, coordinates of all mesh points are written here. For flow solutions, X, Y, velocities, pressures and MACH are recorded for graphic display. The program currently has no graphic output capability. No user action is necessary to create this file.
18	Used as temporary storage. No output is stored here. No user action is necessary in conjunction with this file.
23	Previously developed mesh coordinates are read in from this file during the flow solution. After a mesh generation run, the user must create this file and put in it the data from I/O unit 13, so that during the flow solution QSONIC can read in the mesh points.

QSONIC is presently configured to operate with the CMS system of the IBM 370 computer. This system provides a high degree of flexibility in parameter selection. With this system, all the input/output units previously mentioned are on the disk space assigned to the Turbopropulsion Laboratory (TPL). Access to QSONIC and the TPL disk space can be obtained through the Director of TPL.

The first step in using QSONIC is the creation of the data file necessary for the mesh generation run. This is done using the standard procedures of the XEDIT function of the CMS operating system. Reference 14 has specific instructions for creating new files. The filename and file-type for the data used in this study was NAMELIST GFOMD. Once the data file is opened, the necessary data is input beginning at column 2 of the virtual card. Since the variables are in namelist form, they can be input in any order.

Table D.1 is an example of the data file necessary for the mesh generation run. The TITLE must appear on the first line (FORMAT = 20A4). After the TITLE, the logical and case control parameters are input after the namelist &PARAM'S. When all the case control parameters required are input the PARAMS namelist is closed with &END. On the next line of the data file the bulk data for the mesh generation run is input in namelist form, with the namelist &INSTUF. The $H1 = 100*(0.0,0.0)$ that appears after &INSTUF on Table D.1 was used on earlier versions of QSONIC, but is not used in the present version. It should, however, appear in the data file before the H2 variables (X,Y coordinates defining the blade profile).

At this point, some discussion of the coordinates defining the blade profile is warranted. Table D.2 is a listing of the X and Y coordinates of the DCA blading used in this study. Figure D.1 is a plot of these coordinates.

Recall that the coordinates defining the blade profile for QSONIC must be for the blade at the stagger angle and minimum X at the origin. The coordinates of Table D.2 were translated and rotated using a coordinate transformation routine for the HP-67 programmable calculator. These new coordinates appear in the namelist INSTUFF on Table D.1. Figure D.2 is a plot of the translated and rotated coordinates. It is highly recommended that such a plot be made for any new blade profiles, to ensure that the original coordinates are translated and rotated properly.

The second step in using QSONIC is the creation of the data files necessary for the flow solution run. The file used for the flow solution in this report is on the TPL disk space with a filename/filetype of NAMELIST FLOWD. The simplest way to open this data file is to use the XEDIT function, as discussed in Ref. 14, to start a new file. Then input the same data as is in the data file for the mesh generation run using the XEDIT subcommand GET (filename) (filetype). The appropriate changes and additions can then be made to this file. Table D.3 is an example of the data file just discussed.

Two more data files are required for the flow solution. The data for one of these is created by the mesh generation run. The other file contains the streamchannel thickness data for implementing quasi-3D effects.

After the mesh generation run, a file with the file-name/filetype MESHGEN DATA will appear on the disk. Create a new file with the filename/filetype MESHIN DATA. This is most easily done by issuing the command 'XEDIT MESHIN DATA'; then use 'GET MESHGEN DATA'. This file contains the previously developed mesh coordinates.

The streamchannel data file should have the filename/filetype of DATA5D DATA. The format for the data file is shown below.

<u>Virtual Card</u>	<u>Column No.</u>	<u>Variable Name</u>
1	_____ BLANK _____	
2	_____ BLANK _____	
3	21-30	CHO
4	_____ BLANK _____	
5	36-40	NRSP
6	_____ BLANK _____	
7	_____ BLANK _____	
8		
9		
10		
11		
12		RM
↓		
As needed	1-80 (8F10.5)	RMSP (not used in this study)
↓		
As needed	1-80 (8F10.5)	BESP

Table D.4 is an example of the data file used in the present study. Since NRSP = 2 was used for this study a

linear distribution is assumed for the streamtube thickness values and only 2 values of RM and BESP are required; therefore, only 1 virtual card was required for each array.

D.4 PROGRAM OUTPUT

The output generated by QSONIC for the geometry generation run includes a printed listing (I/O unit 6) and a mesh point file (I/O unit 13). The printed listing under the CMS system I/O unit 6 is normally the computer terminal unless the command 'FILEDEF 06 PRINTER' has been invoked. It is unusual for the program to run properly the first time, so initially it is helpful to have the printed listing appear at the terminal. Once the program is running properly the output should be sent to the line printer.

The flow solution run output consists of a printed listing (I/O unit 6) and a plot data save file (I/O unit 13). Once the flow solution is running properly the printed listing should be sent to the line printer.

Table D.5 is an example of the output generated by the geometry generation run. Figure D.3 is a plot of the grid output points on the blade surface, horizontal chord, produced by the mesh generation run. Figure D.4 is a plot of the grid output points with the blade at the stagger angle. Table D.6 is an example of the output generated by the flow solution.

A detailed explanation of the printed output for the program QSONIC may be found in Ref. 9.

D.5 RUNNING THE PROGRAM

The files on the TPL disk space that apply to QSONIC are listed below:

QSONIC EXEC	A1
QSONIC FORTRAN	A1
QSONIC TEXT	A1
NAMELIST GEOM	A1
NAMELIST FLOW	A1
NAMELIST GEOMD	A1
NAMELIST FLOWD	A1
DATA5 DATA	A1
DATA5D DATA	A1

QSONIC EXEC sets the input/output devices required to read and store data. QSONIC FORTRAN is the source program. To document the changes to QSONIC necessary to use the code with the IBM 370 operating system and serve as a reference for future users, a program listing is included at the end of this appendix. QSONIC TEXT is the computer executable code created when QSONIC FORTRAN is compiled. NAMELIST GEOM and NAMELIST FLOW are the data files for the geometry generation and flow generation respectively for the example in Ref. 9. DATA5 DATA is the streamchannel data required for the quasi-3D solution for the example in Ref. 9.

NAMelist GEOMD is the data file for the geometry generation for the DCA blading used in the study reported herein. NAMelist FLOWD is the file for the flow solution for the cascade configuration used in this study.

QSONIC expects the input data to be in a file on the TPL disk space named NAMelist DATA. Since the first time QSONIC is run is to develop the body centered mesh, the file NAMelist GEOMD must be renamed NAMelist DATA, using procedures specified in Ref. 13. Because QSONIC requires large amounts of virtual memory, extra storage must be defined for the code to operate. This is accomplished by issuing the command 'DEFINE STORAGE 1504K'.

With the data file renamed and more storage defined, type 'QSONIC' to load the program. The output will appear on the terminal screen unless FILEDEF 06 PRINTER was invoked prior to loading the program.

After the mesh generation is complete, rename NAMelist DATA to NAMelist GEOMD and change NAMelist FLOWD to NAMelist DATA. Create a data file with the filename/filetype MESHIN DATA. The elements of this file are the same as the elements in the file MESHGEN DATA that was created by the mesh generation run. The necessary input/output files are now configured for a flow solution run. Issue the command 'QSONIC' to begin execution.

If the program output appears at the terminal it is possible to have some I/O error messages appear with the

output. This is because the write statements in QSONIC are formatted for the 132 character long line of the printer. These errors do not affect the validity of the program output.

The explanation for any error or condition message generated by QSONIC can be found in Ref. 9.

D.6 QSONIC UPDATE

Recently an improved version of QSONIC was reported by NASA Lewis Research Center [Ref. 13]. The new version requires less virtual memory and executes approximately 30% faster than the version presently in use at NPS. Also, the output appears in a different format than is described in this appendix. Reference 18 describes the most recent version of QSONIC in detail.

TABLE D.1. INPUT DATA FOR MESH GENERATION RUN OF QSONIC

```

NASAS DCA BLADES, GEOMETRY GEN 42.4,5.3
&PARAMS NOFLOW=.TRUE.,RESTAR=.FALSE.,REMESH=4,
MS=3,5,10,15,NOZES=9,13,25,49,MESH1=4,MESHN=4,LAMDAO=14.27,
CHORD=5.01,S=3.0,NED=51,KN=0,RLE=0.44,RTE=0.44,
THETL=-45.72,THET=45.72,CAMPER=5,STABAC=0.999,CHOP=0.99,
SMOOTH=.TRUE.,LEONLY=.FALSE.
&ENDSTUF
H1=100*(0.0,0.0,0.0)
H2=(0.47426E+01,0.12616E+01),(0.48095E+01,0.12066E+01)
(0.42827E+01,0.12102E+01),(0.45112E+01,0.12153E+01)
(0.38285E+01,0.12170E+01),(0.40545E+01,0.12096E+01)
(0.33812E+01,0.11975E+01),(0.36030E+01,0.11793E+01)
(0.29391E+01,0.11549E+01),(0.31591E+01,0.11232E+01)
(0.25038E+01,0.10879E+01),(0.27205E+01,0.10467E+01)
(0.18621E+01,0.9978),(0.22877E+01,0.9428),(0.20745E+01,0.8845)
(0.12322E+01,0.5898),(0.16499E+01,0.7486),(0.14402E+01,0.6726)
(0.6158,0.3071),(0.10257E+01,0.5011),(0.8201,0.4045)
(0.656E-01,0.0),(0.4137,0.2010),(0.2134,0.882701E-01)
(0.1801,0.2190),(0.3701,0.126E-01),(0.5135),(0.7588,0.6458)
(0.9584,0.7657),(0.3726),(0.5633,0.13630E+01),(0.9759)
(0.15693E+01,0.10655E+01),(0.17783E+01,0.11486E+01)
(0.19897E+01,0.12179E+01),(0.22017E+01,0.12811E+01)
(0.24183E+01,0.13341E+01),(0.26362E+01,0.13782E+01)
(0.28562E+01,0.14135E+01),(0.30795E+01,0.14362E+01)
(0.33055E+01,0.14524E+01),(0.35325E+01,0.14565E+01)
(0.37639E+01,0.14514E+01),(0.39971E+01,0.14354E+01)
(0.42334E+01,0.14109E+01),(0.44717E+01,0.13704E+01)
(0.47147E+01,0.13197E+01),(0.48232E+01,0.12947E+01)
(0.48554E+01,0.12616E+01),48*(0.0,0.0)
BUG2=
&BEND

```


TABLE D.2. TEST BLADE COORDINATES

X-COORD.	Y-PRESS.	Y-SUCT.
-0.044	0.000	0.000
-0.021	-----	0.039
0.013	-0.042	-----
0.178	0.007	0.142
0.400	0.067	0.244
0.622	0.120	0.333
0.844	0.164	0.413
1.067	0.207	0.480
1.289	0.242	0.538
1.511	0.271	0.584
1.733	0.293	0.620
1.956	0.309	0.649
2.178	0.320	0.664
2.399	0.324	0.673
2.622	0.324	0.671
2.844	0.318	0.660
3.066	0.304	0.640
3.288	0.284	0.607
3.511	0.260	0.567
3.732	0.229	0.515
3.955	0.191	0.453
4.177	0.147	0.380
4.400	0.098	0.298
4.621	0.040	0.200
4.844	-0.022	0.091
4.908	-0.042	-----
4.943	-----	0.040
4.966	0.000	0.000

TABLE D.3. INPUT DATA FOR FLOW SOLUTION RUN OF QSONIC

```

NASA DCA BLADES, FLOW SOLUTION 42.4,5.3
PARAMS NOFLOW=.FALSE., RESTAR=.FALSE., REMESH=4,
MS=3, 5, 10, 15, NOZES=-9, -13, -25, CHORD=5.01, 42,
MESH1=1, MESH2=0.3127, BETA1=28.16, BETA2=-12.42,
S=3.0, MINF=0.3127, E+04, SUPREL=1.0, NOWREL=20, NOTYET=10,
GAMMA=1.4, TOL=1.5, UNDERL=1.1, SUPREL=1.0, NOWREL=20, NOTYET=10,
OVEREL=1.5, UNDERL=1.1, SUPREL=1.0, NOWREL=20, NOTYET=10,
CIRI=0.40, I=40, ALLOUT=.FALSE., QUASI3=.TRUE., NSTRM=1,
RINF=1., WAKE=0., MINF2=10.0, OMEGA=0.
END
INSTUF
H1=100*(0.0,0.0,0.0)
H2=(0.48554E+01, 0.12616E+01), (0.48095E+01, 0.12066E+01)
(0.42827E+01, 0.12170E+01), (0.45112E+01, 0.12153E+01)
(0.38285E+01, 0.11975E+01), (0.40545E+01, 0.12096E+01)
(0.33812E+01, 0.11549E+01), (0.36030E+01, 0.11793E+01)
(0.29391E+01, 0.10879E+01), (0.31591E+01, 0.11232E+01)
(0.25038E+01, 0.9978), (0.22877E+01, 0.9428), (0.20745E+01, 0.8845)
(0.18621E+01, 0.8191), (0.16499E+01, 0.7486), (0.14402E+01, 0.6726)
(0.12322E+01, 0.5898), (0.10257E+01, 0.5011), (0.82201, 0.4045)
(0.6158, 0.3071), (0.4137, 0.2010), (0.2134, 0.882E-01)
(0.656E-01, 0.0), (0.3701, 0.267E-01), (0.126E-01, 0.701E-01)
(0.1801, 0.2190), (0.3701, 0.3726), (0.5633, 0.5135), (0.7588, 0.6458)
(0.9584, 0.7657), (0.11592E+01, 0.8766), (0.13630E+01, 0.9759)
(0.15693E+01, 0.10655E+01), (0.17783E+01, 0.1486E+01)
(0.19897E+01, 0.12179E+01), (0.22017E+01, 0.12811E+01)
(0.24183E+01, 0.13341E+01), (0.26362E+01, 0.13782E+01)
(0.28562E+01, 0.14135E+01), (0.30795E+01, 0.14362E+01)
(0.33055E+01, 0.14524E+01), (0.35325E+01, 0.14565E+01)
(0.37633E+01, 0.14514E+01), (0.39971E+01, 0.14354E+01)
(0.42334E+01, 0.14109E+01), (0.44717E+01, 0.13704E+01)
(0.47147E+01, 0.13197E+01), (0.48232E+01, 0.12947E+01)
(0.48554E+01, 0.12616E+01), 48*(0.0, 0.0)
BUG2=F
END

```


TABLE D.4. DATA FILE FOR QUASI-3D SOLUTION

STREAMLINE DATA FOR DCA1

4.8554

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0.0	4.85500
1.00000	0.98476

TABLE D.5 (Continued)

0	90043390	0	2425748																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																															
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TABLE D.5 (Cont'd)

2	0	312	81E-01	0	824	62E-01	68	-0	101	98E+00	0	1	93	32E+00
2	1	252	1E-02	0	755	73E-01	69	-0	808	04E-01	0	0	12	573E+00
2	2	821	39E-01	0	682	20E-01	70	-0	596	91E-01	0	0	13	173E+00
2	2	573	39E-01	0	604	91E-01	71	-0	385	46E-01	0	0	13	727E+00
2	2	861	80E+00	0	523	330E-01	72	-0	172	71E-02	0	0	14	231E+00
2	2	114	61E+00	0	437	43E-01	73	-0	409	76E-01	0	0	14	690E+00
2	2	142	54E+00	0	347	46E-01	74	0	255	43E-01	0	0	15	109E+00
2	2	170	05E+00	0	254	21E-01	75	0	470	74E-01	0	0	15	483E+00
2	2	197	07E+00	0	157	33E-02	76	0	686	71E-01	0	0	15	801E+00
2	2	223	56E+00	0	565	39E-02	77	0	903	93E+00	0	0	16	068E+00
2	2	249	39E+00	-0	470	77E-02	78	0	112	39E+00	0	0	16	291E+00
2	2	274	51E+00	-0	153	15E-01	79	0	134	55E+00	0	0	16	470E+00
2	2	298	83E+00	-0	261	58E-01	80	0	156	82E+00	0	0	16	605E+00
2	2	322	27E+00	-0	369	51E-01	81	0	179	14E+00	0	0	16	693E+00
2	2	344	80E+00	-0	476	08E-01	82	0	201	64E+00	0	0	16	727E+00
2	2	366	50E+00	-0	581	74E-01	83	0	224	28E+00	0	0	16	709E+00
2	2	387	34E+00	-0	686	41E-01	84	0	246	99E+00	0	0	16	444E+00
2	2	406	85E+00	-0	788	44E-01	85	0	269	76E+00	0	0	16	530E+00
2	2	425	04E+00	-0	887	96E-01	86	0	292	50E+00	0	0	16	374E+00
2	2	441	22E+00	-0	978	84E-01	87	0	315	17E+00	0	0	16	172E+00
2	2	455	45E+00	-0	110	637E+00	88	0	337	42E+00	0	0	15	917E+00
2	2	477	30E+00	-0	113	77E+00	89	0	359	26E+00	0	0	15	278E+00
2	2	484	84E+00	-0	120	67E+00	90	0	380	27E+00	0	0	14	895E+00
2	2	494	68E+00	-0	119	25E+00	91	0	400	63E+00	0	0	14	518E+00
2	2	496	85E+00	-0	115	93E+00	92	0	419	36E+00	0	0	14	176E+00
2	2	494	88E+00	-0	110	77E+00	93	0	436	56E+00	0	0	13	848E+00
2	2	488	83E+00	-0	103	79E+00	94	0	451	23E+00	0	0	13	541E+00
2	2	479	05E+00	-0	94	958E-01	95	0	461	779E+00	0	0	13	229E+00
2	2	466	96E+00	-0	84	229E-01	96	0	469	63E+00	0	0	12	825E+00
2	2	452	18E+00	-0	71	822E-01	97	0	467	774E+00	0	0	12	400E+00
2	2	435	54E+00	-0	58	480E-01	98	0						
2	2	416	86E+00	-0	44	022E-01								
2	2	397	21E+00	-0	29	507E-01								
2	2	376	69E+00	-0	15	007E-02								
2	2	355	83E+00	-0	10	233E-01								
2	2	334	68E+00	-0	12	473E-01								
2	2	313	39E+00	-0	25	319E-01								
2	2	291	99E+00	-0	37	531E-01								
2	2	270	72E+00	-0	49	044E-01								
2	2	249	51E+00	-0	59	877E-01								
2	2	228	30E+00	-0	70	028E-01								
2	2	185	98E+00	-0	79	567E-01								
2	2	164	92E+00	-0	88	653E-01								
2	2	144	00E+00	-0	97	197E-01								
2	2	123	08E+00	-0	110	509E+00								
2	2			-0	11	124E+00								

TABLE D.6. SAMPLE OUTPUT FROM FLOW SOLUTION RUN

[illegible]

TABLE D.6 (Continued)

RELAXATION BEGINS ON GRID OF 3 SURFACE CONTOURS INTERSECTED BY 17 RADIATING LINES									
ITERATION	AVERAGE PHI CORRECTION	RESIDUAL AT 1% C.	MAX MACH ON BLADE	CALCULATED CIRCULATION	RELATIVE CIRC FACOR	SUBSONIC RELAX. FAC.	SUPERSONIC RELAX. FAC.		
40	C.031149E-01	0.889240E-02	0.313030E+00	-0.203196E+01	-0.105212E+01	0.150000E+01	0.100000E+01		
80	C.015749E-01	0.889185E-02	0.313030E+00	-0.165187E+01	-0.117147E+01	0.150000E+01	0.100000E+01		
120	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
160	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
200	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
240	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
280	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
300	C.077503E-02	0.889185E-02	0.313030E+00	-0.109995E+00	-0.128216E+01	0.150000E+01	0.100000E+01		
END OF CALCULATION ON GRID 1 OF 4									
FINAL FLOW CALCULATION ON BLADE SURFACE FOR THE 3 BY 17 MESH									
RADIATING LINE NO.	X/CX	Y/CX	X	Y	MACH	STATIC PRES COEF	PHI	XVEL	DENSITY
1	C.00000	C.26029	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
2	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
3	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
4	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
5	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
6	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
7	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
8	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
9	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
10	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
11	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
12	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
13	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
14	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
15	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
16	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291
17	C.00000	C.00000	0.46564	0.12825	0.22825	-0.25555	1.70549	0.71364	0.05291

TABLE D.6 (Continued)

RELAXATION BEGINS ON GRID OF 5 SURFACE CONTIGUOUS INTERSECTED BY 25 RADIATING LINES									
SUPERSONIC RELAXATION PARAMETER, SUPREL= 0.60000E+00									
ITERATION	AVERAGE	MAX MACH	RELATIVE	SUBSONIC	SUPERSONIC				
CCOUNT	PMI CORRECTN	ON BLADE	CALCULATION	RELAX. FAC.	RELAX. FAC.				
40	C.210941E-02	0.180530E-02	0.390200E+00	0.542207E-03	0.150000E+00				
55	0.113744E-02	0.195710E-03	0.410352E+00	0.139110E-04	0.150000E+01				
FINAL FLOW CALCULATION ON BLADE SURFACE FOR THE 5 BY 25 MESH									
RADIATING	X/CX	Y/CX	X	Y	MACH	STATIC	PMI	XVEL	DENSITY
LINE NO.						PRES COEFF			
1	0.0000	0.25667	0.46563	0.12825	0.20406	0.59614	-0.08327	0.65456	1.02414
2	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
3	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
4	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
5	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
6	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
7	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
8	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
9	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
10	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
11	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
12	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
13	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
14	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
15	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
16	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
17	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
18	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
19	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
20	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
21	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
22	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
23	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
24	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423
25	0.0000	0.25667	0.46563	0.12825	0.20406	0.33110	-0.10239	0.71854	1.01423

END OF CALCULATION ON GRID 2 OF 4

TABLE D.6 (Continued)

RELAXATION REGIONS CN GRID OF 15 SURFACE CONTOURS INTERSECTED BY 49 RADIATING LINES										
SUPERSONIC RELAXATION PARAMETER, SUPREL= 0.50000E+00										
ITERATION COUNT	AVERAGE FPI CORRECTN	RESIDUAL AT T. E.	MAX MACH CN BLADE	CALCULATED CIRCULATION	RELATIVE ERROR	PHI	XVEL	YVEL	DENSITY	
40	0.712658E-03	-0.160764E-03	0.302182E+00	0.389971E+00	0.358700E-03	0.358700E-03	0.150000E+01	0.150000E+01	0.500000E+00	
80	0.176843E-03	-0.338110E-04	0.302193E+00	0.389848E+00	0.443410E-04	0.443410E-04	0.150000E+01	0.150000E+01	0.500000E+00	
120	0.697057E-04	-0.136388E-04	0.304539E+00	0.385830E+00	0.177322E-04	0.177322E-04	0.150000E+01	0.150000E+01	0.500000E+00	
FINAL FLOW CALCULATION ON PLANE SURFACE FOR THE 15 BY 49 MESH										
RADIATING LINE NO.	X/CX	Y/CX	X	Y	MACH	STATIC PRES COEFF	PHI	XVEL	YVEL	DENSITY
1	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
2	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
3	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
4	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
5	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
6	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
7	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
8	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
9	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
10	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
11	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
12	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
13	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
14	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
15	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
16	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
17	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
18	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
19	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
20	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
21	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
22	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
23	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
24	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
25	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
26	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
27	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
28	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
29	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
30	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
31	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
32	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
33	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
34	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
35	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
36	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
37	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
38	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
39	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
40	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
41	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
42	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
43	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
44	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
45	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
46	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
47	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
48	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864
49	0.00000	0.25760	0.46393	0.12825	0.12741	0.48914	-0.14220	0.40573	0.17419	1.02864

END OF CALCULATION CN GRID 3 OF 4

TABLE D.6 (Continued)

[illegible]

FINAL FLOW CALCULATION ON BLADE SURFACE FOR THE 15 BY 97 MESH

[illegible]

TABLE D.6 (Continued)

[illegible]

END OF CALCULATION CN GRID 4 CF 4

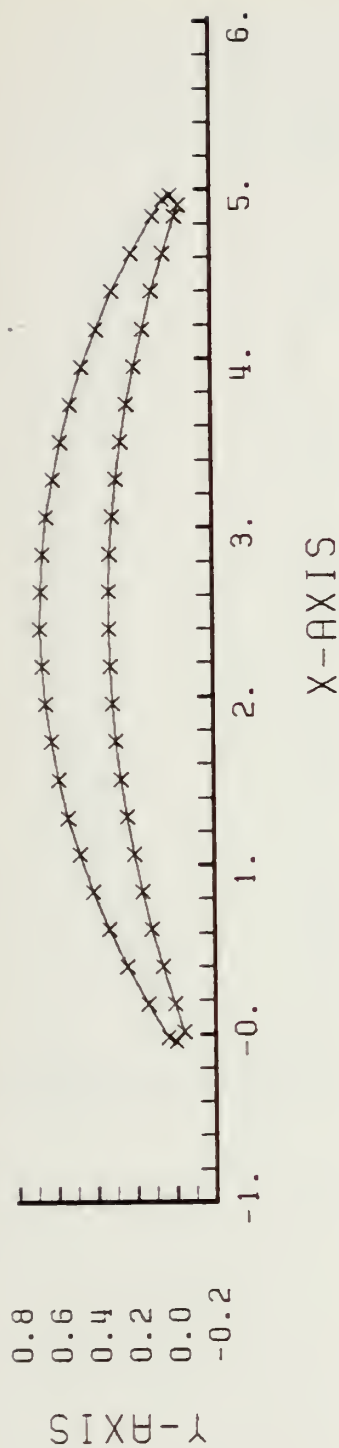


Fig. D.1. Blade Coordinates

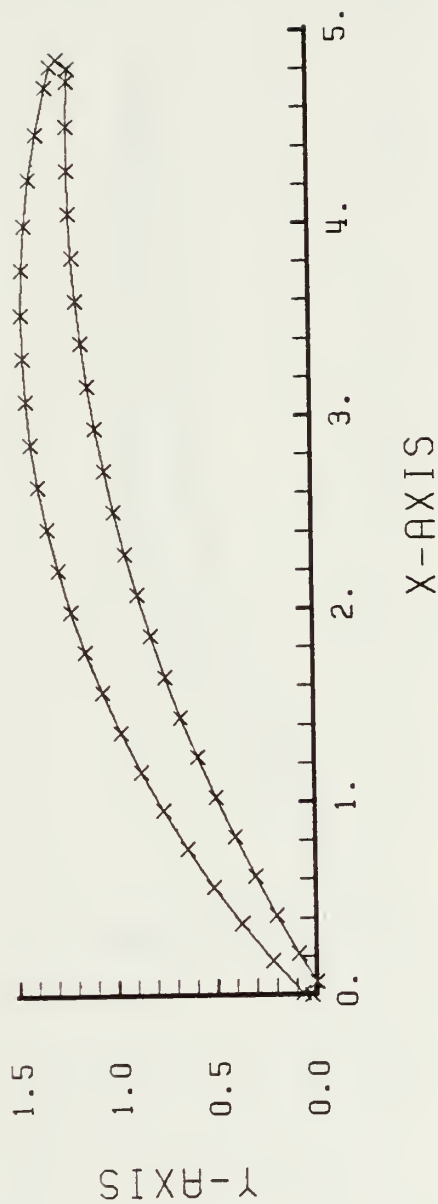


Fig. D.2. Blade Coordinates Translated and Rotated

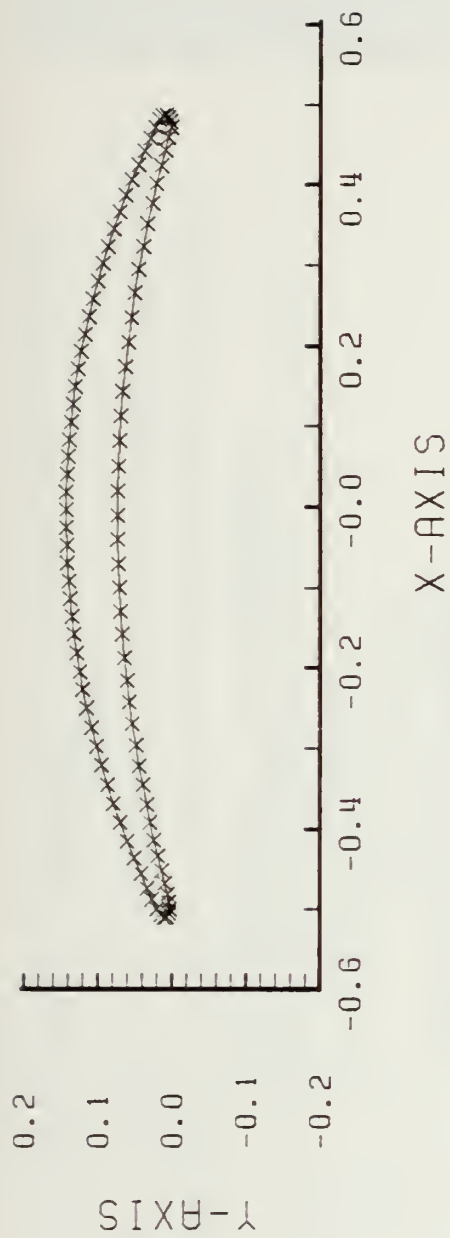


Fig. D.3. Mesh Points on Blade Surface, Horizontal Chord

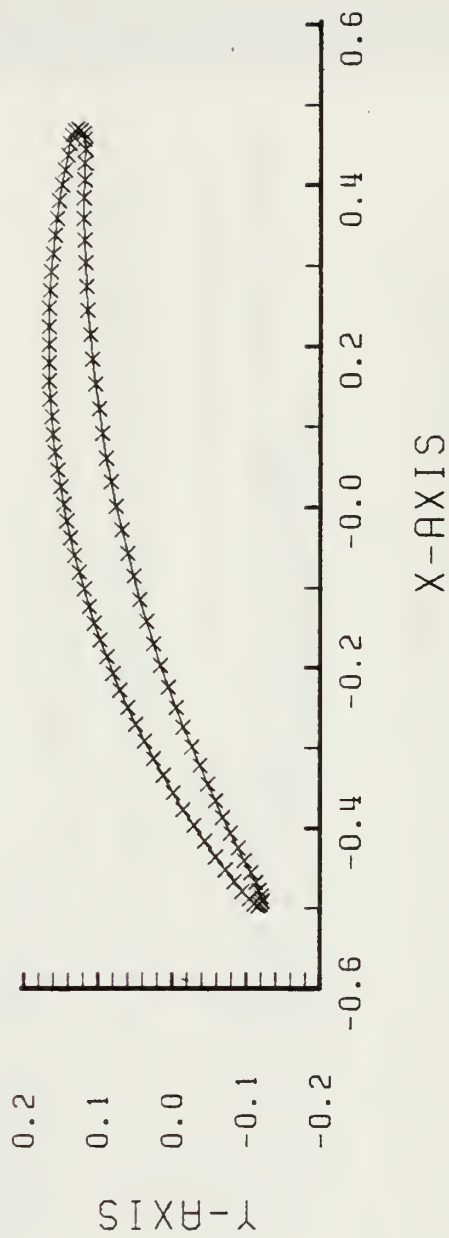


Fig. D.4. Mesh Points on Blade Surface, Chord at Stagger Angle

qqS00010
 qqS00020
 qqS00030
 qqS00040
 qqS00050
 qqS00060
 qqS00070
 qqS00080
 qqS00090
 qqS00100
 qqS00110
 qqS00120
 qqS00130
 qqS00140
 qqS00150
 qqS00160
 qqS00170
 qqS00180
 qqS00190
 qqS00200
 qqS00210
 qqS00220
 qqS00230
 qqS00240
 qqS00250
 qqS00260
 qqS00270
 qqS00280
 qqS00290
 qqS00300
 qqS00310
 qqS00320
 qqS00330
 qqS00340
 qqS00350
 qqS00360
 qqS00370
 qqS00380
 qqS00390
 qqS00400
 qqS00410
 qqS00420
 qqS00430
 qqS00440
 qqS00450
 qqS00460
 qqS00470
 qqS00480

[illegible]

ADAPTED TO THE NAVAL POSTGRADUATE SCHOOL IBM 370/3033
BY
C. A. FARRELL, J. J. ADAMCZYK
NASA LEWIS RESEARCH CENTER 1981
LT. WILLIAM D. MOLLOY JR. 18 DEC 81

SONIC EXECUTIVE

READS CASE CONTROL INPUT
FOR EACH GRID REQUESTED, CALLS
GEOMETRY SETUP
STREAMCHANNEL DATA SETUP
FLOW SOLVER
CALLS FINAL OUTPUT GENERATOR

```

LOGICAL RESTAR, NOFLOW, QUASI3, LEONLY
1, BUG, BUG2, BUG3, SMOOTH, FINEST, ALLOUT
INTEGER REMESH, CAMPER
REAL MINF, LAMDAO, MINF2
DOUBLE PRECISION CAPK, CAPKP
COMMON/MESHES/NOZES(10), MS(10), TOL$(10), NOLD(2)
COMMON/PARAM/RESTAR, NOZIN, BETA1, BETA2, QINF1, CI, CII, GAMMA, MINF,
1, MINF2
11, DELTA, BETA, TOL, BUG, BUG2, BUG3, IT, GUESS, OVEREL, TIMER, NOWREL, NOTYET
11, DAMP, SUPREL, S, WAKE, B2OB1, UNDERL, R2OR1, RINF, OMEGA, FLOCO, VAXIAL
11, ALLOUT, KKKMAX
COMMON/QUASIR(100, 30), B(100, 30)
COMMON/ENTIRE/ X(100, 30), Y(100, 30), PHI(100, 30), DELPSV(100, 30)
COMMON/GEOM2/ZETA(100), ETA(100)
COMMON/GEOM/NEWNDZ, NEWM, RLE, RTE, A, CHORD, XUPS, XDNS, LAMDAO, CC, CAPK,
1, CAPKP, PI, RNK, VB, KN, NED, BB, DOSURF, RFAC, SOLID, MPLS
11, STABAC, SLP1, SLP2, SLP3, SLP4, SMOOTH, CHOP, THEIT, THETL
11, FINEST, LEONLY, CAMPER

DIMENSION TITLE(20)
NAMELIST/PARAMS/ NOFLOW, RESTAR, REMESH, MS, NOZES, MESH1, MESH2,
1, LAMDAO, CHORD, S, NED, KN, RLE, RTE, THEIT, CAMPER, STABAC, CHOP,
1, SMOOTH, LEONLY, SLP1, SLP2, SLP3, SLP4, MINF1, BETA1, BETA2, GAMMA,
1, TOL$(10), OVEREL, UNDERL, NOWREL, NOTYET, TEGARD, DAMP, CII, IT,
1, ALLOUT, QUASI3, NSTRM, RINF, WAKE, OMEGA, VAXIAL, FLOCO, MINF2

```



```

3      DATA NSTRM,QUASI3,MESH1/1,.FALSE.,1/,REMESH/4/,TEGARD/2./
1,NOFLOW/.FALSE./
DATA QLEVEL/'9.1'//
READ(5,3) TITLE
FORMAT(20A4)
WRITE(6,33) QLEVEL,TITLE
33  FORMAT(IH1,' QSONIC VERSION 1.4.',A4,2X,21A4//)

READ(5,PARAMS)
WRITE(6,2)
FORMAT(10) CASE CONTROL INPUT ECHO '/'
WRITE(6,PARAMS)

BETA1=BETA1*PI/180.
LAMDAO=LAMDAO*PI/180.
BETA2=BETA2*PI/180.
MIN=MS(MESH1)
IF(RESTAR)MESH1=REMESH
NOZIN=IABS(NOZES(MESH1))
IF(QUASI3.AND.B2OBI.EQ.1.)CALL RBIN(NSTRM,LAMDAO)

DO 1 I=MESH1,MESHN
MESH=I
NOLD(2)=NEWM
NOLD(1)=IEXIT
NEWNOZ=NOZES(MESH)
NEWM=MS(MESH)
TOL=TOLS(MESH)
REWIND 23
REWIND 13
CALL WRAPUP(ZETA,ETA,S)
IEXIT=2*(NEWNOZ-1)
CALL WHEEL(LAMDAO,NEWM,IEXIT,NOFLOW)
IF(NOFLOW)STOP
IF(QUASI3) CALL FILLRB(NEWM,IEXIT,RINF,LAMDAO)
IF(RESTAR.OR.MESH.NE.MESH1)CALL FILPHI(NEWNOZ,NEWM,IEXIT)
IF(SLP1.GE.0.)SLP2=TEGARD
CALL USONIC
MYMESH=MESH-MESH1+1
MYMAX=MESHN-MESH1+1
WRITE(6,4) MYMESH,MYMAX
4  FORMAT(IH0,40X,' END OF CALCULATION ON GRID',I2,' OF ',I2)

```



```

1      CONTINUE
      CALL KEEPER
      STOP
      END
      BLOCK DATA

C      INITIALIZE ALL DATA IN COMMON

      LOGICAL RESTAR, LEONLY
      1 BUG, BUG2, BUG3, SMOOTH, FINEST, ALLOUT
      INTEGER CAMPER
      REAL MINF, LAMDAO
      DOUBLE PRECISION CAPK, CAPKP
      COMMON/MESHES/NOZES(10), MS(10), TOLS(10), NOLD(2)
      COMMON/PARAM/RESTAR, NOZIN, BETA1, BETA2, QINF1, CI, CII, GAMMA, MINF, EM
      1 DELTA, BETA, TOL, BUG, BUG2, BUG3, IF, GUESS, OVERREL, TIMER, NOWREL, NOTYET
      1 DAMP, SUPREL, S, WAKE, B2OB1, UNDERL, RADRAT, RADLE, OMEGA, FLOCO, VAXIAL
      1 ALLOUT, KKMAX
      COMMON/QUASI/R(100,30), B(100,30)
      COMMON/ENTIRE/ X(100,30), Y(100,30), PHI(100,30), DELPSV(100,30)
      COMMON/GEOM2/ZETA(100), ETA(100)
      COMMON/GEOM/NEWNOZ, NEWM, RLE, RTE, A, CHORD, XUPS, XDNS, LAMDAO, CC, CAPK,
      1 CAPKP, PI, RNK, VB, KN, NED, BB, DOSURF, RFAC, SOLID, MPLS
      1 STABAC, SLP1, SLP2, SLP3, SLP4, SMOOTH, CHOP, THETI, THETL
      1 FINEST, LEONLY, CAMPER

      COMMON/CALVEL/D55(55), PRIORS(14,30), INDEX(100,30), IINDEX(32),
      1 FAKEU(100), FAKEV(100), ICOUNT, IDEX, AMY, AMZ

      DATA RADRAT/1./, WAKE, B2OB1/0., 1./, R, B/6000*1./
      DATA RADLE/1./, OVEREL/1.5/, TOL/.001/
      1 PI/3.14159265/, TIMER/1./
      1 OMEGA, FLOCO, VAXIAL/0., 999., 0./
      1 SUPREL/1./, CHOP/.99/, THETI, THETL/0., 0./, CAMPER/6/, EM/10./
      DATA NOTYET/2/, DAMP/1./, STABAC, SLP1, SLP2, SLP3, SLP4, SMOOTH/.999,
      1 1., 2., 2*1., .FALSE./, UNDERL/1./, LEONLY/.FALSE./, FINEST/.FALSE./
      DATA A/1.5/, CII/.2/, CI/1./, GUESS/10./, IT/10/, ALLOUT/.FALSE./
      DATA KKMAX/300/
      DATA DELTA, BETA, QINF1, BUG, RESTAR, GAMMA/3*1., .FALSE., .FALSE., 1.4/

      DATA IINDEX, IINDEX/203*0, 1, 98*0, 2, 1, 96*0, 2, 2, 4, 1, 96*0, 1, 1, 1, 2497*0,
      1 2, 8, 2, 8, 1, 1, 8, 3, 3, 1, 1, 1, 8, 2, 8, 1, 1, 8, 3, 3, 3, 1, 1, 1, 8, 2, 8, 2, 8,
      END

```


QSO01450
QSO01460
QSO01470
QSO01480
QSO01490
QSO01500
QSO01510
QSO01520
QSO01530
QSO01540
QSO01550
QSO01560
QSO01570
QSO01580
QSO01590
QSO01600
QSO01610
QSO01620
QSO01630
QSO01640
QSO01650
QSO01660
QSO01670
QSO01680
QSO01690
QSO01700
QSO01710
QSO01720
QSO01730
QSO01740
QSO01750
QSO01760
QSO01770
QSO01780
QSO01790
QSO01800
QSO01810
QSO01820
QSO01830
QSO01840
QSO01850
QSO01860
QSO01870
QSO01880
QSO01890
QSO01900
QSO01910
QSO01920

```

SUBROUTINE WHEEL(LAMDAO,NEWM,NEW2M1,NOFLOW)
C   ROTATE X,Y COORDINATES THRU AN ANGLE LAMDAO(RADIANS)

LOGICAL NOFLOW
COMMON/ENTIRE/  X(100,30),Y(100,30),PHI(100,30),DELPSV(100,30)
COMMON/GEOM2/ZETA(100),ETA(100)
REAL LAMDAO
COMPLEX H,A,I
DATA AI/(0.,1.) /
NEW2M=NEW2M1-1
MM3=NEWM-3
NNQZ=(NEW2M+1)/2
NEW2M2=NEW2M1+1
DO 1 I=1,NEW2M2
DO 1 J=1,NEWM
H=CMPLX(X(I,J),Y(I,J))*CEXP(AI*LAMDAO)
X(I,J)=REAL(H)
Y(I,J)=AIMAG(H)
IF(.NOT.NOFLOW) RETURN
WRITE(6,10)
FORMAT(1H1,30X,' GRID OUTPUT POINTS ON BLADE SURFACE, CHORD ',
1,AT STAGGER ANGLE',//42X,' I X
DO 2 I=1,NEW2M2
IIM=I-1
WRITE(6,14) IIM,X(I,NEWM),Y(I,NEWM)
FORMAT(41X,14,2E13.5)
RETURN
END
SUBROUTINE FILPHI(NEWNOZ,NEWM,NEW2M1)
C   BASED ON PHI ARRAY FROM PREVIOUS GRID, INTERPOLATES VALUES
C   TO FILL THE INITIAL PHI ARRAY FOR NEXT, FINER GRID.

INTEGER OLDNOZ,OLDM
LOGICAL RESTAR
COMMON/ENTIRE/  X(100,30),Y(100,30),PHI(100,30),TOPHI(100,30)
COMMON/MESHES/ NOZES(10),MS(10),TOLS(10),NOLD(2)
COMMON/GEOM2/ ZNEW(100),ENEW(100)
COMMON/CALVEL/FAKEFI(4,6),FAKFI(4,6),RHOCN,QLIM,EXPO,ROTATN,
1ROTROT,IM1,IEEXIT,PRIORS(14,30),INDEX(100,30),IINDEX(32),FAKEU(75)
1,FAKEV(75),ICOUNT,INDEX
COMMON/PARAM/ RESTAR
DIMENSION OLDE(100),OLDZ(100)

```


Q5001930
Q5001940
Q5001950
Q5001960
Q5001970
Q5001980
Q5001990
Q5002000
Q5002010
Q5002020
Q5002030
Q5002040
Q5002050
Q5002060
Q5002070
Q5002080
Q5002090
Q5002100
Q5002110
Q5002120
Q5002130
Q5002140
Q5002150
Q5002160
Q5002170
Q5002180
Q5002190
Q5002200
Q5002210
Q5002220
Q5002230
Q5002240
Q5002250
Q5002260
Q5002270
Q5002280
Q5002290
Q5002300
Q5002310
Q5002320
Q5002330
Q5002340
Q5002350
Q5002360
Q5002370
Q5002380
Q5002390
Q5002400

```

OLDNOZ=NOLD(1)
OLDM=NOLD(2)
NZOLD=OLDNOZ/2+1
INDEX(OLDNOZ-2,3)=0
INDEX(OLDNOZ-2,4)=0
INDEX(OLDNOZ-2,5)=0
INDEX(OLDNOZ-2,6)=0
INDEX(OLDNOZ-1,5)=0
INDEX(OLDNOZ-1,6)=0
INDEX(OLDNOZ,5)=0
INDEX(OLDNOZ,6)=0
INDEX(NZOLD-2,3)=0
INDEX(NZOLD-2,4)=0
INDEX(NZOLD-2,5)=0
INDEX(NZOLD-2,6)=0
INDEX(NZOLD-1,5)=0
INDEX(NZOLD-1,6)=0
INDEX(NZOLD,5)=0
INDEX(NZOLD,6)=0
INDEX(NZOLD+1,4)=0
INDEX(NZOLD+1,5)=0
INDEX(NZOLD+1,6)=0
INDEX(NZOLD+2,3)=0
INDEX(NZOLD+2,4)=0
INDEX(NZOLD+2,5)=0
DO 13 I1=1,NEW2M1
DO 13 J1=1,NEWM
TOPHI(I1,J1)=0.
REWIND 8

```

13

```

IF(RESTAR)GOTO10
READ(18) OLDE,OLDZ
DO 1 I1=1,NEW2M1
DO 2 I2=1,OLDNOZ
IF(OLDE(I2).GT.ENEW(I1)) GOTO3
CONTINUE
I2=OLDNOZ
DO 1 I3=1,NEWM
DO 5 I4=1,OLDM
IF(OLDZ(I4).GT.ZNEW(I3))GOTO6
CONTINUE
I4=OLDM
FACE=(ENEW(I1)-OLDE(I2-1))/(OLDE(I2)-OLDE(I2-1))
TERP3=
1 PHI(I2-1,I4)+(PHI(I2,I4)-PHI(I2-1,I4))*FACE

```

2

3

5

6


```

1  TERPI=
   1 PHI(I2-1,I4-1)+(PHI(I2,I4-1)-PHI(I2-1,I4-1))*FACE
   8 OP=(TERP3-TERP1)/(OLDZ(I4)-OLDZ(I4-1))*(ZNEW(I3)-
   1 OLDZ(I4-1))+TERP1
   TOPHI(I1,I3)=BOP
QSO02410
QSO02420
QSO02430
QSO02440
QSO02450
QSO02460
QSO02470
QSO02480
QSO02490
QSO02500
QSO02510
QSO02520
QSO02530
QSO02540
QSO02550
QSO02560
QSO02570
QSO02580
QSO02590
QSO02600
QSO02610
QSO02620
QSO02630
QSO02640
QSO02650
QSO02660
QSO02670
QSO02680
QSO02690
QSO02700
QSO02710
QSO02720
QSO02730
QSO02740
QSO02750
QSO02760
QSO02770
QSO02780
QSO02790
QSO02800
QSO02810
QSO02820
QSO02830
QSO02840
QSO02850
QSO02860
QSO02870
QSO02880

7  DO 7 I1=1,NEW2M1
   DO 7 I3=1,NEWM
   PHI(I1,I3)=TOPHI(I1,I3)
QSO02410
QSO02420
QSO02430
QSO02440
QSO02450
QSO02460
QSO02470
QSO02480
QSO02490
QSO02500
QSO02510
QSO02520
QSO02530
QSO02540
QSO02550
QSO02560
QSO02570
QSO02580
QSO02590
QSO02600
QSO02610
QSO02620
QSO02630
QSO02640
QSO02650
QSO02660
QSO02670
QSO02680
QSO02690
QSO02700
QSO02710
QSO02720
QSO02730
QSO02740
QSO02750
QSO02760
QSO02770
QSO02780
QSO02790
QSO02800
QSO02810
QSO02820
QSO02830
QSO02840
QSO02850
QSO02860
QSO02870
QSO02880

1313  FORMAT(4I6,4E13.5)
      FORMAT(1H,8E13.5)
      WRITE(8,11) PHI
      DO 1313 I1=1,NEW2M1
      DO 1313 J1=1,NEWM
      TOPHI(I1,J1)=0.
      RETURN
C      IF RESTART, READ PHI FROM THE RESTART FILE
10     READ(9,11) PHI
11     FORMAT(6E13.5)
      RESTART=.FALSE.
      REWIND 9
      RETURN
12     END
      SUBROUTINE RBIN(NSTRM,LAMDAO)
C      FOR QUASI3D CASES, READS UNIT 2 WITH DISTRIBUTIONS OF SPANWISE RADIUS
C      AND CHANNEL THICKNESS. FORMAT IS THE SAME AS PROGRAM TSONIC.
      REAL LAMDAO
      COMMON/MERIDL/ ZMSP(50,2),THSP(50,2),RMSP(50),
1 BESP(50),RM(50),NRSP,NRSP(2),RTE(2),RLE(2),STGRF,CHO,CNBL,DM
      DIMENSION DUM1(50),R(2)
      REWIND 2
      ISTRM=IABS(NSTRM)
      DO 1 I=1,ISTRM
      READ(2,3)
      READ(2,3)
      READ(2,6) A1,A2,CHO,STGRF
      READ(2,3)
      FORMAT(1H)
      READ(2,4) NBL,NRSP,I1,I2,I3
      CNBL=FLOAT(NBL)
      FORMAT(30X,I5,4I5)
      DO 10 J=1,2
QSO02410
QSO02420
QSO02430
QSO02440
QSO02450
QSO02460
QSO02470
QSO02480
QSO02490
QSO02500
QSO02510
QSO02520
QSO02530
QSO02540
QSO02550
QSO02560
QSO02570
QSO02580
QSO02590
QSO02600
QSO02610
QSO02620
QSO02630
QSO02640
QSO02650
QSO02660
QSO02670
QSO02680
QSO02690
QSO02700
QSO02710
QSO02720
QSO02730
QSO02740
QSO02750
QSO02760
QSO02770
QSO02780
QSO02790
QSO02800
QSO02810
QSO02820
QSO02830
QSO02840
QSO02850
QSO02860
QSO02870
QSO02880

```



```

      READ(2,5) RI,RO,SPLN01
      ISPL1=SPLN01
      WRITE(6,4) I,NRSP,J,ISPL1
      NSP(J)=ISPL1
      RTE(J)=RO
      RLE(J)=RI
      FORMAT(2F10.5,20X,F10.5)
      FORMAT(8F10.6)
      READ(2,6) (ZMSP(IA,J),IA=1,ISPL1)
      READ(2,6) (THSP(IA,J),IA=1,ISPL1)
10
C    READ X VALUES
      READ(2,6) (RM(IA),IA=1,NRSP)
C
      READ CORRESPONDING SPANWISE RADIUS VALUES.
      READ(2,6) (RMSP(IA),IA=1,NRSP)
C
      READ STREAMCHANNEL THICKNESS VALUES.
      READ(2,6) (BESP(IA),IA=1,NRSP)
      IF(I1.EQ.1) READ(2,6) (DUM1(IA),IA=1,NRSP)
      IF(I2.EQ.1) READ(2,6) (DUM1(IA),IA=1,NRSP)
1    READ(2,4) I4
      IF(NSTRM.LT.0) RETURN
C
      TRANSLATE ORIGIN OF X VALUES TO MIDCHORD AND NORMALIZE RADIUS AND
      THICKNESS TO THE AERODYNAMIC CHORD.
      DO 7 I=1,NRSP
      RM(I)=(RM(I)-CHO/2.)/CHO*COS(LAMDA0)
      RMSP(I)=RMSP(I)/CHO*COS(LAMDA0)
      BESP(I)=BESP(I)/CHO*COS(LAMDA0)
7
      RETURN
      END
      SUBROUTINE FILLRB(NEWM,NEW2M1,RADLE,STAG)
C
C    INTERPOLATES ON THE INPUT (OR ASSUMED LINEAR) DISTRIBUTIONS OF RADIUS
C    AND THICKNESS TO FILL ARRAYS OF SPANWISE POSITION AND STREAMCHANNEL
C    THICKNESS AT ALL GRID POINTS.
C
C        IF RADLE=1., RADIUS IS ASSUMED CONSTANT

```



```

COMMON/QUASI/R(100,30),B(100,30)
COMMON/MERIDL/ ZMSP(50,2),THSP(50,2),RMSP(50),
1 BESP(50),RM(50),NRSP,NRP(2),RTE(2),RLE(2),STGRF,CHO,CNBL,DUMM
COMMON/ENTIRE/ X(100,30),Y(100,30),PHI(100,30),DELP(100,30)
COMMON/PARAM/ RESTAR,NOZIN,BRM(17),USELER,BR(6),B2OB1,UNDERL,R2ORI
NEW2M2=NEW2M1+1
N=NRSP
CO=COS(STAG)/2.
C
NOZIN=NEW2M1/2 ON THE FIRST PASS ONLY
IF(NOZIN.EQ.NEW2M1/2)FIXR=RADLE
IF(NOZIN.EQ.NEW2M1/2)B21SAV=B2OB1
IF(RADLE.NE.1..AND.R2ORI.EQ.1.)R2ORI=RMSP(NRSP)/RMSP(1)
IF(B2OB1.EQ.1.)B2OB1=BESP(NRSP)/BESP(1)
IF(B21SAV.NE.1..OR.NOZIN.NE.NEW2M1/2..OR.USELER.EQ.0..OR.RADLE.EQ.1
*)GOTO15
C
FIND L.E. OF BLADE (RM+CO=0.)
DO 13 I5=1,NRSP
IF(RM(I5)+CO.GT.0.)GOTO14
CONTINUE
I5=NRSP
C
CALCULATE SPANWISE POSITION AT L.E. (FIXR) FROM THE GIVEN RADIUS
DISTRIBUTION.
FIXR=
14 RMSP(I5-1)-(RMSP(I5)-RMSP(I5-1))*(CO+RM(I5-1))/(RM(I5)-RM(I5-1))
C
DO 1 I1=1,NEW2M2
DO 1 I3=1,NEWM
IF(B21SAV.NE.1.)GOTO12
DO 2 I2=1,NRSP
IF(RM(I2).GT.X(I1,I3))GOTO3
CONTINUE
I2=NRSP
2
3 IF(I2.EQ.1)I2=2
FACE=(X(I1,I3)-RM(I2-1))/(RM(I2)-RM(I2-1))
TERPR=RMSP(I2-1)+(RMSP(I2)-RMSP(I2-1))*FACE
C
IF(RM(NRSP).LT.X(I1,I3))TERPR=RMSP(NRSP)
IF(RM(1).GT.X(I1,I3))TERPR=RMSP(1)
TERPB=BESP(I2-1)+(BESP(I2)-BESP(I2-1))*FACE
IF(RADLE.NE.1.)R(I1,I3)=TERPR
QSO03370
QSO03380
QSO03390
QSO03400
QSO03410
QSO03420
QSO03430
QSO03440
QSO03450
QSO03460
QSO03470
QSO03480
QSO03490
QSO03500
QSO03510
QSO03520
QSO03530
QSO03540
QSO03550
QSO03560
QSO03570
QSO03580
QSO03590
QSO03600
QSO03610
QSO03620
QSO03630
QSO03640
QSO03650
QSO03660
QSO03670
QSO03680
QSO03690
QSO03700
QSO03710
QSO03720
QSO03730
QSO03740
QSO03750
QSO03760
QSO03770
QSO03780
QSO03790
QSO03800
QSO03810
QSO03820
QSO03830
QSO03840

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      B(I1,I3)=TERPB/BESP(I1)
      GOTO 10
C    IF (B21SAV.NE.1), A LINEAR DISTRIBUTION OF THICKNESS IS ASSUMED OVER
C    3 CHORD LENGTHS.
12    B(I1,I3)=1.+(B20B1-1.)*(X(I1,I3)+1.5)/3.
      IF(RADLE.NE.1.)FIXR=(1.+(R20R1-1.)*(1.5-CO)/3.)*RADLE
      IF(X(I1,I3).LT.-1.5)B(I1,I3)=1.
      IF(X(I1,I3).GT.1.5)B(I1,I3)=B20B1
      IF(RADLE.NE.1.)R(I1,I3)=(1.+(R20R1-1.)*(X(I1,I3)+1.5)/3.)*RADLE
      IF(X(I1,I3).LT.-1.5)R(I1,I3)=RADLE
      IF(X(I1,I3).GT.1.5)R(I1,I3)=R20R1*RADLE
C    SCALE THE TANGENTIAL COORDINATE Y (R*THETA), TO THE LOCAL RADIUS.
C10   Y(I1,I3)=Y(I1,I3)*R(I1,I3)/FIXR
10    CONTINUE
1    CONTINUE
      USELER=FIXR
      RETURN
      FORMAT(2I5,6E10.4)
      END
      SUBROUTINE USONIC
C
C    FULL POTENTIAL FLOW SOLVER
C    FOR CASCADE GEOMETRIES
C
C    ETA = COMPUTATIONAL COORDINATE THAT IS CONSTANT ON LINES
C          RADIATING FROM BLADE
C    ZETA = COMPUTATIONAL COORDINATE THAT IS CONSTANT ON LINES
C           SURROUNDING THE BLADE
C    (THESE ARE REVERSED FROM INTERPOLATION GRID GENERATOR)
C
C    DO (INPUT SPECIFICATION)
C    DO (INITIALIZATION OF FIELD VARIABLES)
      RELAXD=.FALSE.
      DO UNTIL (RELAXD)
        KK=KK+1
        KKK=KKK+1
        IF(KK.GT.NOWREL) OVEREL=REL SAV
        IF(KK.GT.NOTYET) SUPREL=SUP SAV
      END DO

```



```

DO UNTIL (EXIT)
  I=I+1
  IM1= I-1
  IF (IM1.EQ.0) IM1=2
  DO (AXIAL LOCATION INDICATORS)
  DO UNTIL (TOP)
    J=J+1
    JM1=J-1
    IF (JM1.EQ.0) JM1=2
    DO (VERTICAL LOCATION INDICATORS)
    DO (BOUNDARY CONDITION SWITCHES)
    DO (GEOMETRY ADVANCE)
    DO (FIELD GRADIENTS)
    DO (VELOCITIES AND DENSITIES)
    DO (SUPERSONIC CORRECTION)
    DO ( T,S,Q'S AND RESIDUALS)
    DO ( DELPHI COEFFICIENTS AND TRANSPOSED TERMS)
  END
  DO (FORWARD ELIMINATION)
  IF (I.NE.1)
    1 DO (BACK SUBSTITUTION)
  J=0
  END
  DO (UPDATE OF FIELD VARIABLES)
  DO (CONVERGENCE TESTS)
  I=0
  END
  DO (SURFACE FLOW CALCULATION FOR FINISHED GRID)
  RETURN
  ENTRY KEEPER
  DO (OUTPUT OF PHI AND CALCULATION OF FINAL VELOCITY FIELD)
  RETURN

  LOGICAL INLET, BLADE, EXIT, BOTTOM, TOP,
  1 RELAXD, SETTLE, BUG, BUG3, BUG2
  LOGICAL DOSURF, SMOOTH, H, FINEST, RESTAR, ALLOUT
  REAL LAB, LAD, MINF, LENGTH, JACOB, LAMDAO
  REAL MACH(8)
  INTEGER FIRSTJ
  DOUBLE PRECISION CAPK, CAPKP
  COMMON/PARAM/RESTAR, NOZIN, BETA1, BETA2, QINF1, CI, CII, GAMMA, MINF, EM
  1 DELTA, BETA, TOL, BUG, BUG2, BUG3, IT, GUESS, OVEREL, FIXR, NOWREL, NOTYET
  1 DAMP, SUPREL, S, WAKE, B2OB1, UNDERL, RADRA1, RADLE, OMEGA, FLOCO, VAXIAL,
  1 ALLOUT, KKMAX
  COMMON/QUASI/ RADIUS(100,30), HEIGHT(100,30)
  COMMON/ENTIRE/ X(100,30), Y(100,30), PHI(100,30), DELPSV(100,30)

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CC


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COMMON/GEOM2/ZETA(100),ETA(100)
COMMON/CROSS/ ZMACH(100,30)
COMMON/GEOM/NOZ,M,RLE,RTE,A,CHORD,XUPS,XDNS,LAMDAO,CC,CAPK,
1CAPK,PI
1,CRNK,VB,KN,NED,BB,DOSURF,RFAC,SOLID,MPLS
1,STABAC,SLP1,SLP2,SLP3,SLP4,SMOOTH,CHOP,THETT,THETL
1,FINEST
COMMON/CALVEL/FAKEFI(4,6),FAKFI(4,6),RHOCON,QLIM,EXPO,ROTAIN,
1ROTROT,IM1,IEXIT,PRIORS(14,30),INDEX(100,30),IINDEX(32),FAKEU(100)
1,FAKEV(100),ICOUNT,INDEX,AMY,AMZ
COMMON/VELOUT/D(100),E(100),F(100),DELPHI(100),TENOLF(100,30),
1DUMRX(100,30),DUMBY(100,30),BQPR,FADBOP,XOCX,KK
1DIMENSION RHOS(8), FI1(8),FI2(3),FI3(3),FI9(8),SPAN(8),
1EMACH(100,30)
2,COSX(8),COSY(8),LENGTH(8),DEDX(8),DZDX(8),DEDY(8),
3DZDY(8),T(8),DPHIDZ(8),DPHIDE(8),U(8),V(8),UN(8),RHO(8),
4RHOUL(8),ONOFF(8),DELPML(3)
5,HITE(8)
NAMELIST/ABSLUT/MINF,MINF2,QINF2,ABETA1,ABETA2,AQINF1,AQINF2,AMINF
1,AEM,ROTATN
NAMELIST/PARAMS/ IEXIT,NOZ,M,BETA1,BETA2,LAMDAO
1,S,CHORD,RLE,RTE,NED,KN
1,STABAC,SLP1,SLP2,SLP3,SLP4,CHOP,THETT,THETL
1,QINF1,C1,C11,GAMMA,MINF,EM,DELTA,BETA,WAKE,B2OB1,RADRAT
1,QMEGA,FLOCC,VAXIAL
1,TOL,BUG,IT,GUESS,OVEREL, SUPREL,NOWREL,NOTYET,DAMP,
1SMOOTH,FINEST,BUG,BUG2,BUG3
NAMELIST/YTESD/ KK,AIJ,AIJM1,AIJPL, TRANSP,I,J,CIRCO
NAMELIST/CONST/CIRCLN,MINF2,B2OB1,R2OR1,RINF,RATLE
DATA AQINF1/1.,AVGFAC,TEST/1.,1./

COMMON/HIBALL/ SUPERG(46,30,100)
XDIF(A,B,C,D)=.5*(A+B-C-D)

C DO (INPUT SPECIFICATION)
C PROCEDURE (INPUT SPECIFICATION)
C IF(NOZ-1.NE.NOZIN) GOTO 201
C IF(NOZ-1.EQ.NOZIN) THEN

```

```

QSO04810
QSO04820
QSO04830
QSO04840
QSO04850
QSO04860
QSO04870
QSO04880
QSO04890
QSO04900
QSO04910
QSO04920
QSO04930
QSO04940
QSO04950
QSO04960
QSO04970
QSO04980
QSO04990
QSO05000
QSO05010
QSO05020
QSO05030
QSO05040
QSO05050
QSO05060
QSO05070
QSO05080
QSO05090
QSO05100
QSO05110
QSO05120
QSO05130
QSO05140
QSO05150
QSO05160
QSO05170
QSO05180
QSO05190
QSO05200
QSO05210
QSO05220
QSO05230
QSO05240
QSO05250
QSO05260
QSO05270
QSO05280

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```

RELSAV=OVEREL
UNDSAV=UNDERL
SUPSAV=SUPREL
SHIFTM=ABS(CI)
IF(RADRAT.EQ.1.)RADLE=1.
IF(RADRAT.EQ.1.)FIXR=1.
IF(SHIFTM.EQ.0.)SHIFTM=1.
IF(FLOCO.EQ.999.)AND.OMEGA.NE.0.)
1FLOCO=VAXIAL/OMEGA/RADLE
IF(FIXR.LT.1.E-06)FIXR=1.
ROTATN=COS(BETA1+LAMDAO)/FLOCO
IF(OMEGA.EQ.0.)AND.FLOCO.EQ.999.)ROTATN=0.
ROTROT=ROTATN**2
BEETA1=(BETA1+LAMDAO)
BEETA2=(BETA2+LAMDAO)

C DO (EXIT MACH NUMBER ITERATION)
C PROCEDURE (EXIT MACH NUMBER ITERATION)
FAB=(GAMMA-1.)/2.
ROT FAC=ROTROT*(RADRAT**2-1.)
IF(EM.NE.10.)GOTO205
IF(EM.EQ.10.)THEN
PIOP2=1./(RADRAT-WAKE/S)
SETTLE=.FALSE.
IF(MINF.GT.0.)EM=MINF*.8
IF(MINF.LT.0.)EM=1.0+ABS(MINF)
MINF=ABS(MINF)
FAC1=1./((1.+FAB*MINF*MINF*(1.+ROTFAC)))
FAC1=FAC1*((GAMMA+1.)/4./FAB)*COS(BEETA1)/COS(BEETA2)/B20B1
1*PIOP2*MINF+FAB*EM*EM)
FAC2=1./((1.+FAB*EM*EM)
FAC3=FAC2*((GAMMA+1.)/4./FAB)
EFF=EM*FAC3-FAC1
DFDM=FAC3*(1.-FAC2*EM*EM*(GAMMA+1.)/2.)
DM=EFF/DFDM
SETTLE=ABS(DM)/EM.LT..001
EM=EM+DM
IF(.NOT.SETTLE)GOTO208
END
MINF2=EM
MINF=ABS(MINF)
QINF2=SQRT((1.+ROT FAC+1./FAB/MINF/MINF)/(1.+1./FAB/EM/EM))
AQINF2=QINF2
ABETA2=BEETA2*180./PI

```



```

C
ABETA1=BEETA1*180./PI
IF(ROTATN.EQ.0.) GOTO210
IF(ROTATN.NE.0.) THEN
SINBET=SIN(BEETA1)+ROTATN
COSBET=COS(BEETA1)
ABETA1=ATAN2(SINBET,COSBET)*180./PI
SINBET=QINF2*SIN(BEETA2)+ROTATN*RAD RAT
COSBET=QINF2*COS(BEETA2)
ABETA2=ATAN2(SINBET,COSBET)*180./PI
AQINF1=COS(BEETA1)/COS(PI/180.*ABETA1)
AQINF2=QINF2*COS(BEETA2)/COS(PI/180.*ABETA2)
AMINF=MINF*COS(BEETA1)/COS(PI/180.*ABETA1)
AMEM=EM*COS(BEETA2)/COS(ABETA2*PI/180.)
WRITE(6,779)
779 FORMAT(1,ROTATION EFFECTS INCLUDED,ABSOLUTE AND RELATIVE VELOCITY,
1,TRIANGLES HAVE -)
WRITE(6,ABSLUT)
BETA1=ABETA1*PI/180.-LAMDAO
BETA2=ABETA2*PI/180.-LAMDAO
END
C
210 P1OP2=1./RAD RAT
CIRCO=RADLE/FIXR*S*(AQINF1*SIN(LAMDAO+BETA1)-AQINF2*SIN(LAMDAO+
1BETA2)/P1OP2)
CIRCOO=CIRCO
IF(CIRCO.EQ.0.)CIRCOO=1.
CIRCLN=CIRCO
R2OR1=RAD RAT
RINF=RADLE
RATLE=FIXR
WRITE(6,780)
780 FORMAT(1,CALCULATED FLOW PARAMETERS')
WRITE(6,CONST)
END
C
C
201 IF(NOZ-1.NE.NOZIN)SUPSAV=SUPSAV-C11
IF(SUPSAV.LT..5)SUPSAV=.5
OVEREL=1.
UNDEREL=1.
SUPREL=1.
NZZ=2*NOZ-2
KKK=0
IEXIT=NZZ
I67=M-14+1
I67=MAX0(I67,1)
FORMAT(6E13.5)
2

```



```

122 CORB=COS(LAMDAO+BETA1)*AQINF1*RADLE
COSB=COS(LAMDAO+BETA1)*AQINF1
SINB = SIN(LAMDAO+BETA1)*AQINF1*RADLE
SINB = SIN(LAMDAO+BETA1)*AQINF1
IF(RESTAR.OR.NOZ-1.NE.NOZIN)GOTO219
IEXP1=IEXIT+1
BBLR=BEETA1+BEETA2+LAMDAO+ROTATN
DO 135 I=1,IEXP1
DO 134 J=1,M
PHI(I,J)=COSB*X(I,J)+SINB*Y(I,J)*RADLE
IF(ROTATN.NE.0.)PHI(I,J)=PHI(I,J)*RADLE
RDDDD=RADLE/HEIGHT(I,J)/RADIUS(I,J)
IF(BBLR.EQ.0.)PHI(I,J)=PHI(I,J)*RDDDD
CONTINUE
CONTINUE
NOZM1=NOZ-1
NOZP1=NOZ+1
DO 141 I=NOZM1,NOZP1
DO 140 J=3,5
PHI(I,J)=COSB*X(I,J)+SINB*Y(I,J)*RADLE
IF(ROTATN.NE.0.)PHI(I,J)=PHI(I,J)*RADLE
RDDDD=RADLE/HEIGHT(I,J)/RADIUS(I,J)
IF(BBLR.EQ.0.)PHI(I,J)=PHI(I,J)*RDDDD
CONTINUE
CONTINUE
DO 153 J=1,6
DO 152 I=1,4
I10=IEXIT+I-3
IF(J.LE.5.AND.J.GT.2.AND.
1(NOZ-1.NE.NOZIN.OR.RESTAR)
1.AND.I1.NE.4)PHI(I1,J)=(COSB*X(I1,J)+SINB*Y(I1,J))
1
IF(ROTATN.NE.0.)PHI(I1,J)=PHI(I1,J)*RADLE
RDDDD=RADLE/HEIGHT(I1,J)/RADIUS(I1,J)
IF(BBLR.EQ.0.)PHI(I1,J)=PHI(I1,J)*RDDDD
IF(J.LE.5.AND.J.GT.2.AND.
1(NOZ-1.NE.NOZIN.OR.RESTAR)
1.AND.I10.GT.IEXIT-2)PHI(I10,J)=(COSB*X(I10,J)+SINB*Y(I10,J))
1
IF(ROTATN.NE.0.)PHI(I10,J)=PHI(I10,J)*RADLE
RDDDD=RADLE/HEIGHT(I10,J)/RADIUS(I10,J)
IF(BBLR.EQ.0.)PHI(I10,J)=PHI(I10,J)*RDDDD
CONTINUE
CONTINUE
DO 161 J=1,M
PHI(I,J)=
1 PHI(IEXIT-1,J)-RADLE/FIXR*S*(AQINF1*SIN(LAMDAO+BETA1)-AQINF2*SIN(
1 LAMDAO+BETA2)/PIOP2)

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212

134
135
219

140
141

152
153


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161      PHI(IEXIT+1,J)=PHI(3,J)+
1      RADLE/FIXR*S*(AQINF1*SIN(LAMDAO+BETA1)-AQINF2*SIN(LAMDAO+
1      BETA2)/PIOP2)
      I=0
      J=0
      RHOCN=(GAMMA-1.)/2.*MINF*MINF
      EXPO=1./(GAMMA-1.)
      QLIIM=1.+1./RHOCN
      BMZ=1./MINF/MINF
      BMY=(GAMMA-2.)/2.
      AMZ=.5/BMZ
      BMX=8*MY*AMZ/2.
      AMY=-BMX/BMZ
      BIGK=RADLE/FIXR*COS(BEETA1)
      UOOUT=AQINF2*COS(ABETA2*PI/180.)
      DPHTHO=AQINF2*SIN(ABETA2*PI/180.)*RADRAT*RADLE/FIXR
      UOIN=AQINF1*COS(ABETA1*PI/180.)
      DPHTHI=AQINF1*SIN(ABETA1*PI/180.)*RADLE/FIXR
      INDEX(NZ-2,3)=3
      INDEX(NZ-2,4)=3
      INDEX(NZ-2,5)=3
      INDEX(NZ-2,6)=1
      INDEX(NZ-1,5)=2
      INDEX(NZ-1,6)=1
      INDEX(NZ,5)=2
      INDEX(NZ,6)=1
      INDEX(NZ+1,4)=2
      INDEX(NZ+1,5)=4
      INDEX(NZ+1,6)=1
      INDEX(NZ+2,3)=1
      INDEX(NZ+2,4)=1
      INDEX(NZ+2,5)=1
      INDEX(IEXIT-2,3)=3
      INDEX(IEXIT-2,4)=3
      INDEX(IEXIT-2,5)=3
      INDEX(IEXIT-2,6)=1
      INDEX(IEXIT-1,5)=2
      INDEX(IEXIT-1,6)=1
      INDEX(IEXIT,5)=2
      INDEX(IEXIT,6)=1
      IF(B2OB1*RADLE.EQ.1.)GOTO 2691
      FOR QUASI - 3D CASES, ADJUST CHANNEL AREA AT FARFIELD ELEMENTS WHERE
      C IT DROPS BELOW SONIC THROAT AREA BASED ON THE INPUT DISTRIBUTIONS.
      DO 162 J1=1,IEXPI
      DO 162 J1=1,M

```



```

1622 IF (INDEX(I1,J1),EQ,0)GOTO1622
      ROTFAC=ROTR0T*(1/RADIUS(I1,J1)/RADLE)**2-1.)*1.
      IF (I1.LE.NOZ-3.OR.I1.GE.NOZ+3)GOTO1622
      ASTAR=MINF*COS(BEETA1)/(ROTFAC*MINF*MINF*FAB+1.)*((GAMMA+1.)/4.
1/FAB)*RADLE*((1.+MINF*MINF*SIN(BEETA1)**2)*FAB+1.)*((GAMMA+1.)/4.
11/FAB)
      WMACH=MINF
      GOTO1623
      ASTAR=EM*COS(BEETA2)/(ROTFAC*EM*EM*FAB+1.)*((GAMMA+1.)/4.
1/FAB)*RADLE*((1.+EM*EM*SIN(BEETA2)**2)*FAB+1.)*((GAMMA+1.)/4.
11/FAB)*RADRAT*82081
      WMACH=EM
1623 IF (ASTAR.LE.RADIUS(I1,J1)*HEIGHT(I1,J1))GOTO1622
      WRITE(6,1666) I1,J1,X(I1,J1),WMACH,ASTAR
1666 FORMAT('QUASI-3D CHANNEL CROSSSECTION AT BOUNDARY ELEMENT I = ',I3
1,J = ',I3,X = ',E13.5,' FALLS BELOW SONIC THROAT AREA./
1,BASED ON MACH= ',F7.4,' AT FAR FIELD STATION.'
1,' PROCEEDING WITH AREA = 1.01 * THROAT = 1.01 * ',E12.5)
      RRR=ASTAR/HEIGHT(I1,J1)
      IF (RADLE.NE.1..AND.82081.NE.1.)RADIUS(I1,J1)=(RRR+RADIUS(I1,J1))/2
      IF (RADLE.NE.1..AND.82081.NE.1.)HEIGHT(I1,J1)=ASTAR*1.01/RADIUS(I1,
      IF (82081.NE.1..AND.RADLE.EQ.1.)HEIGHT(I1,J1)=1.01*ASTAR
      IF (82081.EQ.1..AND.RADLE.NE.1.)RADIUS(I1,J1)=ASTAR*1.01
      HEIGHT(I1,J1)=ASTAR*1.01/RADIUS(I1,J1)
      CONTINUE
1623 END
      RELAXD= .FALSE.
2691 KK=KK+1
269 IDEX=1
      ICOUNT=0
      KKK=KKK+1
      IF (KK.GT.NOZREL) OVEREL=RELSAV
      IF (KK.GT.NOZREL) SUPREL=SUPSAB
      IF (NOZ-1.NE.NOZIN)
1 UNDERL=UNDSAB+FLOAT(KKK)/FLOAT(NOTYET)*(OVEREL-UNDSAB)
      I=I+1
      IM1= I-1
      IF (IM1.EQ.0) IM1=2
      DO (AXIAL LOCATION INDICATORS)
      C DO (AXIAL LOCATION INDICATORS)
      C
      C PROCEDURE (AXIAL LOCATION INDICATORS)
      INLET=.FALSE.
      EXIT = .FALSE.

```


	IF(I.EQ.1) INLET =.TRUE.	QSO08170
	IF(I.EQ. IEXIT) EXIT=.TRUE.	QSO08180
	END	QSO08190
275	J=J+1	QSO08200
	JM1=J-1	QSO08210
	IF(JM1.FQ.0) JM1=2	QSO08220
		QSO08230
		QSO08240
C	DO (VERTICAL LOCATION INDICATORS)	QSO08250
		QSO08260
C	PROCEDURE (VERTICAL LOCATION INDICATORS)	QSO08270
		QSO08280
	BOTTOM = .FALSE.	QSO08290
	TOP = .FALSE.	QSO08300
	BLADE = .FALSE.	QSO08310
	IF(J.EQ.1) BOTTOM =.TRUE.	QSO08320
	IF(J.EQ.M) TOP =.TRUE.	QSO08330
	BLADE = TOP	QSO08340
C	END	QSO08350
		QSO08360
		QSO08370
C	DO (BOUNDARY CONDITION SWITCHES)	QSO08380
		QSO08390
C	PROCEDURE (BOUNDARY CONDITION SWITCHES)	QSO08400
		QSO08410
		QSO08420
		QSO08430
209	DO 209 I1=1,8	QSO08440
C	ONOFF(I1)=1.	QSO08450
C	IF(INLET) THEN	QSO08460
C	ONOFF(3)= 0.	QSO08470
C	ONOFF(4)= 0.	QSO08480
C	ONOFF(5)= 0.	QSO08490
C	ONOFF(6)= 0.	QSO08500
C	END	QSO08510
C	IF(BOTTOM) THEN	QSO08520
C	ONOFF(5)= 0.	QSO08530
C	ONOFF(6)= 0.	QSO08540
C	ONOFF(7)= 0.	QSO08550
C	ONOFF(8)= 0.	QSO08560
C	END	QSO08570
C	IF(TOP) THEN	QSO08580
C	ONOFF(1)= 0.	QSO08590
C	ONOFF(2)= 0.	QSO08600
C	ONOFF(3)= 0.	QSO08610
C	ONOFF(4)= 0.	QSO08620
	END	QSO08630
	IF(.NOT.INLET.AND..NOT.BOTTOM.AND..NOT.TOP) GOT0235	QSO08640


```

IF(TOP)IS=1
IF(INLET)IS=3
IF(BOTTOM)IS=5
IE=IS+3
DO 2099 I1=IS,IE
ONOFF(I1)=0.
END
2099 C
C
C DO (GEOMETRY ADVANCE)
C
C PROCEDURE (GEOMETRY ADVANCE)
235 HITE(1)=XDIF(HEIGHT(I,J),HEIGHT(I+1,J),0.,0.)
IF(I.EQ.IEXIT)HITE(1)=HEIGHT(I,J)
HITE(2)=XDIF(HEIGHT(I,J),HEIGHT(I+1,J),0.,0.)
HITE(3)=HITE(2)
HITE(8)=HITE(1)
SPAN(1)=XDIF(RADIUS(I,J),RADIUS(I+1,J),0.,0.)
IF(I.EQ.IEXIT)SPAN(1)=RADIUS(I,J)
SPAN(1)=SPAN(1)/FIXR
SPAN(2)=XDIF(RADIUS(I,J),RADIUS(I+1,J),0.,0.)
SPAN(3)=SPAN(2)/FIXR
SPAN(8)=SPAN(1)
T(6) = -T(3)*ONOFF(6)
T(7) = -T(2)*ONOFF(7)
C
C CALCULATE THE METRICS ON THE FIRST ITERATION
C STORE THEM FOR SUBSEQUENT ITERATIONS
IF(KK.GT.2)GOTO237
C
C CALCULATE VELOCITIES AT UP AND DOWNSTREAM BOUNDARY ELEMENTS TO SAT
C MASS FLOW
C INDEX(I,J)>0 POINTS TO BOUNDARY ELEMENTS AFFECTED
IF(INDEX(I,J).EQ.0.OR.KK.GT.1)GOTO2037
ICOUNT=ICOUNT+1
IIS=INDEX(ICOUNT)
IDIF=INDEX(I,J)+IIS-1
DO 9999 I1=IIS,IDIF
I1=I1+1
IF(I1S.EQ.1.AND.I1.EQ.IDIF)I1=8
ROTATX=ROTATN*SPAN(I1)*FIXR/RADLE
BIGKH=BIGK/HITE(I1)/SPAN(I1)

```

QSO08650
QSO08660
QSO08670
QSO08680
QSO08690
QSO08700
QSO08710
QSO08720
QSO08730
QSO08740
QSO08750
QSO08760
QSO08770
QSO08780
QSO08790
QSO08800
QSO08810
QSO08820
QSO08830
QSO08840
QSO08850
QSO08860
QSO08870
QSO08880
QSO08890
QSO08900
QSO08910
QSO08920
QSO08930
QSO08940
QSO08950
QSO08960
QSO08970
QSO08980
QSO08990
QSO09000
QSO09010
QSO09020
QSO09030
QSO09040
QSO09050
QSO09060
QSO09070
QSO09080
QSO09090
QSO09100
QSO09110
QSO09120


```

COSX(2)=-YABMYB*SPAN(2)/HAB
COSX(3)=-YBCMYB*SPAN(3)/HBC
COSY(1)=-XABMXA/LAB
COSY(2)=-XABMXB/HAB
COSY(3)=-XBCMCXB/HBC
END
IF(.NOT.BOTTOM)GOTO241
IF(.NOT.BOTTOM) THEN
  XADMXA=.5*XDIF(X(I+1,JM1),X(I,JM1),X(I,J),X(I+1,J))
  YADMYA=.5*XDIF(Y(I+1,JM1),Y(I,JM1),Y(I,J),Y(I+1,J))
  LAD=SQRT(XADMXA**2+YADMYA**2)*SPAN(8)/LAD
  COSX(8)=-YADMYA*SPAN(8)/LAD
  COSY(8)=-XADMXA/LAD
END
LENGTH(1)=LAB
LENGTH(2)=HAB
LENGTH(3)=HBC
LENGTH(8)=LAD
EXDIF1=X(I+1,J)-X(I,J)
YDIF1=Y(I+1,J)-Y(I,J)
XDIF2=SPAN(1)*(Y(I+1,J)-Y(I,J))
YDIF2=Y(I,J)-Y(I+1,J)
SLEN=EXDIF1*EXDIF1+YDIF1*YDIF1
ZETDF1=ZETA(J+1)-ZETA(J)
ZETDF2=ZETA(JM1)-ZETA(J)
ETADF1=ETA(I+1)-ETA(I)
ETADF2=ETA(IM1)-ETA(I)
CELL1=POINT A
EK4=2.*YABMYA/ZETDF1
EK3={Y(I+1,J)-Y(I,J)}/ETADF1
EK2=2.*XABMXA/ZETDF1
EK1={X(I+1,J)-X(I,J)}/ETADF1
L=1
DO (TRANSFORMATION MATRIX)
  PROCEDURE (TRANSFORMATION MATRIX)
    JACOB=EK1*EK4-EK2*EK3
    IF(JACOB.EQ.0.) GOTO243
    IF(JACOB.NE.0.) THEN
      DEDY(L)=EK4/JACOB
      DEDY(L)=-EK2/JACOB/SPAN(1)
      DZDX(L)=-EK3/JACOB
      DZDY(L)=EK1/JACOB/SPAN(1)
    END
  END
EK4=2.*YADMYA/ZETDF2
CELL IV, POINT A
EK2=2.*XADMXA/ZETDF2
L=8

```

C 239
C

C 241
C

C

C C

C

C C 243
C


```

C      DO (TRANSFORMATION MATRIX)
JACOB=EK1*EK4-EK2*EK3
IF (JACOB.EQ.0.) GOTO245
IF (JACOB.NE.0.) THEN
C      DEDX(L)= EK4/JACOB
DEDY(L)=-EK2/JACOB/SPAN(8)
DZDX(L)= -EK3/JACOB
DZDY(L)= EK1/JACOB/SPAN(8)
END
C      CELL 11, POINT B
C      EK4 = {Y(I,J+1)-Y(I,J)}/ZETDF1
245 EK3 = 2.*YBCMYB/ETADF2
EK2 = {X(I,J+1)-X(I,J)}/ZETDF1
EK1 = 2.*XBCMXB/ETADF2
L=3
C      DO (TRANSFORMATION MATRIX)
JACOB=EK1*EK4-EK2*EK3
IF (JACOB.EQ.0.) GOTO247
IF (JACOB.NE.0.) THEN
C      DEDX(L)= EK4/JACOB
DEDY(L)=-EK2/JACOB/SPAN(3)
DZDX(L)= -EK3/JACOB
DZDY(L)= EK1/JACOB/SPAN(3)
END
C      CELL 1, POINT B
C      EK1 = 2.*XABMYB/ETADF1
247 EK3 = 2.*YABMYB/ETADF1
L=2
C      DO (TRANSFORMATION MATRIX)
JACOB=EK1*EK4-EK2*EK3
IF (JACOB.EQ.0.) GOTO249
IF (JACOB.NE.0.) THEN
C      DEDX(L)= EK4/JACOB
DEDY(L)=-EK2/JACOB/SPAN(2)
DZDX(L)= -EK3/JACOB
DZDY(L)= EK1/JACOB/SPAN(2)
END
C      T(1)=LENGTH(1)*HITE(1)*(DEDX(1)*COSX(1)+DEDY(1)*COSY(1)
249 1)*ONOFF(1)
T(2)=LENGTH(2)*HITE(2)*(DZDX(2)*COSX(2)+DZDY(2)*COSY(2)
1)*ONOFF(2)
T(3)=LENGTH(3)*HITE(3)*(DZDX(3)*COSX(3)+DZDY(3)*COSY(3)
1)*ONOFF(3)
T(8)=LENGTH(8)*HITE(8)*(DEDX(8)*COSX(8)+DEDY(8)*COSY(8)
1)*ONOFF(8)
C      STORE METRICS AND GEOMETRY AT POINT I,J

```

```

QSO10090
QSO10100
QSO10110
QSO10120
QSO10130
QSO10140
QSO10150
QSO10160
QSO10170
QSO10180
QSO10190
QSO10200
QSO10210
QSO10220
QSO10230
QSO10240
QSO10250
QSO10260
QSO10270
QSO10280
QSO10290
QSO10300
QSO10310
QSO10320
QSO10330
QSO10340
QSO10350
QSO10360
QSO10370
QSO10380
QSO10390
QSO10400
QSO10410
QSO10420
QSO10430
QSO10440
QSO10450
QSO10460
QSO10470
QSO10480
QSO10490
QSO10500
QSO10510
QSO10520
QSO10530
QSO10540
QSO10550
QSO10560

```



```

SUPERG(1,J,J,I)=COSX(1,I)
SUPERG(2,J,J,I)=COSX(2,I)
SUPERG(3,J,J,I)=COSX(3,I)
SUPERG(4,J,J,I)=COSX(8,I)
SUPERG(5,J,J,I)=COSY(1,I)
SUPERG(6,J,J,I)=COSY(2,I)
SUPERG(7,J,J,I)=COSY(3,I)
SUPERG(8,J,J,I)=COSY(8,I)
SUPERG(9,J,J,I)=LENGTH(1,I)
SUPERG(10,J,J,I)=LENGTH(2,I)
SUPERG(11,J,J,I)=LENGTH(3,I)
SUPERG(12,J,J,I)=LENGTH(8,I)
SUPERG(13,J,J,I)=EXDIF1
SUPERG(14,J,J,I)=EXDIF2
SUPERG(15,J,J,I)=YDIF1
SUPERG(16,J,J,I)=YDIF2
SUPERG(17,J,J,I)=SLEN2
SUPERG(18,J,J,I)=ZETDF1
SUPERG(19,J,J,I)=ZETDF2
SUPERG(20,J,J,I)=ETADF1
SUPERG(21,J,J,I)=ETADF2
SUPERG(22,J,J,I)=DEDX(1,I)
SUPERG(23,J,J,I)=DEDX(2,I)
SUPERG(24,J,J,I)=DEDX(3,I)
SUPERG(25,J,J,I)=DEDX(8,I)
SUPERG(26,J,J,I)=DEDY(1,I)
SUPERG(27,J,J,I)=DEDY(2,I)
SUPERG(28,J,J,I)=DEDY(3,I)
SUPERG(29,J,J,I)=DEDY(8,I)
SUPERG(30,J,J,I)=DZDX(1,I)
SUPERG(31,J,J,I)=DZDX(2,I)
SUPERG(32,J,J,I)=DZDX(3,I)
SUPERG(33,J,J,I)=DZDX(8,I)
SUPERG(34,J,J,I)=DZDY(1,I)
SUPERG(35,J,J,I)=DZDY(2,I)
SUPERG(36,J,J,I)=DZDY(3,I)
SUPERG(37,J,J,I)=DZDY(8,I)
SUPERG(38,J,J,I)=T(1,I)
SUPERG(39,J,J,I)=T(2,I)
SUPERG(40,J,J,I)=T(3,I)
SUPERG(41,J,J,I)=T(8,I)
SUPERG(42,J,J,I)=T(8,I)
SINCE( KK,LE.2)
GO TO 238

```

```
ELSE
```

```
IF ITERATION COUNT EXCEEDS 2, OBTAIN METRICS, ETC. FROM STORAGE
```

```

QSO10570
QSO10580
QSO10590
QSO10600
QSO10610
QSO10620
QSO10630
QSO10640
QSO10650
QSO10660
QSO10670
QSO10680
QSO10690
QSO10700
QSO10710
QSO10720
QSO10730
QSO10740
QSO10750
QSO10760
QSO10770
QSO10780
QSO10790
QSO10800
QSO10810
QSO10820
QSO10830
QSO10840
QSO10850
QSO10860
QSO10870
QSO10880
QSO10890
QSO10900
QSO10910
QSO10920
QSO10930
QSO10940
QSO10950
QSO10960
QSO10970
QSO10980
QSO10990
QSO11000
QSO11010
QSO11020
QSO11030
QSO11040

```


237

```

COSX(1)=SUPERG(1,J,I)
COSX(2)=SUPERG(2,J,I)
COSX(3)=SUPERG(3,J,I)
COSX(8)=SUPERG(4,J,I)
COSY(1)=SUPERG(5,J,I)
COSY(2)=SUPERG(6,J,I)
COSY(3)=SUPERG(7,J,I)
COSY(8)=SUPERG(8,J,I)
LENGTH(1)=SUPERG(9,J,I)
LENGTH(2)=SUPERG(10,J,I)
LENGTH(3)=SUPERG(11,J,I)
LENGTH(8)=SUPERG(12,J,I)
EXDIF1=SUPERG(13,J,I)
EXDIF2=SUPERG(14,J,I)
YDIF1=SUPERG(15,J,I)
YDIF2=SUPERG(16,J,I)
SLEN2=SUPERG(17,J,I)
ZETDF1=SUPERG(18,J,I)
ZETADF1=SUPERG(19,J,I)
ZETADF2=SUPERG(20,J,I)
ZETADF2=SUPERG(21,J,I)
ZETADF2=SUPERG(22,J,I)
ZETADF2=SUPERG(23,J,I)
ZETADF2=SUPERG(24,J,I)
ZETADF2=SUPERG(25,J,I)
ZETADF2=SUPERG(26,J,I)
ZETADF2=SUPERG(27,J,I)
ZETADF2=SUPERG(28,J,I)
ZETADF2=SUPERG(29,J,I)
ZETADF2=SUPERG(30,J,I)
ZETADF2=SUPERG(31,J,I)
ZETADF2=SUPERG(32,J,I)
ZETADF2=SUPERG(33,J,I)
ZETADF2=SUPERG(34,J,I)
ZETADF2=SUPERG(35,J,I)
ZETADF2=SUPERG(36,J,I)
ZETADF2=SUPERG(37,J,I)
ZETADF2=SUPERG(38,J,I)
T(1)=SUPERG(39,J,I)
T(2)=SUPERG(40,J,I)
T(3)=SUPERG(41,J,I)
T(8)=SUPERG(42,J,I)
END
CELL II, POINT C
T(5)=PRIORS(1,J)*ONOFF(5)
T(4)=PRIORS(2,J)*ONOFF(4)
PRIORS(1,J)=-t(8)

```

C
238

```

SO11050
QSO11060
QSO11070
QSO11080
QSO11090
QSO11100
QSO11110
QSO11120
QSO11130
QSO11140
QSO11150
QSO11160
QSO11170
QSO11180
QSO11190
QSO11200
QSO11210
QSO11220
QSO11230
QSO11240
QSO11250
QSO11260
QSO11270
QSO11280
QSO11290
QSO11300
QSO11310
QSO11320
QSO11330
QSO11340
QSO11350
QSO11360
QSO11370
QSO11380
QSO11390
QSO11400
QSO11410
QSO11420
QSO11430
QSO11440
QSO11450
QSO11460
QSO11470
QSO11480
QSO11490
QSO11500
QSO11510
QSO11520

```



```

C      PRIORS(2,J) = - T(1)
END
C
C      DO (FIELD GRADIENTS)
C
C      PROCEDURE (FIELD GRADIENTS)
DQ 438 I1=1,3
      FI1(I1)=PHI(I+1,J)
      FI2(I1)=PHI(I+1,J+1)
      FI3(I1)=PHI(I,J+1)
      FI9(I1)=PHI(I,J)
      FI4      =PHI(IM1,J+1)
      FI5      =PHI(IM1,JM1)
      FI6      =PHI(IM1,JM1)
      FI7      =PHI(I+1,JM1)
      FI8      =PHI(I+1,J)
      FI9(8)=PHI(I,J)
      I10=I-1-IEEXIT+3
438
C
C      CELL I, POINT A
251 DPHIDZ(1)=XDIF(FI3(1),FI2(1),FI9(1),FI1(1))/ZETDF1
      DPHIDE(1)=(FI1(1)-FI9(1))/ETADF1
C      CELL I, POINT B
      DPHIDE(2)=XDIF(FI1(2),FI2(2),FI9(2),FI3(2))/ETADF1
C      CELL I, POINT B
      DPHIDZ(3)=XDIF(FI5,FI4,FI9(3),FI3(3))/ETADF2
C      DPHIDE(3)=(FI3(3)-FI9(3))/ZETDF1
C      CELL IV, POINT A
      DPHIDE(8)=(FI1(8)-FI9(8))/ETADF1
C      DPHIDZ(8)=XDIF(FI7,FI8,FI9(8),FI1(8))/ZETDF2
END
C
C      DO (VELOCITIES AND DENSITIES)
C
C      PROCEDURE (VELOCITIES AND DENSITIES)
      U(6) = U(3)
      V(6) = V(3)
      U(7) = U(2)

```


QSO12010
QSO12020
QSO12030
QSO12040
QSO12050
QSO12060
QSO12070
QSO12080
QSO12090
QSO12100
QSO12110
QSO12120
QSO12130
QSO12140
QSO12150
QSO12160
QSO12170
QSO12180
QSO12190
QSO12200
QSO12210
QSO12220
QSO12230
QSO12240
QSO12250
QSO12260
QSO12270
QSO12280
QSO12290
QSO12300
QSO12310
QSO12320
QSO12330
QSO12340
QSO12350
QSO12360
QSO12370
QSO12380
QSO12390
QSO12400
QSO12410
QSO12420
QSO12430
QSO12440
QSO12450
QSO12460
QSO12470
QSO12480

```

V(7) = V(2)
DO 541 I1=1,8
  IF(I1.GE.4.AND.I1.NE.8) GOTO 541
  IF(I1.LT.4.OR.I1.EQ.8) THEN
    U(I1)=DPHIDE(I1)*DEDX(I1)+DPHIDZ(I1)*DZDX(I1)
    V(I1)=DPHIDE(I1)*DEDY(I1)+DPHIDZ(I1)*DZDY(I1)
    IF(INDEX(I,J).EQ.0)GOTO5411
    ICOUNT=ICOUNT+1
    IIS=I1DEX(ICOUNT)
    IF(I1.LE.IIS)IIP=IIS
    IDIF=INDEX(I,J)+IIS-1
    IF(IIS.EQ.1.AND.IIP.EQ.IDIF)IIP=8
    IF(I1.NE.IIP)GOTO5410
    IF(IIP.GT.IDIF.AND.IIP.NE.8)GOTO5410
    V(I1)=FAKEV(IDEX)
    U(I1)=FAKEU(IDEX)
    IDEX=IDEX+1
    IIP=IIP+1
    IF(I1.NE.8) ICOUNT=ICOUNT-1
    V(I1)=V(I1)-SPAN(I1)*FIXR/RADLE*ROTATN
    UN(I1)=U(I1)*COSX(I1)+V(I1)*COSY(I1)
  END
CONTINUE
GOTO 2003
IF(.NOT.TOP) GOTO 2003
U8=SQRT(U(8)*U(8)+V(8)*V(8))*ABS(EXDIF1)/SQRT(SLEN)
IF(KK.GT.7.OR.ABS(FLOCO).GT..01)U(8)=SIGN(U8,U(8))
V(8)=U(8)*YDIF1/EXDIF1
UN(8)=U(8)*COSX(8)+V(8)*COSY(8)
END
U(4) = PRIORS(3,J)
U(5) = PRIORS(4,J)
V(4) = PRIORS(5,J)
V(5) = PRIORS(6,J)
PRIORS(3,J)=U(1)
PRIORS(4,J)=U(8)
PRIORS(5,J)=V(1)
PRIORS(6,J)=V(8)
RHO(7)=RHO(2)
RHO(6)=RHO(3)
RHO(4)=PRIORS(7,J)
RHO(5)=PRIORS(8,J)
ONSUM=0
DO 595 I1=1,8
  IF(KK.LE.2.OR.MOD(KK,2).EQ.0) THEN
    IF(I1.GE.4.AND.I1.NE.8) GOTO 2005
    IF(I1.LT.4.OR.I1.EQ.8) THEN
      RHOFAC=1.

```



```

RHO(I1)=1.
IF(I1.EQ.2.OR.I.EQ.IEXIT).AND.J.LE.4.AND.ROTATN.NE.0.
1.OR.KK.LE.NOTVET) GOTO 2005
QSQR=U(I1)*U(I1)+(V(I1)*V(I1))
IF(QSQR.GE.QLIM)QSQR=.99*QLIM
RHOFAC=RHOCON*(1.-QSQR)*ONOFF(I1)+1.
RHO(I1)=1.-AMZ*(QSQR-1.)+AMY*(QSQR-1.)*(QSQR-1.)
IF(QSQR.LT..65.OR.QSQR.GT.1.44)RHO(I1)=RHOFAC**EXPD

C CORRECT DENSITY FOR ROTATION
ROTATX=SPAN(I1)*FIXR/RADLE
IF(ROTROT.NE.0.AND.J.GT.3)
1RHO(I1)=(RHO(I1)**(1./EXPD))+RHOCON*ROTROT*((ROTATX)
1*2-1.)*ONOFF(I1)**EXPD
2005 QSQR=U(I1)*U(I1)+V(I1)*V(I1)
IF(I1.GT.1)
1MACH(I1)=MINF*SQRT(QSQR)/RHO(I1)**(1./EXPD)
1MACH(I1)=MINF*SQRT(QSQR/RHO(I1)**(1./EXPD))
IF(MACH(I1).GT.2.)MACH(I1)=2.
CONTINUE
PRIORS(7,J)=RHO(I1)
PRIORS(8,J)=RHO(8)
END

C
C DO (SUPERSONIC CORRECTION)
C PROCEDURE (SUPERSONIC CORRECTION)
ONSUM=0.
RCSUM=RHO(4)+RHO(5)+RHO(6)+RHO(7)
EMACH(I,J)=0.
XVELIJ=0.
DO 608 I3=1,8
RHOS(I3)=0.
ONSUM=ONSUM+ONOFF(I3)
YVELIJ=0.
SMALLA=0.
SMALLB=0.
ZETDF1=ZETA(J+1)-ZETA(J)
IF(J.EQ.M)ZETDF1=ZETA(J)-ZETA(J-1)
EMACH(I,J)=(ONOFF(I1)*MACH(I1)+ONOFF(8)*MACH(8))/(ONOFF(I1)+ONOFF(8)
1)
EMACH(IEXIT+1,J)=EMACH(3,J)
EMACH(I,J)=EMACH(IEXIT-1,J)

```

QS012490
 QS012500
 QS012510
 QS012520
 QS012530
 QS012540
 QS012550
 QS012560
 QS012570
 QS012580
 QS012590
 QS012600
 QS012610
 QS012620
 QS012630
 QS012640
 QS012650
 QS012660
 QS012670
 QS012680
 QS012690
 QS012700
 QS012710
 QS012720
 QS012730
 QS012740
 QS012750
 QS012760
 QS012770
 QS012780
 QS012790
 QS012800
 QS012810
 QS012820
 QS012830
 QS012840
 QS012850
 QS012860
 QS012870
 QS012880
 QS012890
 QS012900
 QS012910
 QS012920
 QS012930
 QS012940
 QS012950
 QS012960


```

C      IF(KK.LE.2.OR.MOD(KK,IT).EQ.0.OR.MOD(KK,IT).GE.IT/2) THEN
C      STORE DENSITIES FROM SURFACE OF ELEMENT IN DUMMY ARRAYS
      DUMBX(I,J)=(ONOFF(1)*RHO(1)+ONOFF(8)*RHO(8))/(ONOFF(1)+ONOFF(8)
1)
      IF(.NOT.TOP)DUMBY(I,J)=(ONOFF(2)*RHO(2)+ONOFF(3)*RHO(3))/
1(ONOFF(2)+ONOFF(3))
      IF(.NOT.TOP)ZMACH(I,J)=(ONOFF(2)*MACH(2)+ONOFF(3)*MACH(3))/
1(ONOFF(2)+ONOFF(3))
      IF(TOP)DUMBY(I,J)=2.*DUMBY(I,J-1)-DUMBY(I,J-2)
      IF(TOP)ZMACH(I,J)=2.*ZMACH(I,J-1)-ZMACH(I,J-2)
      DUMBX(IEXIT+1,J)=DUMBX(3,J)
      ZMACH(I,J)=ZMACH(IEXIT-1,J)
      DUMBY(I,M+1)=2.*DUMBY(I,1)-DUMBY(I,2)
      ZMACH(I,M+1)=2.*ZMACH(I,1)-ZMACH(I,2)
C      CALCULATE DENSITY CORRECTION TERMS, MU*DRHODS*DS
C      IF(J.GT.5.OR.I.LT.NOZ-1.OR.I.GT.NOZ+1) THEN
C      IF(J.LE.5.AND.I.GE.NOZ-1.AND.I.LE.NOZ+1) GOTO20001
      DO 694 I1=2,8,6
      IF(TOP.AND.I1.NE.8) GOTO 694
      IF(.NOT.TOP.OR.I1.EQ.8) THEN
      I1P1=I1+1
      IF(I1.EQ.8) I1P1=1
      ONSUM=ONOFF(I1)+ONOFF(I1P1)
      XVELIJ=U(I1)*ONOFF(I1)/ONSUM
      XVELIJ=XVELIJ+U(I1P1)*ONOFF(I1P1)/ONSUM
      YVELIJ=V(I1)*ONOFF(I1)/ONSUM
      YVELIJ=YVELIJ+V(I1P1)*ONOFF(I1P1)/ONSUM
      SMALLA=(U(I1)*DZDX(I1)+V(I1)*DZDY(I1))*ONOFF(I1)/ONSUM
      SMALLA=SMALLA+(U(I1P1)*DZDX(I1P1)+V(I1P1)*DZDY(I1P1))
1*ONOFF(I1P1)/ONSUM
      SMALLB=(U(I1)*DEDX(I1)+V(I1)*DEDY(I1))*ONOFF(I1)
1/ONSUM
      SMALLB=SMALLB+(U(I1P1)*DEDX(I1P1)+V(I1P1)*DEDY(I1P1))
1*ONOFF(I1P1)/ONSUM
      IF(KK.LE.NOTYET) GOTO694
      IF(KK.GT.NOTYET) THEN
      IF(BLADE)SMALLA=0.
      SIGNOA=SIGN(1.,SMALLA)
      IF(SMALLA.EQ.0.)SIGNOA=1.
      FLOWAT=AMAX1(0.,SIGNOA)
      SIGNOB=SIGN(1.,SMALLB)
      FLOWBY=AMAX1(0.,SIGNOB)
      QUE=SQRT(XVELIJ**2+YVELIJ**2)
      SLP2=TEGARD
      IF (ABS(SMALLB)/QUE.GT.SLP2)QUE=SQRT(SMALLA**2+SMALLB**2)

```



```

C      DO ( T'S,Q'S AND RESIDUALS)
C
C      PROCEDURE ( T'S,Q'S AND RESIDUALS)
C
C      NET MASS FLOW TERM
C      ONSUM=0.
C      FLONET = -RHOUL(2)*ONOFF(7)-RHOUL(3)*ONOFF(6)+PRIORS(9,J)*ONOFF(4
1) + PRIORS(10,J)*ONOFF(5)
C      DO 711 I1=1,8
C      ONSUM=ONSUM+ONOFF(I1)
C      IF(I1.GE.4.AND.I1.NE.8) GOTO 711
C      IF(I1.LT.4.OR.I1.EQ.8) THEN
C      ROSUM=ROSUM+RHO(I1)
C      RHOUL(I1)=RHO(I1)*UN(I1)*LENGTH(I1)* HITE(I1)*ONOFF(I1)
C      FLONET =FLONET + RHOUL(I1)
C      END
C      CONTINUE
C      ROAVG=ROSUM/ONSUM
C      TENOLF(I,J)=FLONET
C      PRIORS(9,J) = -RHOUL(1)
C      PRIORS(10,J) = -RHOUL(8)
C
C      RESIDUAL TOTAL
C      R=-FLONET
C      END
C      IF(BUG) DO (FIRST DEBUG LIST)
C
C      PROCEDURE (FIRST DEBUG LIST)
C
C      BUG AND BUG3 ARE NOT INCLUDED IN NAMELIST PARAMS. THEY MUST BE
C      ADDED OR SET HERE MANUALLY IN ORDER TO ACTIVATE THESE PRINTOUTS.
C
C      IF(.NOT.EXIT.OR.MOD(KK,IT).NE.0.OR..NOT.TOP.OR..NOT.BUG) GOTO 2023
C      IF(EXIT.AND.MOD(KK,IT).EQ.0.AND.TOP.AND.BUG) THEN
C      WRITE(6,YTESD)
C      IF(.NOT.BUG3) GOTO2025
C      IF(BUG3) THEN
C      WRITE(6,7001)
C      FORMAT(10ARRAY OF POTENTIAL CORRECTIONS,BLADE SURFACE=FAR RIGHT',
1, COLUMN, )
C      DO 732 I2=1,IEXIT
C      WRITE(6,9)(DELPV(I2,J2),J2=167,M)
C      WRITE(6,7002)
C      FORMAT(10ARRAY OF POTENTIAL VALUES,BLADE SURFACE=FAR RIGHT ',
7001
732
7002

```

QSO13930
 QSO13940
 QSO13950
 QSO13960
 QSO13970
 QSO13980
 QSO13990
 QSO14000
 QSO14010
 QSO14020
 QSO14030
 QSO14040
 QSO14050
 QSO14060
 QSO14070
 QSO14080
 QSO14090
 QSO14100
 QSO14110
 QSO14120
 QSO14130
 QSO14140
 QSO14150
 QSO14160
 QSO14170
 QSO14180
 QSO14190
 QSO14200
 QSO14210
 QSO14220
 QSO14230
 QSO14240
 QSO14250
 QSO14260
 QSO14270
 QSO14280
 QSO14290
 QSO14300
 QSO14310
 QSO14320
 QSO14330
 QSO14340
 QSO14350
 QSO14360
 QSO14370
 QSO14380
 QSO14390
 QSO14400


```

1' COLUMN' )
DO 738 I2=1, IEXIT
WRITE(6,9) (PHI(I2, J2), J2=I67, M)
END
738 C
2025 WRITE(6,7003)
7003 FORMAT(10ARRAY OF RESIDUAL MASS FLOWS, BLADE SURFACE=FAR RIGHT',
1, COLUMN')
DO 745 I2=1, IEXIT
WRITE(6,9) (TENOLF(I2, J2), J2=I67, M)
END
745 C
7004 WRITE(6,7004)
7004 FORMAT(10ARRAY OF MACH NUMBERS, BLADE SURFACE=FAR RIGHT COLUMN',
1, COLUMN')
DO 750 I2=1, IEXIT
WRITE(6,9) (EMACH(I2, J2), J2=I67, M)
REWINDD
END
750 C
WRITE(8,2) PHI
END
9 C
FORMAT(1H, 14E9.3)
END
C
DO ( DELPHI COEFFICIENTS AND TRANSPOSED TERMS)
C
PROCEDURE ( DELPHI COEFFICIENTS AND TRANSPOSED TERMS)
C
AIJPI*DELPHI(I, J+1)+AIJ*DELPHI(I, J)+AIJMI*DELPHI(I, J-1)= R + BIGZ
C
2023 DELPM1(2) = DELPHI(J)
IF(I.EQ.2) DELPM1(2)=DELPSV( IEXIT-1, J)
IF(KK.GT.2.AND.MOD(KK, IT).NE.0) GOTO 2029
IF(KK.LE.2.OR.MOD(KK, IT).EQ.0) THEN
AIJPI=(T(2)*RHO(2)+T(3)*RHO(3))/ZETDF1
AIJMI=(T(6)*RHO(6)+T(7)*RHO(7))/ZETDF2
TT18=(T(1)*RHO(1)+T(8)*RHO(8))/ETADF1
ZIMIJ=(T(4)*RHO(4)+T(5)*RHO(5))/ETADF2
AIJ=-1.*(AIJMI+AIJPI+TT18+ZIMIJ)
ZIPIJ=0.
ZJPI=0.
ZJMI=0.
C
SAVE COEFFICIENTS UNTIL THE NEXT TIME DENSITY IS UPDATED (WHEN KK IS
DI VISIBLE BY IT).
SUPERG(43, J, I)=AIJ
SUPERG(44, J, I)=AIJMI
SUPERG(45, J, I)=AIJPI
SUPERG(46, J, I)=ZIMIJ
ZIMIJ=ZIMIJ*DELPM1(2)

```

QSO14410
QSO14420
QSO14430
QSO14440
QSO14450
QSO14460
QSO14470
QSO14480
QSO14490
QSO14500
QSO14510
QSO14520
QSO14530
QSO14540
QSO14550
QSO14560
QSO14570
QSO14580
QSO14590
QSO14600
QSO14610
QSO14620
QSO14630
QSO14640
QSO14650
QSO14660
QSO14670
QSO14680
QSO14690
QSO14700
QSO14710
QSO14720
QSO14730
QSO14740
QSO14750
QSO14760
QSO14770
QSO14780
QSO14790
QSO14800
QSO14810
QSO14820
QSO14830
QSO14840
QSO14850
QSO14860
QSO14870
QSO14880


```

C      SINCE (KK.LE.2.OR.MOD(KK,IT)).EQ.0)
C      GOTO 2030
C      IF ITERATION COUNT EXCEEDS 2 AND IS NOT DIVISIBLE BY IT, OBTAIN
C      COEFFICIENTS FROM THE LAST CALCULATION.
2029  AIJ=SUPERG(43,J,I)
      AIJMI=SUPERG(44,J,I)
      AIJPI=SUPERG(45,J,I)
      ZIMIJ=SUPERG(46,J,I)
      ZIMIJ=ZIMIJ*DELPMI(2)
      ZJPI=0.
      ZJMI=0.
      END
2030  BIGZ = -(ZUPIJ +ZIMIJ + ZJPI + ZJMI)
      IF(J.EQ.4)BIGZ=BIGZ-AIJMI*DELPV(IEXIT+2-1,5)
      TRANSP = R +BIGZ
C      ELIMINATE CHANGES TO PHI(BY ZEROING COEFFICIENTS) ON ALL DUMMY LINES
C      BEYOND PERIODIC LINE.
      IF(.NOT.(J.LT.4.OR.(J.LE.5.AND.
1(I.LE.3.OR.I.GE.IEXIT-1.OR.I.EQ.NOZ-1.OR.
1(I.EQ.NOZ.OR.I.EQ.NOZ+1)))) GOTO 2031
C      AIJ=0.
      AIJMI=0.
      AIJPI=0.
      TRANSP=0.
C      STORE COEFFICIENTS FOR LATER TRIAGONAL SOLUTION OF THIS LINE
2031  PRIORS(11,J)=AIJ
      PRIORS(12,J)=AIJPI
      PRIORS(13,J)=AIJMI
      PRIORS(14,J)=TRANSP
C      PROCEED TO NEXT VALUE OF J ON THIS RADIATING LINE
      IF(.NOT.TOP)GOTO275
C      END
C      DO (FORWARD ELIMINATION)
C      PROCEDURE (FORWARD ELIMINATION)
      DO 828 J=1,M
      JM1=J-1
      IF(JM1.EQ.0) JM1=2

```



```

BOTTOM = .FALSE.
TOP = .FALSE.
BLADE = .FALSE.
IF(J.EQ.1) BOTTOM = .TRUE.
IF(J.EQ.M) TOP = .TRUE.
BLADE = TOP
QSO15370

C RECOVER COEFFICIENTS
AIJ=PRIORS(11,J)
AIJPI=PRIORS(12,J)
AIJMI=PRIORS(13,J)
TRANSP=PRIORS(14,J)
IF(BOTTOM) GOTO 828
IF(.NOT.BOTTOM) THEN
FFAC=AIJ-AIJMI*E(JMI)
E(J)= +AIJPI/FFAC
F(J)= (TRANSP - AIJMI*F(JMI))/FFAC
FORMAT(9E13.5)
END
3333 C
828 C
CONTINUE
END
C
IF(I.NE.1)
1DO (BACK SUBSTITUTION)
C
PROCEDURE (BACK SUBSTITUTION)
DELPHI(M)=F(M)
OV=OVEREL
IF(KKK.LT.NOTYET)OV=UNDERL
IF(EMACH(I,M).GE.1.)OV=SUPREL*(1.-D(M))*(1.-CI))
DELPSV(I,M)=DELPHI(M)*OV
J=M-1
IF(J.LT.1)GOTO857
FORMAT(3I6,9E12.5)
BOTTOM = .FALSE.
TOP = .FALSE.
BLADE = .FALSE.
IF(J.EQ.1) BOTTOM = .TRUE.
IF(J.EQ.M) TOP = .TRUE.
BLADE = TOP
IF(.NOT.BOTTOM) DELPHI(J)=-E(J)*DELPHI(J+1)+F(J)
OV=OVEREL
IF(KKK.LT.NOTYET)OV=UNDERL
QSO15380
QSO15390
QSO15400
QSO15410
QSO15420
QSO15430
QSO15440
QSO15450
QSO15460
QSO15470
QSO15480
QSO15490
QSO15500
QSO15510
QSO15520
QSO15530
QSO15540
QSO15550
QSO15560
QSO15570
QSO15580
QSO15590
QSO15600
QSO15610
QSO15620
QSO15630
QSO15640
QSO15650
QSO15660
QSO15670
QSO15680
QSO15690
QSO15700
QSO15710
QSO15720
QSO15730
QSO15740
QSO15750
QSO15760
QSO15770
QSO15780
QSO15790
QSO15800
QSO15810
QSO15820
QSO15830
QSO15840

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```

      IF(EMACH(I,J).GE.1.)OV=SUPREL*(1.-D(J))*(1.-CI)
      DELPSV(I,J)= DELPHI(J)*OV
      J=J-1
      GOT0856
      CONTINUE
      END
      J=0
857 C
      C
      C      GO TO NEXT RADIATING LINE
      IF(.NOT.EXIT)GOT0272
      TOT=0.
      C
      C      IF ALL LINES ARE COMPLETED, THEN
      C      DO (UPDATE OF FIELD VARIABLES)
      C
      C      PROCEDURE (UPDATE OF FIELD VARIABLES)
      DO 871 I =2, IEXIT
      DO 871 J1=1,M
      PHI(I,J1)= PHI(I,J1)+DELPSV(I,J1)
      IF(J1.GE.4. AND. I.GT.1. AND. (ABS(DELPSV(I,J1)).LT. TEST*AVGFAC*GUESS
1/FLOAT(IEXIT-1))/FLOAT(M-3).OR. KKK.LT. NOTYET))
1TOT=TOT+ABS(DELPSV(I,J1))
      SSFAC=RADLE/FIXR*SQRT(1+LAMBDA**2)
      DO 880 I1=2, IEXIT
      IF(I1.EQ. NOZ) GOT0 880
      IF(I1.NE. NOZ) THEN
      SFAC= SSFAC*FLOAT(1+SIGN(1,I1-NOZ))
      C
      C      CORRECT THE DUMMY LINES BEYOND PERIODIC BOUNDARY USING PERIODICITY
      C
      C      CONDITION.
      DO 878 J1=1,3
      PHI(I1,J1)=PHI(IEXIT+2-I1,8-J1)+SFAC
      END
      CONTINUE
878 C
880 C
      C      UPDATE DUMMY LINES ON EACH SIDE OF BRANCH CUT
      DO 890 J1=1,M
      PHI(1,J1)=

```

QSO15850
 QSO15860
 QSO15870
 QSO15880
 QSO15890
 QSO15900
 QSO15910
 QSO15920
 QSO15930
 QSO15940
 QSO15950
 QSO15960
 QSO15970
 QSO15980
 QSO15990
 QSO16000
 QSO16010
 QSO16020
 QSO16030
 QSO16040
 QSO16050
 QSO16060
 QSO16070
 QSO16080
 QSO16090
 QSO16100
 QSO16110
 QSO16120
 QSO16130
 QSO16140
 QSO16150
 QSO16160
 QSO16170
 QSO16180
 QSO16190
 QSO16200
 QSO16210
 QSO16220
 QSO16230
 QSO16240
 QSO16250
 QSO16260
 QSO16270
 QSO16280
 QSO16290
 QSO16300
 QSO16310
 QSO16320


```

C      1 PHI(IEXIT-1,J1)-CIRCO
C      1 PHI(IEXIT-1,J1)-RADLE/FIXR*S*(AQINF1*SIN(LAMDAO+BETA1)-AQINF2*SIN(
890 1 LAMDAO+BETA2)/PIOP2)
C      1 PHI(IEXIT+1,J1)=PHI(3,J1)+
C      1 CIRCO
C      1 RADLE/FIXR*S*(AQINF1*SIN(LAMDAO+BETA1)-AQINF2*SIN(LAMDAO+
1 BETA2)/PIOP2)
C      1 END
C
C      DO (CONVERGENCE TESTS)
C
C      PROCEDURE (CONVERGENCE TESTS)
RELAXD=.FALSE.
NOZO2=NOZ/2
MO2=M/2
AVGFAC=FLOAT(IEXIT-2)*FLOAT(M-3)*ABS(PHI(NOZO2,MO2))
TEST=TOT/AVGFAC
CIRCN=PHI(IEXIT,M)-PHI(2,M)
DCIRC=(CIRCN-CIRCO)/CIRCO
IF(TOL.GT.0..AND.TOL.LT.1..AND.ABS(TEST).LT.TOL)RELAXD=.TRUE.
IF(TOL.GT.1..AND.KK.GE.IFIX(TOL))RELAXD=.TRUE.
TRUNC=ABS(TOL)
IF(TOL.LT.0..AND.ABS(DCIRC).LT.TRUNC.AND.KK.GT.50)RELAXD=.TRUE.
IF(KK.GE.KKMAX)RELAXD=.TRUE.
TESMAC=0.
DO 909 I=2, IEXIT
  RF=(.5*(DUMBX(I,M)+DUMBX(I-1,M)))*(1./2./EXP0)
  HIMAC=.5*(EMACH(I,M)+EMACH(I-1,M))*RF
  IF(HIMAC.GT.TESMAC.AND.ABS(X(I,M)/COS(LAMDAO))
1 .LT..44)TESMAC=HIMAC
1 CONTINUE
IF(MOD(KK,I).EQ.0.OR.BUG.OR.RELAXD)
1 WRITE(6,99) KK,TEST,TRANSP,JESMAC,CIRCN,DCIRC,OVEREL,SUPREL
99 1 FORMAT(1H,4X,14,4X,7E14.6)
C      1 I=0
C
C      IF(.NOT.RELAXD)GOTO269
C
C      OTHERWISE
C      DO (SURFACE FLOW CALCULATION FOR FINISHED GRID)

```


QSO16810
QSO16820
QSO16830
QSO16840
QSO16850
QSO16860
QSO16870
QSO16880
QSO16890
QSO16900
QSO16910
QSO16920
QSO16930
QSO16940
QSO16950
QSO16960
QSO16970
QSO16980
QSO16990
QSO17000
QSO17010
QSO17020
QSO17030
QSO17040
QSO17050
QSO17060
QSO17070
QSO17080
QSO17090
QSO17100
QSO17110
QSO17120
QSO17130
QSO17140
QSO17150
QSO17160
QSO17170
QSO17180
QSO17190
QSO17200
QSO17210
QSO17220
QSO17230
QSO17240
QSO17250
QSO17260
QSO17270
QSO17280

C PROCEDURE (SURFACE FLOW CALCULATION FOR FINISHED GRID)

WRITE(6,781) M3,ITIEX
ICOUNT=0
IDEX=1
DO 937 I=1, IEXIT
IM=I-1
IM1=IM
IF(IM1.EQ.0) IM1=2
FIRSTJ=M-2
LINEI=I

C DO (VELOCITY CALCULATION ALONG RADIATING LINE)
CALL SPEEDS(LINEI,FIRSTJ)

937 IF(IM.GT.0)
1WRITE(6,782)IM,XOCX,FADBOP,X(I,M),Y(I,M),D(M),BOPR,
1PHI(I,M),E(M),F(M),DELPHI(M)
781 FORMAT(1H0/1H0,22X,
1.FINAL FLOW CALCULATION ON BLADE SURFACE FOR THE ,I3, LINE NO. ,
1. BY ,I3, MESH ,//, RADIATING,50X, STATIC ,//, PRES , ,
1. X/CX Y/CX X YVEL Y DENSITY ,//)
1.COEF PHI XVEL
782 FORMAT(16,4X,10F10.5)
C END

RETURN

ENTRY KEEPER

C DO (OUTPUT OF PHI AND CALCULATION OF FINAL VELOCITY FIELD)

C PROCEDURE (OUTPUT OF PHI AND CALCULATION OF FINAL VELOCITY FIELD)

10 REWIND 7
FORMAT(5E15.8)
ENT=1.


```

131      EXI=1.
          IF(ALLOUT)WRITE(6,131) M3,ITIEX
          FORMAT(1H1,38X,' CALCULATED FLOW FIELD AT ALL GRID POINTS '/1H0,
138X,SURFACE CONTOUR NO. 1 = PERIODIC BOUNDARY'/40X,'SURFACE CONT',
139X,OUR NO. 1 = BLADE SURFACE'/1H0,31X,' RADIATING LINE NO. 1 BEGINS AT',
140X,DOWNSTREAM,
141X,INFINITY,
142X,' AND IS REPEATED AS LINE NO. ',I3)
          IF(ALLOUT)WRITE(6,13)
          FORMAT(1H0,15X,' SURFACE ',74X,'FLOW STATIC'/16X'CONTOUR ',
143X/CX,
144X,Y/CX,
145X,XVEL,
146X,YVEL,
147X,DENSITY,
148X,MACH,
149X,ANGLE',
150X,PRES COEF'/15X,' NUMBER')
          IDEX=1
          ICOUNT=0
          DO 969 I=1, IEXIT
          IIM=I-1
          IF(I.GT.1.AND.ALLOUT)WRITE(6,14) IIM
          FORMAT('ORADIATING LINE',NUMBER',I3)
          IM1=I-1
          IF(IM1.EQ.0) IM1=2
          FIRSTJ=1
          LINEI=1

C      DO (VELOCITY CALCULATION ALONG RADIATING LINE)
          CALL SPEEDS(LINEI,FIRSTJ)

969      CONTINUE
          DO 972 I=2, IEXIT
          E(I)=.5*(DELPSV(I,4)+DELPSV(IXIT+2-I,4))
972      DO 975 I=2, IEXIT
          DELPSV(I,4)=E(I)
          REWIND 13
          MM3=M-3
          NNOZ=NNOZ-1

C      WRITE THE PLOT DATA SAVE FILE

1      WRITE(13,1) NNOZ,MM3
          FORMAT(2I5)
          WRITE(13,2) ((X(I,J), I=2,NZZ), J=4,M), ((Y(I,J), I=2,NZZ), J=4,M),
          WRITE(13,2) ((DUMBX(I,J), I=2,NZZ), J=4,M), ((DUMBY(I,J), I=2,NZZ),
          J=4,M), ((DELPSV(I,J), I=2,NZZ), J=4,M)
          WRITE(13,2) ((TENOLF(I,J), I=2,NZZ), J=4,M)

```

QSO17290
 QSO17300
 QSO17310
 QSO17320
 QSO17330
 QSO17340
 QSO17350
 QSO17360
 QSO17370
 QSO17380
 QSO17390
 QSO17400
 QSO17410
 QSO17420
 QSO17430
 QSO17440
 QSO17450
 QSO17460
 QSO17470
 QSO17480
 QSO17490
 QSO17500
 QSO17510
 QSO17520
 QSO17530
 QSO17540
 QSO17550
 QSO17560
 QSO17570
 QSO17580
 QSO17590
 QSO17600
 QSO17610
 QSO17620
 QSO17630
 QSO17640
 QSO17650
 QSO17660
 QSO17670
 QSO17680
 QSO17690
 QSO17700
 QSO17710
 QSO17720
 QSO17730
 QSO17740
 QSO17750
 QSO17760


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QSO17770
QSO17780
QSO17790
QSO17800
QSO17810
QSO17820
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QSO17840
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QSO17980
QSO17990
QSO18000
QSO18010
QSO18020
QSO18030
QSO18040
QSO18050
QSO18060
QSO18070
QSO18080
QSO18090
QSO18100
QSO18110
QSO18120
QSO18130
QSO18140
QSO18150
QSO18160
QSO18170
QSO18180
QSO18190
QSO18200
QSO18210
QSO18220
QSO18230
QSO18240

IF (BUG3)
1WRITE(6,2)((X(I,J),I=2,NZZ),J=4,M),((Y(I,J),I=2,NZZ),J=4,M)
IF (BUG3)
1WRITE(6,2)((DUMBX(I,J),I=2,NZZ),J=4,M),((DUMBY(I,J),I=2,NZZ),
1J=4,M)
END

C
RETURN

END
SUBROUTINE SPEEDS(I,MM2)
VELOCITY CALCULATION ALONG ONE RADIATING LINE (I), BEGINNING AT J
= MM2 AND GOING TO J=M (THE BLADE SURFACE). ARRAYS DELPHI, DELPS
V D,E,F,PRIORS,DUMBY, AND DUMBX ARE REUSED (OVERWRITTEN) IN THE PRO
CESS.

LOGICAL INLET, BLADE, EXIT, BOTTOM, TOP
LOGICAL DOSURF, SMOOTH, FINEST, RESTAR, ALLOUT
REAL LAB, LAD, MINF, LENGTH, JACOB, LAMDAO
REAL MACH(8)
DOUBLE PRECISION CAPK, CAPKP
COMMON/PARAM/RESTAR,NOZIN,BETA1,BETA2,QINF1,C1,CII,GAMMA,MINF,EM
1,DELTA,BETA,TOL,BUG,BUG2,BUG3,IF,GUESS,OVEREL,FIXR,NOWREL,NOTYET
1,DAMP,SUPREL,S,WAKE,B2OB1,UNDERL,RADRA1,RADLE,OMEGA,FLOCO,VAXIAL,
1ALLOUT
COMMON/QUASI/ RADIUS(100,30),HEIGHT(100,30)
COMMON/ENTIRE/ X(100,30),Y(100,30),PHI(100,30),DELPVS(100,30)
COMMON/GEOM2/ZETA(100),ETA(100)
COMMON/CROSS/ ZMACH(100,30)
COMMON/GEOM/NOZ,M,RLE,RFE,A,CHORD,XUPS,XDNS,LAMDAO,CC,CAPK,
1CAPKP,PI
1,RNK,VB,KN,NED,BB,DOSURF,RFAC,SOLID,MPLS
1,STABAC,SLP1,SLP2,SLP3,SLP4,SMOOTH,CHOP,THETT,THETL
1,FINEST

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COMMON/CALVEL/FAKEFI(4,6), FAKFI(4,6), RHOCON, QLIM, EXPO, ROTAIN,
1 ROTROT, IM1, IEXIT, PRIORS(14,30), INDEX(100,30), IINDEX(32), FAKEU(100),
1 FAKEV(100), ICOUNT, IDEX, AMY, AMZ
COMMON/VELOCITY/DELPHI(100), F(100), DELPHI(100), TENOLF(100,30),
1 DUMBX(100,30), DUMBY(100,30), BOPR, FADBDP, XOCX, KK
1 DIMENSION RHOSS(8), FI1(8), FI2(3), FI3(3), FI9(8), SPAN(8),
1 EMACH(100,30)
2, COSX(8), COSY(8), LENGTH(8), DEDX(8), DZDX(8), DEDY(8),
3 DZDY(8), t(8), DPHIDZ(8), DPHIDE(8), U(8), V(8), UN(8), RHO(8),
4 RHOUL(8), ONOFF(8), DELPM1(3)
5, HITE(8)

COMMON/HIBALL/ SUPERG(46,30,100)

XDIF(A,B,C,D)=.5*(A+B-C-D)

PROCEDURE (VELOCITY CALCULATION ALONG RADIATING LINE)
DO (AXIAL LOCATION INDICATORS)
INLET=.FALSE.
EXIT=.FALSE.
IF(I.EQ.1) INLET=.TRUE.
IF(I.EQ. IEXIT) EXIT=.TRUE.
XLOW=0.
XHI=0.
YLOW=1.E10
DO 1111 I1=1, IEXIT
IF(XLOW.LT.X(I1,M)) GOTO11
XLOW=X(I1,M)
IF(XHI.GT.X(I1,M)) GOTO111
XHI=X(I1,M)
IF(YLOW.LT.Y(I1,M)) GOTO1111
YLOW=Y(I1,M)
CONTINUE
DO 1427 J=MM2,M
J3M=J-3
JM1=J-1
IF(JM1.EQ.0) JM1=2
DO (VERTICAL LOCATION INDICATORS)
BOTTOM=.FALSE.
TOP=.FALSE.
BLADE=.FALSE.
IF(J.EQ.1) BOTTOM=.TRUE.
IF(J.EQ.M) TOP=.TRUE.
BLADE=TOP

```



```

DO (GEOMETRY ADVANCE)
SPAN(1)=XDIFF(RADIUS(I,J),RADIUS(I+1,J),0.,0.,0.)
IF(I.EQ.IEXIT)SPAN(1)=RADIUS(I,J)
SPAN(1)=SPAN(1)/FIXR
SPAN(2)=XDIFF(RADIUS(I,J),RADIUS(I,J+1),0.,0.,0.)
SPAN(2)=SPAN(2)/FIXR
SPAN(3)=SPAN(2)
SPAN(8)=SPAN(1)
COSX(1)=SUPERG(1,J,I)
COSX(2)=SUPERG(2,J,I)
COSX(3)=SUPERG(3,J,I)
COSX(4)=SUPERG(4,J,I)
COSX(5)=SUPERG(5,J,I)
COSX(6)=SUPERG(6,J,I)
COSX(7)=SUPERG(7,J,I)
COSX(8)=SUPERG(8,J,I)
LENGTH(1)=SUPERG(9,J,I)
LENGTH(2)=SUPERG(10,J,I)
LENGTH(3)=SUPERG(11,J,I)
LENGTH(8)=SUPERG(12,J,I)
EXDIF1=SUPERG(13,J,I)
YDIF1=SUPERG(14,J,I)
YDIF2=SUPERG(15,J,I)
SLEN2=SUPERG(16,J,I)
ZETDF1=SUPERG(17,J,I)
ZETDF2=SUPERG(18,J,I)
ETADF1=SUPERG(19,J,I)
ETADF2=SUPERG(20,J,I)
DEDX(1)=SUPERG(21,J,I)
DEDX(2)=SUPERG(22,J,I)
DEDX(3)=SUPERG(23,J,I)
DEDX(8)=SUPERG(24,J,I)
DEDY(1)=SUPERG(25,J,I)
DEDY(2)=SUPERG(26,J,I)
DEDY(3)=SUPERG(27,J,I)
DEDY(8)=SUPERG(28,J,I)
DZDX(1)=SUPERG(29,J,I)
DZDX(2)=SUPERG(30,J,I)
DZDX(3)=SUPERG(31,J,I)
DZDX(8)=SUPERG(32,J,I)
DZDY(1)=SUPERG(33,J,I)
DZDY(2)=SUPERG(34,J,I)
DZDY(3)=SUPERG(35,J,I)
DZDY(8)=SUPERG(36,J,I)
T(1)=SUPERG(37,J,I)
T(2)=SUPERG(38,J,I)
T(3)=SUPERG(39,J,I)
T(4)=SUPERG(40,J,I)

```

Q5018730
Q5018740
Q5018750
Q5018760
Q5018770
Q5018780
Q5018790
Q5018800
Q5018810
Q5018820
Q5018830
Q5018840
Q5018850
Q5018860
Q5018870
Q5018880
Q5018890
Q5018900
Q5018910
Q5018920
Q5018930
Q5018940
Q5018950
Q5018960
Q5018970
Q5018980
Q5018990
Q5019000
Q5019010
Q5019020
Q5019030
Q5019040
Q5019050
Q5019060
Q5019070
Q5019080
Q5019090
Q5019100
Q5019110
Q5019120
Q5019130
Q5019140
Q5019150
Q5019160
Q5019170
Q5019180
Q5019190
Q5019200


```

C      T(3)=SUPERG(41,J,I)
      T(8)=SUPERG(42,J,I) C
      CELL=POINT C
      T(5)=PRIORS(1,J)*ONOFF(5)
      T(4)=PRIORS(2,J)*ONOFF(4)
      PRIORS(1,J)=-T(8)
      PRIORS(2,J)=-T(1)
      DO (FIELD GRADIENTS)
      CELL,I,POINT C
      DO 1214, I=1,3
      FI(1(I))=PHI(I+1,J)
      FI(2(I))=PHI(I+1,J+1)
      FI(3(I))=PHI(I+1,J+1)
      FI(4(I))=PHI(IM1,J+1)
      FI(5(I))=PHI(IM1,J)
      FI(6(I))=PHI(IM1,JM1)
      FI(7(I))=PHI(IM1,JM1)
      FI(8(I))=PHI(I+1,JM1)
      FI(9(I))=PHI(I+1,J)
      I10=I-IEEXIT+3
      END
C      END
C      CELL,I,POINT A
      DPHIDZ(1)=XDIF(FI3(1),FI2(1),FI9(1))/ZETDF1
      DPHIDE(1)=(FI1(1)-FI9(1))/ETADF1
      CELL,I,POINT B
      DPHIDZ(2)=XDIF(FI1(2),FI2(2),FI9(2))/ZETDF1
      DPHIDE(2)=(FI1(2)-FI9(2))/ETADF1
      CELL,I,POINT B
      DPHIDZ(3)=XDIF(FI5,FI4,FI9(3),FI3(3))/ETADF2
      DPHIDE(3)=(FI3(3)-FI9(3))/ZETDF1
      CELL,I,POINT A
      DPHIDZ(8)=XDIF(FI1(8)-FI9(8))/ETADF1
      DPHIDE(8)=XDIF(FI7,FI8,FI9(8),FI1(8))/ZETDF2
      DO (BOUNDARY CONDITION SWITCHES)
      DO 1306, I=1,8
      ONOFF(I)=1
      IF(.NOT. INLET.AND..NOT.BOTTOM.AND..NOT.TOP) GOTO2060
      IF(TOP)IS=1
      IF(INLET)IS=3
      IF(BOTTOM)IS=5
      IE=IS+3
      DO 2059, I=IS,IE
      ONOFF(I)=0
      DO (VELOCITIES AND DENSITIES)
      U(6)=U(3)

```

```

QS019210
QS019220
QS019230
QS019240
QS019250
QS019260
QS019270
QS019280
QS019290
QS019300
QS019310
QS019320
QS019330
QS019340
QS019350
QS019360
QS019370
QS019380
QS019390
QS019400
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QS019540
QS019550
QS019560
QS019570
QS019580
QS019590
QS019600
QS019610
QS019620
QS019630
QS019640
QS019650
QS019660
QS019670
QS019680

```



```

V(6) = V(3)
U(7) = U(2)
DO 1337 I1 = 1, 8
  IF (I1 .GE. 4 .AND. I1 .NE. 8) GOTO 1337
  IF (I1 .LT. 4 .OR. I1 .EQ. 8) THEN
    U(I1) = DPHIDE(I1)*DEDY(I1) + DPHIDZ(I1)*DZDX(I1)
    V(I1) = DPHIDE(I1)*DEDY(I1) + DPHIDZ(I1)*DZDY(I1)
    IF (INDEX(I, J) .EQ. 0) GOTO 5411
    ICOUNT = ICOUNT + 1
    IIS = INDEX(ICOUNT)
    IF (I1 .LE. IIS) IIP = IIS
    IF (I1 .EQ. IIP) GOTO 5410
    IF (I1 .NE. IIP) GOTO 5410
    IF (I1 .GT. IIP .AND. IIP .NE. 8) GOTO 5410
    V(I1) = FAKEV(I, IDEX)
    U(I1) = FAKEU(I, IDEX)
    IDEX = IDEX + 1
    IIP = IIP + 1
  IF (I1 .NE. 8) ICOUNT = ICOUNT - 1
  V(I1) = V(I1) - SPAN(I1)*FIXR/RADLE*ROTATN
  UN(I1) = U(I1)*COSX(I1) + V(I1)*COSY(I1)
END
CONTINUE
IF (.NOT. TOP) GOTO 2064
IF (.TOP) THEN
  U(8) = (DPHIDE(8)*ETADFL-RADIUS(I, J)/RADLE*ROTATN*YDIF1)*EXDIF1/SLEN
  V(8) = (DPHIDE(8)*ETADFL-RADIUS(I, J)/RADLE*ROTATN*YDIF1)*YDIF1/SLEN
  ROTATX = ROTATN*RADIUS(I, J)/RADLE
  U8 = SQR((DPHIDE(8)*ETADFL/EXDIF1)**2 + (DPHIDE(8)*ETADFL/YDIF1-
1-ROTATX)**2)*EXDIF1/SQRT(SLEN)
  U8 = SQR(U(8)*U(8) + V(8)*V(8))*ABS(EXDIF1)/SQRT(SLEN)
  U(8) = SIGN(U8, U(8))
  V(8) = U(8)*YDIF1/EXDIF1
  UN(8) = U(8)*COSX(8) + V(8)*COSY(8)
END
C 2064
U(4) = PRIORS(3, J)
U(5) = PRIORS(4, J)
V(4) = PRIORS(5, J)
V(5) = PRIORS(6, J)
PRIORS(3, J) = U(1)
PRIORS(4, J) = U(8)
PRIORS(5, J) = V(1)
PRIORS(6, J) = V(8)
RHO(7) = RHO(2)
RHO(6) = RHO(3)
RHO(4) = PRIORS(7, J)

```

QSO19690
 QSO19700
 QSO19710
 QSO19720
 QSO19730
 QSO19740
 QSO19750
 QSO19760
 QSO19770
 QSO19780
 QSO19790
 QSO19800
 QSO19810
 QSO19820
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 QSO19930
 QSO19940
 QSO19950
 QSO19960
 QSO19970
 QSO19980
 QSO19990
 QSO20000
 QSO20010
 QSO20020
 QSO20030
 QSO20040
 QSO20050
 QSO20060
 QSO20070
 QSO20080
 QSO20090
 QSO20100
 QSO20110
 QSO20120
 QSO20130
 QSO20140
 QSO20150
 QSO20160


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RHO(5)=PRIORS(8,J)
ONSUM=0.
DO 1391 I1=1,8
IF(KK.LE.2.OR.MOD(KK,2).EQ.0) THEN
IF(I1.GE.4.AND.I1.NE.8) GOTO 2066
IF(I1.LT.4.OR.I1.EQ.8) THEN
RHO FAC=1.
RHO(I1)=1.
IF(I1.EQ.2.OR.I1.EQ.IEXIT).AND.J.LE.4.AND.ROTATN.NE.0.
1 OR.KK.LE.NOTYET) GOTO 2066
QSQR=U(I1)*U(I1)+(V(I1)*V(I1))
IF(QSQR.GE.QLIM) QSQR=.99*QLIM
RHO FAC=RHOCON*(1-QSQR)*ONOFF(I1)+1.
RHO(I1)=1.-AMZ*(QSQR-1.)+AMY*(QSQR-1.)*(QSQR-1.)
IF(QSQR.LT.65.OR.QSQR.GT.1.44) RHO(I1)=RHO FAC**EXPO
ROTATX=SPAN(I1)*FIXR
IF(ROTROT.NE.0..AND.J.GT.3)
1 RHO(I1)=(RHO(I1))* (1./EXPO)+RHOCON*ROTROT*((ROTATX/RADLE)
1**2-1.)*ONOFF(I1)**EXPO
END
END
QSQR=U(I1)*U(I1)+V(I1)*V(I1)
IF(I1.GT.1)
1 MACH(I1)=MINF*SQRT(QSQR)/RHO(I1)**(1./EXPO)
IF(MACH(I1).GT.2.) MACH(I1)=2.
CONTINUE
PRIORS(7,J)=RHO(1)
PRIORS(8,J)=RHO(8)
IF(I1.LF.1.OR.J.LE.3) GOTO 1427
IF(I1.GT.1.AND.J.GT.3) THEN
F(J)=1.
F(J)=0.
ONSUM=ONOFF(1)+ONOFF(8)+ONOFF(4)+ONOFF(5)
E(J)=(U(1)*ONOFF(1)+U(8)*ONOFF(8)+U(4)*ONOFF(4)+U(5)
1*ONOFF(5))/ONSUM
F(J)=(V(1)*ONOFF(1)+V(8)*ONOFF(8)+V(4)*ONOFF(4)+V(5)
1*ONOFF(5))/ONSUM
DUMBX(I,J)=E(J)
DUMBY(I,J)=F(J)
EFFAC=1.-E(J)*E(J)-F(J)*F(J)
DELPHI(J)=(RHO(1)*ONOFF(1)+RHO(8)*ONOFF(8)+RHO(4)*ONOFF(4)+RHO(5)
1*ONOFF(5))/ONSUM
D(J)=0
1 F(J)=MINF*SQRT((F(J)*F(J)+E(J)*E(J))/DELPHI(J)**(1./EXPO))
IF(J.LE.6.AND.(I.LE.4.OR.I.GE.IEXIT-2)) D(J)=EM
IF(J.LE.6.AND.I.GE.NOZ-1.AND.I.LE.NOZ+1) D(J)=MINF
DELP SV(I,J)=D(J)
END
C
2066
1391
C
C
C

```



```

2076 IF(E(J).NE.0.)BOPS=ATAN2(F(J),E(J))*180./PI
      BOPR=-999.
      IF(D(J).NE.0.)
        1BOPR=2./GAMMA*(DELPHI(J)*(1.-EFFAC)/D(J)/D(J)-1./MINF/MINF)
      IF(MINF.LT..25)BOPR=1.+DELPHI(J)*(EFFAC-1.)
      XOCX=(X(I,J)-XLOW)/(XHI-XLOW)
      FADBOP=(Y(I,J)-YLOW)/(XHI-XLOW)
      IF(ALLOUT.AND.MM2.EQ.1)
        1WRITE(6,12) J3M,XOCX,FADBOP,PHI(I,J),E(J),F(J),DELPHI(J)
      1,D(J),BOPS,BOPR
      1,TENOLF(I,J)=BOPR
      END
C
1427 CONTINUE
12  FORMAT(15X,I4,4X,9F10.5)
      RETURN
      END
      SUBROUTINE WRAPUP(ZETA,ETA,S)
C
      GEOMETRY GENERATION FOR CASCADE POTENTIAL FLOW SOLVER

      LOGICAL DOSURF,SMOOTH,BUG2,ORTHO
      REAL LAMDAO
      COMPLEX HI,H2,ORIGIN,CDWISE
      COMPLEX AI/(0.,1.)
      DOUBLE PRECISION CAPK,CAPKP
      DIMENSION ZETA(100),ETA(100),DUMBE(100),H1(100),H2(100)
      DIMENSION XB(200),YB(200),DUMBX(100,30)
      DIMENSION ENTIRE/ X(100,30),Y(100,30),PHI(100,30),DUMBY(100,30)
      COMMON/ENTIRE/ X(100,30),Y(100,30),PHI(100,30),DUMBY(100,30)
      COMMON/GEOM/NOZ,M,RLE,RTE,A,CHORD,XUPS,XDNS,LAMDAO,CC,CAPK
      1,CAPKP,PI
      1,RNK,V8,KN,NED,BB,DOSURF,RFAC,SOLID,MPLS
      1,STABAC,SLP1,SLP2,SLP3,SLP4,SMOOTH,CHOP,THETT,THETL
      1,NAMELIST/INSTUF/H1,H2,IMAXY,BUG2
      DATA ORTHO/.FALSE./,BUG2/.FALSE./

      MAGIC=0
      MAGICM=0

      REWIND 18
C
      RECORD OLD COMPUTATIONAL VARIABLES FOR INTERPOLATION IN FILPHI
      WRITE(18) ETA,ZETA
      PI=3.14159265

```



```

SO=CHORD
C   IF(NOZ.LT.0) OBTAIN MESH FROM STORAGE FILE
QSO21130
QSO21140
QSO21150
QSO21160
QSO21170
QSO21180
QSO21190
QSO21200
QSO21210
QSO21220
QSO21230
QSO21240
QSO21250
QSO21260
QSO21270
QSO21280
QSO21290
QSO21300
QSO21310
QSO21320
QSO21330
QSO21340
QSO21350
QSO21360
QSO21370
QSO21380
QSO21390
QSO21400
QSO21410
QSO21420
QSO21430
QSO21440
QSO21450
QSO21460
QSO21470
QSO21480
QSO21490
QSO21500
QSO21510
QSO21520
QSO21530
QSO21540
QSO21550
QSO21560
QSO21570
QSO21580
QSO21590
QSO21600

C   IF(NOZ.LT.0) OBTAIN MESH FROM STORAGE FILE
C   IF(NOZ.LT.0) GENERATE A NEW MESH
C   IEXIT=2*NOZ-1
C   NZZ=IEXIT
C   DOSURF=.TRUE.
C   IF(NED.LE.0)DOSURF=.FALSE.
C   NED=IABS(NED)
C   IF(DOSURF)READ(5,INSTUF,END=15)
C   WRITE(6,12)
C   FORMAT(37)THE FOLLOWING IS THE FIRST ECHO PRINT)
C   WRITE(6,INSTUF)
C   IF(DOSURF)READ(5,INSTUF,END=16)
C   WRITE(6,11)
C   FORMAT(38)THE FOLLOWING IS THE SECOND ECHO PRINT)
C   WRITE(6,INSTUF)
C   IF(KN.EQ.0)ORTHO=.TRUE.
C   IF(ORTHO) GOTO203
C   IF(.NOT.ORTHO) REARRANGE H2 INPUT INTO H1(UPPER SURFACE), AND H2(L
C   OWER SURFACE)
C   UNSTAGGERED DATA TABLES, FOR THE INTERPOLATION SCHEME
C   NEDKN1=NED-KN+1
C   ORIGIN=H2(NEDKN1)
C   DO 205 I1=1,KN
C   I5=NED-KN+I1
C   H1(I1)=H2(I5)
C   CDWISE =(H1(I1)-ORIGIN)*CEXP(-AI*LAMDA0)
C   H1(I1)=CDWISE
C   CONTINUE
C   DO 206 I1=1,NEDKN1
C   I6=NED-KN-I1+2
C   IF(I6.LE.0)I6=1
C   H1(KN+I1)=H2(I6)
C   DO 209 I1=1,NEDKN1
C   H2(I1)=H1(KN+I1)
C   CDWISE=(H2(I1)-ORIGIN)*CEXP(-AI*LAMDA0)
C   H2(I1)=CDWISE
C   CONTINUE
C   NED=NED+1
C   GOTO233

C   IF(ORTHO) REARRANGE H2 INPUT TO START AT MINIMUM Y POINT RATHER
C   THAN MAX X,

```


C FOR ELECTROSTATIC ANALOG SCHEME

203

T2=1.E10
IT2=0
DO 2333 I1=1,NED
IF(AIMAG(H2(I1)).GE.T2) GOTO2333
IT2=I1
T2=AIMAG(H2(IT2))
CONTINUE
DO 23333 I1=1,NED
I7=IT2+I1-1
IF(I7.EQ.NED)IT3=I1
IF(I7.GT.NED)I7=I1-IT3+1
23333 H1(I1)=H2(I7)
T2=-1.E10
I2T=0
DO 2033 I1=1,NED
IF(AIMAG(H1(I1)).LE.T2)GOTO2033
T2=AIMAG(H1(I1))
I2T=I1
H2(I1)=H1(I1)

2033

IMAXY=I2T

C LOAD COMPLEX INPUT INTO XBOD AND YBOD ARRAYS

233

CONTINUE
DO 213 K=1,NED
KMKN=K-KN
IF(K.GT.KN) GOTO217
IF(K.LE.KN) THEN
XB(K)=REAL(H1(K))
YB(K)=AIMAG(H1(K))
GOTO213
XB(K)=REAL(H2(KMKN))
YB(K)=AIMAG(H2(KMKN))
CONTINUE
IF(CHORD.EQ.1.) GOTO219
IF(CHORD.NE.1.) NORMALIZE COORDINATES TO AERODYNAMIC CHORD
DO 221 I2=1,NED
XB(I2)=XB(I2)/CHORD
YB(I2)=YB(I2)/CHORD
RLE=RLE/CHORD
S=S/CHORD
CHORD=1.
END

C

217

213

C

221

C

QSO21610
QSO21620
QSO21630
QSO21640
QSO21650
QSO21660
QSO21670
QSO21680
QSO21690
QSO21700
QSO21710
QSO21720
QSO21730
QSO21740
QSO21750
QSO21760
QSO21770
QSO21780
QSO21790
QSO21800
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QSO21830
QSO21840
QSO21850
QSO21860
QSO21870
QSO21880
QSO21890
QSO21900
QSO21910
QSO21920
QSO21930
QSO21940
QSO21950
QSO21960
QSO21970
QSO21980
QSO21990
QSO22000
QSO22010
QSO22020
QSO22030
QSO22040
QSO22050
QSO22060
QSO22070
QSO22080


```

219      IF(.NOT.ORTHO) GOTO225
C      IF(ORTHO) DO ELECTROSTATIC ANALOG GRID

227      DO 227 I2=1,NED
        HI(I2)=CMPLX(XB(I2),YB(I2))
        WRITE(6,9)
9        FORMAT(IH1,40X,' ELECTROSTATIC ANALOG GRID GENERATED.')
        CALL PJGRID(ZETA,ETA,HI,IMAXY,S)
        GOTO226

C      OTHERWISE DO INTERPOLATION SCHEME GRID

225      WRITE(6,10)
10      FORMAT(IH1,40X,' INTERPOLATION SCHEME GRID GENERATED.')
        CALL GRIDDL(ZETA,ETA,XB,YB,S)

C      WRITE MESH POINTS STORAGE FILE

226      WRITE(13,1) NOZ,M,KN,NED
        WRITE(13,2)((X(I,J),I=1,NZZ),J=1,M),((Y(I,J),I=1,NZZ),J=1,M)
        I,(ETA(I),I=1,NZZ),(ZETA(J),J=1,M)

        GOTO202

C      FOR EXISTING MESH FILES, NORMALIZE PARAMETERS AND READ FILE

201      IF(CHORD.EQ.1.) GOTO231
C      IF(CHORD.NE.1.) THEN
        RLE=RLE/CHORD
        RTE=RTE/CHORD
        S=S/CHORD
        CHORD=1.
      END

C      231      READ(23,1) NOZZ,MM,KN,NED
        MAGIC=1ABS((NOZZ-1)/(NOZ+1))
        M=MM
        NOZ=NOZZ
        IEXIT=2*NOZ-1
        NZZ=1EXIT
        READ(23,2)((X(I,J),I=1,NZZ),J=1,M),((Y(I,J),I=1,NZZ),J=1,M)

```

502222090
 502221100
 502221110
 502221120
 502221130
 502221140
 502221150
 502221160
 502221170
 502221180
 502221190
 502222000
 502222110
 502222220
 502222230
 502222240
 502222250
 502222260
 502222270
 502222280
 502222290
 502222300
 502222310
 502222320
 502222330
 502222340
 502222350
 502222360
 502222370
 502222380
 502222390
 502222400
 502222410
 502222420
 502222430
 502222440
 502222450
 502222460
 502222470
 502222480
 502222490
 502222500
 502222510
 502222520
 502222530
 502222540
 502222550
 502222560


```

      1,(ETA(1),I=1,NZZ),(ZETA(J),J=1,M)
C      IF FINEST MESH IS DESIRED, SKIP SELECTION PROCESS
      IF(MAGIC.LE.1.AND.MAGICM.LE.1) GOTO202
      IF(MAGIC.GT.1.OR.MAGICM.GT.1) SELECT AND LOAD GRID LINES DESIRED
      O FORM
      A COARSE MESH
      DO 235 J=1,M,MAGICM
      JON=(J-1)/MAGICM+1
      ZETA(JON)=ZETA(J)
      DO 239 I=1,NZZ,MAGIC
      ION=(I-1)/MAGIC+1
      DUMBX(ION,JON)=X(I,J)
      DUMBY(ION,JON)=Y(I,J)
      IF(MOD(ION,2).EQ.0) ION=ION-1
239      C      RADIATING LINE TO UPSTREAM INFINITY MUST BE INCLUDED
      DUMBX(ION,JON)=X(NZZ,J)
      DUMBY(ION,JON)=Y(NZZ,J)
      NOZZ=(ION+1)/2
      C      RADIATING LINE TO DOWNSTREAM INFINITY MUST BE INCLUDED
235      DUMBX(NOZZ,JON)=X(NOZZ,J)
      DUMBY(NOZZ,JON)=Y(NOZZ,J)
      DO 243 I=1,ION
      IOLD=(I-1)*MAGIC+1
      ETA(I)=ETA(IOLD)
      C      BLADE SURFACE MUST BE LAST CLOSED CURVE
      DUMBX(I,JON)=X(IOLD,M)
      DUMBY(I,JON)=Y(IOLD,M)
      C      PERIODIC BOUNDARY MUST BE FIRST CLOSED CURVE
243      DUMBX(I,1)=X(IOLD,1)
      DUMBY(I,1)=Y(IOLD,1)
      DUMBX(ION,JON)=X(NZZ,M)
      DUMBY(ION,JON)=Y(NZZ,M)
      DUMBX(ION,1)=X(NZZ,1)
      DUMBY(ION,1)=Y(NZZ,1)
      DUMBX(NOZZ,M)=X(NOZZ,M)
      DUMBY(NOZZ,M)=Y(NOZZ,M)
      DUMBX(NOZZ,1)=Y(NOZZ,1)
      DUMBY(NOZZ,1)=X(NOZZ,1)

```



```

251      DO 251 J=1, JON
        DO 251 I=1, ION
          X(I,J)=DUMBX(I,J)
          Y(I,J)=DUMBY(I,J)
          ZETA(JON)=ZETA(M)
          ETA(ION)=ETA(NZZ)
          ETA(NZZ)=ETA(NOZ)
          NZZ=ION
          IEXIT=NZZ
          NOZ=NOZZ
          M=JON
        END OF SELECTION PROCESS
      CONTINUE
202      IF(.NOT.BUG2) GOTO255
      IF(BUG2) THEN
        WRITE(6,3) NOZ,M,KN,NED
        FORMAT(10NOZ= ',13,' M= ',13,' KN= ',13,' NED= ',13)
        NEDM1=NED-1
      FOR A NEW GEOMETRY GENERATION, CALCULATE THE SECOND DERIVATIVES
      N BLADE
      SURFACE USING SMOOTHED INPUT COORDINATES
      DO 257 I=2, NEDM1
        DUMBX(I,15)=1.E06
        IF(XB(I).NE.XB(I-1)).AND.XB(I).NE.XB(I+1)).AND.
          1XB(I+1).NE.XB(I-1))
          1DUMBX(I,15)=((YB(I+1)-YB(I))/(XB(I+1)-XB(I))-(YB(I)-YB(I-1)))/
          1(XB(I)-XB(I-1))/(XB(I+1)-XB(I-1))*2.
        CONTINUE
      WRITE(6,5)
      FORMAT(1H0,35X,' SMOOTHED BLADE SURFACE Y INPUT, HORIZONTAL CHORD')
      FORMAT(1H0,35X,' I GRID POINTS, AS STORED ON MESH FILE.')
      FORMAT(1H0,20X,' X GRID POINTS, AS STORED ON MESH FILE.')
      FORMAT(1H0,20X,' Y GRID POINTS, AS STORED ON MESH FILE.')
      FORMAT(35X,14,3E13.5)
      WRITE(6,4) (I,XB(I),YB(I),DUMBX(I,15),I=1,NED)
      WRITE(6,6)
      WRITE(6,2)((X(I,J),I=1,NZZ),J=1,M)
      WRITE(6,7)

```



```

1      WRITE(6,2) ((Y(I,J), I=1,NZZ), J=1,M)
14     FORMAT(4I5)
2      FORMAT(1H, 14E9.3)
      FORMAT(6E13.5)

255    IF(KN.NE.0) GOTO 261
C      IF(ORTHO) TRANSLATE THE ORIGIN OF X POINTS TO MIDCHORD (INTERP SCH
C      EME
C      ALREADY TRANSLATED

263    DO 263 I1=1,NZZ
      DO 263 J1=1,M
      X(I1,J1)=X(I1,J1)-.5

      REARRANGE (X,Y) TABLES SO THAT X(2,J),Y(2,J) AND X(NZZ+1,J),Y(NZZ
      +1,J) GO
      TO DOWNSTREAM INFINITY, AND X(NOZ+1,J),Y(NOZ+1,J) GOES TO UPSTREA
      M INFINITY
      NUMBERING THE LINES CLOCKWISE AROUND THE BLADE. AT PRESENT, LINE
      1 GOES
      TO UPS. INF., NOZ GOES TO DOWNS. INF. AND NZZ TO UPS. INF.

      ALSO REALIGN ETA SO THAT VALUES WILL GO FROM ZERO (LINE 2) TO 2*
      CAPKP (LINE
      NZZ+1), INSTEAD OF -CAPKP (LINE 1) TO +CAPKP (LINE NZZ).

261    DO 271 I1=1,NZZ
      DO 271 J1=1,M
      I2=I1+NOZ-1
      DUMBE(I1)=-ETA(I2)
      DUMBX(I1,J1)=X(I1,J1)
      DUMBY(I1,J1)=Y(I1,J1)
      X(I1,J1)=X(I1+NOZ-1,J1)
      Y(I1,J1)=Y(I1+NOZ-1,J1)
      NOZP1=NOZ+1
      DO 279 I1=NOZP1,NZZ
      DO 279 J1=1,M
      I2=I1-NOZ+1
      DUMBE(I1)=-ETA(I2)+2.*ETA(1)
      DUMBX(I1,J1)=X(I1,J1)
      DUMBY(I1,J1)=Y(I1,J1)
      X(I1,J1)=DUMBX(I1-NOZ+1,J1)
      Y(I1,J1)=DUMBY(I1-NOZ+1,J1)

279    MOVE ALL VALUES UP 3 LOCATIONS IN J TO MAKE ROOM FOR 3 DUMMY ELI
C      PSES

```



```

C      BEYOND THE PERIODIC LINE.
2088      I1=IEXIT
2955      IF(I1.LT.1)GOTO2872
2087      J1=M
      IF(J1.LT.1)GOTO2871
      X(I1,J1+3)=X(I1,J1)
      IF(I1.EQ.1)ZETA(J1+3)=ZETA(J1)
287      Y(I1,J1+3)=Y(I1,J1)
      J1=J1-1
      GOTO2087
2871      I1=I1-1
      GOTO2088

C      FINISH LOADING ETA; CREATE 3 DUMMY LINES USING PERIODIC RELATION
C      OF X,Y VALUES
2872      I1=IEXIT
295      IF(I1.LT.2)GOTO2951
      ETA(I1)=DUMBE(I1)
      DO 299 J1=1,3
      SIGEN=1;
      IF(I1.LT.NOZ)SIGEN=-1.
      IF(I1.EQ.NOZ)SIGEN=0;
      X(I1,J1)=X(IEXIT-I1+1,8-J1)+S*SIN(LAMDAO)*SIGEN
      IF(I1.EQ.2)ZETA(J1)=-ZETA(8-J1)
299      Y(I1,J1)=Y(IEXIT-I1+1,8-J1)+S*COS(LAMDAO)*SIGEN
      ETA(I1+1)=ETA(I1)

C      LOAD SPECIAL POINTS (J=4 NOW EQUALS PERIODIC LINE POINTS)
2951      I1=I1-1
      GOTO 295
      ETA(2)=0.
      ETA(IEXIT+1)=2.*ETA(1)
      X(IEXIT,1)=2.*X(IEXIT,4)
      X(IEXIT,2)=1.5*X(IEXIT,4)
      X(IEXIT,3)=1.2*X(IEXIT,4)
      Y(IEXIT,1)=2.*Y(IEXIT,4)
      Y(IEXIT,2)=1.5*Y(IEXIT,4)
      Y(IEXIT,3)=1.2*Y(IEXIT,4)
      X(NOZ,1)=2.*X(NOZ,4)
      X(NOZ,2)=1.5*X(NOZ,4)
      X(NOZ,3)=1.2*X(NOZ,4)
      Y(NOZ,1)=2.*Y(NOZ,4)
      Y(NOZ,2)=1.5*Y(NOZ,4)

```

```

QSO24010
QSO24020
QSO24030
QSO24040
QSO24050
QSO24060
QSO24070
QSO24080
QSO24090
QSO24100
QSO24110
QSO24120
QSO24130
QSO24140
QSO24150
QSO24160
QSO24170
QSO24180
QSO24190
QSO24200
QSO24210
QSO24220
QSO24230
QSO24240
QSO24250
QSO24260
QSO24270
QSO24280
QSO24290
QSO24300
QSO24310
QSO24320
QSO24330
QSO24340
QSO24350
QSO24360
QSO24370
QSO24380
QSO24390
QSO24400
QSO24410
QSO24420
QSO24430
QSO24440
QSO24450
QSO24460
QSO24470
QSO24480

```



```

C      DO (CALCULATION OF GEOMETRY CONSTANTS)
C      PROCEDURE (CALCULATION OF GEOMETRY CONSTANTS)
A= COS(LAMDAO)/2./SOLIDO
K= EXP(-PI/2./A)
LNK= -A*LOG(K)
M=K*K
DM=M
DM1=1,DO-DM
M1=DM1
CAPK=MMDELK(1,DM,IER)
CAPKP=MMDELK(1,DM1,IER)
END
C
C      DO (KNOWN GRID COORDINATES, ET,ZET)
C      PROCEDURE (KNOWN GRID COORDINATES, ET,ZET)
DELZ=CAPKP/(ZNO-1)
DELE=CAPK*STABAC/(ENO-1)
ZN2M1=2*ZNO-1
ZET(1)=+CAPKP
DO 217 NZ=2,ZN2M1
ZET(NZ)=ZET(NZ-1)-DELZ
ET(1)=0.
ZN2=2*ZNO
DO 221 NE=2,ENOPLS
ET(NE)=ET(NE-1)+DELE
ET(ENO)=STABAC*CAPK
ZET(ZNO)=0.
IF (SLP1.GE.0.)GOTO205
C      IF (SLP1.LT.0.) DO (CONCENTRATION OF GRID LINES IN KEY AREAS)
C      PROCEDURE (CONCENTRATION OF GRID LINES IN KEY AREAS)
XTES=-1.E19
ITS=1
SLP1=-SLP1
C      IF SLP2.LT.0 SETUP THE PROPER STAGGERED FLATPLATE MESH TO FIND WH
C      ICH LINE
C      INTERSECTS T. E.
C      IF (SLP2.GE.0.:OR.S.NE.2.*PI) GOTO226
DELTA=ABS(SLP2)

```



```

C      DO (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y UPPER SURFACE)
C      PROCEDURE (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y UPPER SURFACE)
DO 2060 I=1,ZNO
DO 2060 J=1,ENOPLS
IF(I.EQ.1.OR.I.EQ.ZNO).AND.J.EQ.1) GOTO2060
ETER=ET(J)

C      DO (YOUR BASIC TRANSFORMATION )
C      PROCEDURE (YOUR BASIC TRANSFORMATION )
ZED=ZET(I)
IF(ETER.GT.CAPK) ZED=-ZED
IF(ETER.GT.CAPK) ETER=2.*CAPK-ETER
IF(I.EQ.ZNO) ZED=0.
ALLFNC=FUDS(ETER, ZED,M1)
LAM = BADZAC(M1)
TH = OWOW(M1)
X(I,J)= CHORD*A/PI*(LNK-2.*ALOG(ALLFNC/LAM))
IF(J.GT.ENO.AND.I.EQ.ZN2M1) X(I,J)=-CHORD-X(I,J)
IF(J.GT.ENO.AND.I.EQ.ZNO) X(I,J)=CHORD-X(I,J)
Y(I,J)= 2.*A*CHORD/PI*TH
IF(X(I,J).GT.XDNS) X(I,J)=XDNS
IF(X(I,J).LT.XUPS) X(I,J)=XUPS
END

C      2060
C      CONTINUE
C      END

C      DO (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y LOWER SURFACE)
C      PROCEDURE (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y LOWER SURFACE)
DO 2071 I=ZNPI,ZN2M1
IDIF=I-ZNO
X(I,1)=X(ZNO-IDIF,1)-S*SIN(LAMDAO)
Y(I,1)=-A*CHORD
DO 2071 J=1,ENOPLS
IF(I.EQ.ZN2M1.AND.J.EQ.1) GOTO2071
ETER=ET(J)

C      DO (YOUR BASIC TRANSFORMATION )
C      PROCEDURE (YOUR BASIC TRANSFORMATION )
ZED=ZET(I)
IF(ETER.GT.CAPK) ZED=-ZED
IF(ETER.GT.CAPK) ETER=2.*CAPK-ETER
IF(I.EQ.ZNO) ZED=0.
ALLFNC=FUDS(ETER, ZED,M1)
LAM = BADZAC(M1)
TH = OWOW(M1)
X(I,J)= CHORD*A/PI*(LNK-2.*ALOG(ALLFNC/LAM))

```



```

IF(J.GT.ENO.AND.I.EQ.ZN2M1)X(I,J)=-CHORD-X(I,J)
IF(J.GT.ENO.AND.I.EQ.ZNO)X(I,J)=CHORD-X(I,J)
Y(I,J)=2.*A*CHORD/PI*TH
IF(X(I,J).GT.XDNS)X(I,J)=XDNS
IF(X(I,J).LT.XUPS)X(I,J)=XUPS
END

```

```

C
2071 CONTINUE
C END

```

```

CALL TOSTAG(S,ZET,CHORD)
DO 234 I3=1,ZN2M1
IF(X(I3,ENO).LE.XTES) GOTO234
WRITE(6,4445) XTES,I3,X(I3,ENO)
FORMAT(E13.5,I6,E13.5)
XTFS=X(I3,ENO)
ITS=I3
CONTINUE

```

```

234 EF=ZET(ITS)/CAPKP
IF(SLP1.EQ.10.) EF=1.-EF
SLP1=(1.-DELTA/EF*(.6667-.2/EF/EF))/
1(I1.-1./EF/EF*(.6667-.2/EF/EF))
SLP2=3.-SLP1*(2.-1./2.5/EF**4)-DELTA/2.5/EF**4
226 CONTINUE

```

```

C CONCENTRATE THE RADIATING LINES (COMPUTATIONAL COORD ZET)

```

```

C DO (CONCENTRATION POLYNOMIAL)
C PROCEDURE (CONCENTRATION POLYNOMIAL)
CON1=2.5*(1.-SLP1)/CAPKP**2
CON2=(SLP2-SLP1)/(2.*CAPKP**2)
CON1=CON1-CON2
CON3=(SLP2-SLP1)/(2.*CAPKP**4)
CON4=1.5*(1.-SLP1)/(CAPKP**4)
CON3=CON3-CON4
C END

```

```

DO 237 I3=1,ZN2M1
CAPFAC=0.
ZETER1=ZET(I3)
ZET(I3)=SLP1*ZETER1+CON1*ZETER1**3+CON3*ZETER1**5-CAPFAC
237 IF(DELTA.EQ.0.) GOTO241
EF=1.-EF
SLP1=(1.-DELTA/EF/EF*(.6667-.2/EF/EF))/
1(I1.-1./EF/EF*(.6667-.2/EF/EF))
SLP2=3.-SLP1*(2.-1./2.5/EF**4)-DELTA/2.5/EF**4

```

QSO26890
QSO26900
QSO26910
QSO26920
QSO26930
QSO26940
QSO26950
QSO26960
QSO26970
QSO26980
QSO26990
QSO27000
QSO27010
QSO27020
QSO27030
QSO27040
QSO27050
QSO27060
QSO27070
QSO27080
QSO27090
QSO27100
QSO27110
QSO27120
QSO27130
QSO27140
QSO27150
QSO27160
QSO27170
QSO27180
QSO27190
QSO27200
QSO27210
QSO27220
QSO27230
QSO27240
QSO27250
QSO27260
QSO27270
QSO27280
QSO27290
QSO27300
QSO27310
QSO27320
QSO27330
QSO27340
QSO27350
QSO27360


```

C      DO (CONCENTRATION POLYNOMIAL)
C      PROCEDURE (CONCENTRATION POLYNOMIAL)
CON1=2.5*(1.-SLP1)/CAPKP**2
CON2=(SLP2-SLP1)/(2.*CAPKP**2)
CON1=CON1-CON2
CON3=(SLP2-SLP1)/(2.*CAPKP**4)
CON4=1.5*(1.-SLP1)/(CAPKP**4)
CON3=CON3-CON4
END
C
C      CONCENTRATE THE SURFACE CONTOURS (COMPUTATIONAL COORD ET)
DO 244 I3=1,ZN2M1
CAPFAC=0.
ZETER1=ZET(I3)
ZET(I3)=SLP1*ZETER1+CON1*ZETER1**3+CON3*ZETER1**5-CAPFAC
CON5=2.5*(1.-SLP3)/CAPKP**2
CON6=(SLP4-SLP3)/(2.*CAPKP**2)
CON5=CON5-CON6
CON7=(SLP4-SLP3)/2/CAPKP**4
CON8=1.5*(1.-SLP3)/CAPKP**4
CON7=CON7-CON8
DO 248 J3=1,ENOPLS
IF(J3.GT.ENO)ET(J3)=2.*CAPK-ET(J3)
ET(J3)=SLP3*ET(J3)+CON5*ET(J3)**3+CON7*ET(J3)**5
IF(J3.GT.ENO)ET(J3)=2.*CAPK-ET(J3)
CONTINUE
SLP1=-SLP1
IF(DELTA.NE.0.)SLP2=-DELTA
FORMAT(6E13.5)
END
C      END OF CONCENTRATION PROCEDURE
C
C      X(1,1)=XUPS
X(ZN0,1)=XDNS
X(ZN2M1,1)=XUPS
ZNOM1=ZN0-1
C
C      DO (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y UPPER SURFACE)

```



```

C      PROCEDURE (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y UPPER SURFACE)
C      DO 260 I=1,ZNO
C      DO 260 J=1,ENOPLS
C      IF((I.EQ.1.OR.I.EQ.ZNO).AND.J.EQ.1) GOTO260
C      ETER=ET(J)
C
C      DO (YOUR BASIC TRANSFORMATION )
C      PROCEDURE (YOUR BASIC TRANSFORMATION )
C      ZED=ZET(I)
C      IF(ETER.GT.CAPK)ZED=-ZED
C      IF(ETER.GT.CAPK) ETER=2.*CAPK-ETER
C      IF(I.EQ.ZNO)ZED=0.*CAPK-ETER
C      ALLFNC=FUDS(ETER, ZED,M1)
C      LAM = BADZAC(M1)
C      TH = OWOW(M1)
C      X(I,J)= CHORD*A/PI*(LNK-2.*ALOG(ALLFNC/LAM))
C      IF(J.GT.END.AND.I.EQ.ZN2M1)X(I,J)=-CHORD-X(I,J)
C      IF(J.GT.END.AND.I.EQ.ZNO)X(I,J)=CHORD-X(I,J)
C      Y(I,J)= 2.*A*CHORD/PI*TH
C      IF(X(I,J).GT.XDNS)X(I,J)=XDNS
C      IF(X(I,J).LT.XUPS)X(I,J)=XUPS
C      END
C
C      CONTINUE
C      END
C
C      ZNP1=ZNO+1
C      FK=1./SQRT(K)
C      NZN2M2=ZN2M1-1
C
C      DO (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y LOWER SURFACE)
C      PROCEDURE (FLATPLATE-ZERO STAGGER TRANSFM. E,Z-X,Y LOWER SURFACE)
C      DO 271 I=ZNP1,ZN2M1
C      IDIF=I-ZNO
C      X(I,1)=X(ZNO-IDIF,1)-S*SIN(LAMDA0)
C      Y(I,1)=-A*CHORD
C      DO 271 J=1,ENOPLS
C      IF(I.EQ.ZN2M1.AND.J.EQ.1) GOTO271
C      ETER=ET(J)
C
C      DO (YOUR BASIC TRANSFORMATION )
C      PROCEDURE (YOUR BASIC TRANSFORMATION )
C      ZED=ZET(I)
C      IF(ETER.GT.CAPK)ZED=-ZED
C      IF(ETER.GT.CAPK) ETER=2.*CAPK-ETER

```



```

IF(I.EQ.ZNO)ZED=0.      ZED,M1)
ALLFNC=FUDS(ETER)
LAM = BADZAC(M1)
TH = OWOW(M1)
X(I,J)= CHORD*A/PI*(LNK-2.*ALOG(ALLFNC/LAM))
IF(J.GT.ENO.AND.I.EQ.ZN2M1)X(I,J)=-CHORD-X(I,J)
IF(J.GT.ENO.AND.I.EQ.ZNO)X(I,J)=CHORD-X(I,J)
Y(I,J)= 2.*A*CHORD/PI*TH
IF(X(I,J).GT.XDNS)X(I,J)=XDNS
IF(X(I,J).LT.XUPS)X(I,J)=XUPS
END

```

C

```

CONTINUE
END

```

271
C

```

DO (SPECIAL POINTS)

```

C

```

PROCEDURE (SPECIAL POINTS)

```

C

```

DO 278 J=1, ENOPLS

```

```

X(I,J)=X(ZN2M1,J)

```

```

Y(ZN2M1,J)=0.

```

```

Y(ZNO,J)=0.

```

```

Y(I,J)=0.

```

278
C

```

IF(STAG.EQ.0.) GOTO 209

```

```

DO (CIRCLE TRANSF. FROM ZERO STAGGER TO INPUT VALUES)

```

C

```

PROCEDURE (CIRCLE TRANSF. FROM ZERO STAGGER TO INPUT VALUES)

```

C

```

CALL TOSTAG(S,ZET,CHORD)
CHORD=CHORD-RLE/2.-RLE/2.

```

```

LAMDA0=STAG

```

```

SOLID0=SOLFLT

```

```

S=CHORD/SOLFLT

```

```

OLDK=CAPK

```

```

OLDKP=CAPKP

```

```

DO (CALCULATION OF GEOMETRY CONSTANTS)

```

C

```

PROCEDURE (CALCULATION OF GEOMETRY CONSTANTS)

```

C

```

A= COS(LAMDA0)/2./SOLID0

```

```

K= EXP(-PI/2./A)

```

```

LNK= -ALOG(K)

```

```

M=K*K

```

```

DM=M

```

QSO28330
QSO28340
QSO28350
QSO28360
QSO28370
QSO28380
QSO28390
QSO28400
QSO28410
QSO28420
QSO28430
QSO28440
QSO28450
QSO28460
QSO28470
QSO28480
QSO28490
QSO28500
QSO28510
QSO28520
QSO28530
QSO28540
QSO28550
QSO28560
QSO28570
QSO28580
QSO28590
QSO28600
QSO28610
QSO28620
QSO28630
QSO28640
QSO28650
QSO28660
QSO28670
QSO28680
QSO28690
QSO28700
QSO28710
QSO28720
QSO28730
QSO28740
QSO28750
QSO28760
QSO28770
QSO28780
QSO28790
QSO28800


```

DM1=1,DO-DM
M1=DM1
CAPK=MMDELK(1,DM,IER)
CAPKP=MMDELK(1,DM1,IER)
END
C
DO 283 I1=1,ENOPLS
ET(I1)=ET(I1)*CAPK/OLDK
DO 287 I1=1,ZN2M1
ZET(I1)=ZET(I1)*CAPKP/OLDKP
END
C
283
287
C
209
C
DO (TRANSLATE ORIGIN OF INPUT BODY POINTS TO MIDCHORD)
C
C
PROCEDURE (TRANSLATE ORIGIN OF INPUT BODY POINTS TO MIDCHORD)
DO 291 L=1,END
XBOD(L)=XBOD(L)-RLE/2.-.5*CHORD
END
C
291
C
C
DO (TRAILING EDGE FIX OF CAMBER POINTS)
C
C
PROCEDURE (TRAILING EDGE FIX OF CAMBER POINTS)
ENOP1=ENO+1
DO 295 J=ENOP1,ENOPLS
JNEXT=2*ENO-J
FAD=1
IF(X(ZNO+1,ENO)-X(ZNO-1,ENO).NE.0.)
1FAD=(X(ZNO,ENO)-X(ZNO-1,ENO))/(X(ZNO+1,ENO)-X(ZNO-1,ENO))
IFAB=1
IF(X(2,ENO)-X(ZN2M1-1,ENO).NE.0.)
1FAB=(X(1,ENO)-X(ZN2M1-1,ENO))/(X(2,ENO)-X(ZN2M1-1,ENO))
X(ZNO,J)=X(ZNO-1,J)+FAD*(X(ZNO+1,J)-X(ZNO-1,J))
Y(ZNO,J)=Y(ZNO-1,J)+FAD*(Y(ZNO+1,J)-Y(ZNO-1,J))
X(1,J)=X(ZN2M1-1,J)+FAB*(X(2,J)-X(ZN2M1-1,J))
Y(1,J)=Y(ZN2M1-1,J)+FAB*(Y(2,J)-Y(ZN2M1-1,J))
X(ZN2M1,J)=X(1,J)
Y(ZN2M1,J)=Y(1,J)
END
C
295
C
DO (ADDITION OF BLADE SURFACE ON CLEAN MESH)
IF(DOSURF) CALL SURFUP(ET,ZET,XBOD,YBOD,EF)

```


7777 FORMAT(14E9.3)

RETURN

```

C-----CALCS COMPLETE ELLIPTIC INTEGRAL OF FIRST KIND FOR MODULUS SQUARED
      = ARG
      DOUBLE PRECISION ARG,PI,A,B,C,A0,B0
      DATA PI/3.141592653589793D0/
      IER = 130
      IF( ILPT.NE.1) STOP 105
      IF( ARG.LT.0.D0.OR.ARG.GE.1.D0) GOTO40
      IER = 0
      A = 1.D0
      B = DSQRT(1.D0 - ARG)
      DO 10 I = 1,15
      C = .5D0 * (A - B)
      IF(DABS(C).LT.1.D-12) GOTO15
      A0 = A
      B0 = B
      A = .5D0 * (A0 + B0)
      B = DSQRT(A0 * B0)
      CONTINUE
      IF(I.GT.15) STOP 110
      MMDELK = .5D0 * PI / A
      RETURN
      END
      SUBROUTINE SURFUP(ET,ZET,XBOD,YBOD,EF)

```

10
15
40

QSO29290
QSO29300
QSO29310
QSO29320
QSO29330
QSO29340
QSO29350
QSO29360
QSO29370
QSO29380
QSO29390
QSO29400
QSO29410
QSO29420
QSO29430
QSO29440
QSO29450
QSO29460
QSO29470
QSO29480
QSO29490
QSO29500
QSO29510
QSO29520
QSO29530
QSO29540
QSO29550
QSO29560
QSO29570
QSO29580
QSO29590
QSO29600
QSO29610
QSO29620
QSO29630
QSO29640
QSO29650
QSO29660
QSO29670
QSO29680
QSO29690
QSO29700
QSO29710
QSO29720
QSO29730
QSO29740
QSO29750
QSO29760

Q S030250
Q S030260
Q S030270
Q S030280
Q S030290
Q S030300
Q S030310
Q S030320
Q S030330
Q S030340
Q S030350
Q S030360
Q S030370
Q S030380
Q S030390
Q S030400
Q S030410
Q S030420
Q S030430
Q S030440
Q S030450
Q S030460
Q S030470
Q S030480
Q S030490
Q S030500
Q S030510
Q S030520
Q S030530
Q S030540
Q S030550
Q S030560
Q S030570
Q S030580
Q S030590
Q S030600
Q S030610
Q S030620
Q S030630
Q S030640
Q S030650
Q S030660
Q S030670
Q S030680
Q S030690
Q S030700
Q S030710
Q S030720

```

DOUBLE PRECISION CAPK,CAPKP
COMMON/GEOM/ZNO,ENO,RLE,RTE,A,CHORD,XUPS,XDNS,LAMDAO,CC,CAPK
1,CAPKP,PI
1,*,LNK,M1,KM,END,M,DOSURF,AARR,SOL,ENOPLS
1,SDUM(5),SMOOTH,CHOP,THETT,THETL,TDUM,LEONLY
COMMON/ENTIRE/XX(100,30),YY(100,30)
COMMON/SPGENC/DA,DSMAX,RMAX,THIN,DB,TMIN,DSEND
COMMON/FUNCOS/S,C,D,SN,CN,DN
COMMON/MAN/DELSMX,PI02,DELSI,IHUB
DIMENSION XBOD(200),YBOD(200),SU(400),SD(400),ET(100),ZET(100),
1,ISAVE(25),SEDGT(400),SEDGL(400),SDXETA(400),SXYETA(400),SDYETA(400)
1,INTEGER ZNO,ENO,END,ZN2M1,ENOPLS,ENDM1,ENPOLLS,ENDMM1,ENM1
LOGICAL DUM,RZTRP,I2TRP,THIN,DONE,SMOOTH,DOSURF,LEONLY
LOGICAL TE,RELAXD,BOTTOM,FALSE,/,FAILD,/,FALSE,/,EDGES,/,FALSE,/.
COMPLEX FZTRP,DZTRP,FZ,Z(400),Z2(400),XOETA(400),YOETA(400)
1,EDGL(400),EDGT(400),XYETA(400),YYETA(400)
1,REAL M,M1,LNK,LAMDAO
NAMELIST/SPGENS/DA,DSMAX,RMAX,THIN,DB,TMIN,DSEND
NAMELIST/TE SY/I,IS,ETA,Y,X,SPX,SPE,ITST,DF1DN,DF2DN,DF3DX,
1,F1,F2,F3,DELN,DELX,DELY,FZ,SP
NAMELIST/TE SX/ XYETA,SXYETA,YYETA,SYETA
DATA Z/400*(1.E20,0.)/
DATA Z2/400*(1.E20,0.)/
DATA EDGT,EDGL,XOETA,YOETA,XYETA,YYETA/2400*(1.E20,0.)/

ET(END)=CAPK
DELSMX=.06667
PI02=1.57079
THETT=THETT*PI/180.
THETL=THETL*PI/180.
ISA=1
PLATE=(CHORD-RLE/2.-RTE/2.)/2.

```

C DO (BODY COORDINATE LOADING)

C PROCEDURE (BODY COORDINATE LOADING)

IF(.NOT.SMOOTH) GOT0222


```

IF(LEONLY) GOTO1008
      KMH=(KM+1)/2
      IF(MOD(KM,2).NE.0)KMH=KMH-1
      DO 234 I1=1,KMH
      I5=I1+KMH
      Z(I1)=CMPLX(XBOD(I5),YBOD(I5))
      IF(MOD(KM,2).NE.0)
      1 Z(KMH+1)=CMPLX(XBOD(I5+1),YBOD(I5+1))
      IF(MOD(KM,2).NE.0)KMH=KMH+1
      KWOW=KMH+1+END-KM-2-(KM+1)/2+KM/2
      KMH1=KMH+1
      DO 240 I1=KMH1,KWOW
      I5=END-I1+KMH
      Z(I1)=CMPLX(XBOD(I5),YBOD(I5))
      KWOWP1=KWOW+1
      ENDMM1=END-1
      DO 244 I1=KWOWP1,ENDMM1
      I5=I1-END+(KM-1)/2+3-MOD(KM,2)
      Z(I1)=CMPLX(XBOD(I5),YBOD(I5))
      GOT0225
      KMH=END-KM
      DO 226 I1=1,KMH
      I5=END-I1+1
      Z(I1)=CMPLX(XBOD(I5),YBOD(I5))
      KWOW=END-1
      KMH1=KMH+1
      DO 230 I1=KMH1,KWOW
      I5=I1-KMH+1
      Z(I1)=CMPLX(XBOD(I5),YBOD(I5))
      FORMAT(6E13.5)
      ENDM1=END-1
      WRITE(6,1234) (Z(IW),IW=1,ENDM1),
      1 (XBOD(IQ),YBOD(IQ),IQ=1,END)
      FORMAT(10E13.6)
      DA=17
      WRITE(6,1235)
      FORMAT(55H0THE FOLLOWING IS A PRINT
      1235 WRITE(6,*)Z
      C CALL XYCALC(1,ENDM1,Z,SU,SD)
      C WRITE(6,1236)
      1236 FORMAT(69H0THE FOLLOWING IS A PRINT
      C +E CALL XYCALC)
      C WRITE(6,*)Z
      C WRITE(6,*)SU
      C WRITE(6,*)SD

```

OF THE Z MATRIX FROM SURFUP)

OF Z,SU,SD MATRICES AFTER TH


```

248      END=ENDM1
      ITS=0.
      XTS=0.
      DO 248 I1=1,END
      IF (SU(I1).GT.XTS) ITS=I1
      IF (SU(I1).GT.XTS) XTS=SU(I1)
      CONTINUE
      KMP=ITS
      ITS=0
      XTS=100.
      DO 254 I1=1,END
      IF (SU(I1).LT.XTS) ITS=I1
      IF (SU(I1).LT.XTS) XTS=SU(I1)
      CONTINUE
      KIP=ITS
      KM=END-(KIP-KMP)
      KMI=KM+1
      END=END+1
      DO 260 I1=1,KM
      I5=KIP+I1-1
      IF (I5-GE.END-1) I5=I1-END+KIP+1
      X80D(I1)=SU(I5)
      Y80D(I1)=SD(I5)
      FORMAT(4E13.5,3I7)
260      LOAD SMOOTHED DATA AROUND L.E. REGION INTO EDGL FOR USE IN 'EDGE
448      REGION' TECHNIQUE
      DO 264 I1=KMI,END
      I5=END+KMP-I1
      X80D(I1)=SU(I5)
      Y80D(I1)=SD(I5)
      DO 268 I1=KMP,KIP
      IF (SU(I1).LT.-CHOP*.50*PLATE) GOTO271
      CONTINUE
      I1=KIP
      I2L=0
      DO 274 I3=I1,END
      IF (ABS(SU(I3)).LT.CHOP*.50*PLATE) GOTO277
      YEE=SU(I3)*SIN(THETL)+SD(I3)*COS(THETL)
      I2L=I2L+1
      EDGL(I2L)=CMPLX(YEE,SU(I3))
      NOT0=SGEN(SEDGL,EDGL,I2L)
274      IF (.NOT.LEONLY) LOAD SMOOTHED DATA AROUND T.E. INTO EDGT FOR USE
277      IN 'EDGE REGION'
      C
      IF (LEONLY) GOTO280

```



```

282 DO 282 I1=1,KMP
285 IF (SU(I1).GT.CHOP*.50*PLATE) GOTO285
CONTINUE
I2T=0
DO 288 I3=I1,KIP
IF (SU(I3).LT.CHOP*.50*PLATE) GOTO291
YEE=SU(I3)*SIN(THET)+SD(I3)*COS(THET)
I2T=I2T+1
EDGT(I2T)=CMPLX(YEE,SU(I3))
NOTO=SGEN(SEDGT,EDGT,I2T)

288
291

280 DO 298 I1=1,400
Z(I1)=1.E20
IF(I1.LE.400) SU(I1)=0.
IF(I1.LE.400) SD(I1)=0.
CONTINUE
DO 2100 I1=1,KM
Z(I1)=CMPLX(XBOD(I1),YBOD(I1))
NOTO=SGEN(SU,Z,KM)
KM1=KM+1
IF(NOTO.NE.0) WRITE(6,2) NOTO
FORMAT(10SGEN FAILURE,16)
KENDO=END-KM
DO 2104 I1=KM1,END
I2=I1-KM
Z2(I2)=CMPLX(XBOD(I1),YBOD(I1))
NOTO=SGEN(SD,Z2,KENDO)
END OF BODY COORDINATE LOADING

ZN2M1=2*ZN0-1
NZ2M2=ZN2M1-1

DO 202 I=1,NZ2M2
ENPOL=ENPOL+1

C DO (ITERATION SETUP)
C PROCEDURE (ITERATION SETUP)
ENPOL=ENPOL+1
RELAXD=.FALSE.
FALID=.FALSE.
EDGES=.FALSE.
BOTTOM=.FALSE.

```

QSO31690
QSO31700
QSO31710
QSO31720
QSO31730
QSO31740
QSO31750
QSO31760
QSO31770
QSO31780
QSO31790
QSO31800
QSO31810
QSO31820
QSO31830
QSO31840
QSO31850
QSO31860
QSO31870
QSO31880
QSO31890
QSO31900
QSO31910
QSO31920
QSO31930
QSO31940
QSO31950
QSO31960
QSO31970
QSO31980
QSO31990
QSO32000
QSO32010
QSO32020
QSO32030
QSO32040
QSO32050
QSO32060
QSO32070
QSO32080
QSO32090
QSO32100
QSO32110
QSO32120
QSO32130
QSO32140
QSO32150
QSO32160


```

C      DO (GRID-LINE COORDINATE LOADING)
C      PROCEDURE (GRID-LINE COORDINATE LOADING)
      ITST=0
      JTST=0
      DO 20109 I1=1,400
      XOETA(I1)=1.E20
      YOETA(I1)=1.E20
      IF(I1.LE.400) SDXETA(I1)=0.
      IF(I1.LE.400) SDYETA(I1)=0.
20109 CONTINUE
      DO 20115 I1=1,ENPOLS
      IF(ABS(XX(I,1)).GT.20.) XX(I,1)=SIGN(7.*ABS(XX(I,2)),XX(I,1))
      XOETA(I1)=CMPLX(ET(I1),XX(I,1))
      YOETA(I1)=CMPLX(ET(I1),YY(I,1))
      NOTO=SGEN(SDYETA,YOETA,ENPOLS)
      IF(NOTO.NE.0) WRITE(6,2) NOTO
      NOTO=SGEN(SDXETA,XOETA,ENPOLS)
      IF(NOTO.NE.0) WRITE(6,2) NOTO
      END
C
      Y=YY(I,ENO)
      IF(Y.EQ.0.) Y=SIGN(1.E-04,YY(I,ENO-1))
      X=XX(I,ENO-1)
      X00=X
      ETA=CAPK*(ENO-2)/(ENO-1)
      IF(Y.LE.0.AND.I.NE.1) BOTTOM=.TRUE.
      IF(I.EQ.ZNO.AND.LAMDAO.GT.0.) BOTTOM=.TRUE.
      DF1DN=(XX(I,ENO)-XX(I,ENO-1))/(ET(ENO-1)-ET(ENO))
      DF2DN=(YY(I,ENO)-YY(I,ENO-1))/(ET(ENO-1)-ET(ENO))
      DF3DX=0.
      IF(DF2DN+DF1DN*DF3DX.EQ.0.) DF3DX=1.
      DELN=0.
      DELX=0.
      DELY=0.
      SP=0.
      END
C
C      DO (ITERATION FOR ETA LINE-BODY INTERSECTION)
C      PROCEDURE (ITERATION FOR ETA LINE-BODY INTERSECTION)
      IF(ABS(XX(I,ENO)).GT.CHOP*PLATE.AND.
1((NOT LONLY.OR.I.LE.ZNO/2.OR.I.GE.3*ZNO/2))) GOTO2119
C      DO UNTIL(RELAXD.OR.FAILED)
      ITST=ITST+1
2122 X=X+DELX

```



```

Y=Y+DELY
SPY=0.
SPX=0.
SPE=0.
ETA=ETA+DELN
IF(ETA.LT.0.)ETA=ET(2)
IF(ETA.GT.2.*CAPK)ETA=ET(ENOPLS)
IF(.NOT.EDGES) GOTO2124
IF(ETA.GT.2.*CAPK.AND.ITST.GT.20)ETA=.90*CAPK
DUM=RZTRP(SXYETA,XYETA,ETA,I2S,SPX)
GETA=AIMAG(FZTRP(SXYETA,XYETA,ETA,I2S))
DUM=RZTRP(SYVETA,YVETA,ETA,I2Y,SPY)
FETA=AIMAG(FZTRP(SYVETA,YVETA,ETA,I2Y))
GOTO2125
DUM=RZTRP(SDXETA,XOETA,ETA,ENPOLS,SPX)
GETA=AIMAG(FZTRP(SDXETA,XOETA,SPX,ENPOLS))
DUM=RZTRP(SDYETA,YOETA,ETA,ENPOLS,SPY)
FETA=AIMAG(FZTRP(SDYETA,YOETA,SPY,ENPOLS))
F1=X-GETA
F2=Y-FETA
IF(.NOT.BOTTOM) GOTO2126
DUM=RZTRP(SD,Z2,X,KENDO,SP)
FX=AIMAG(FZTRP(SD,Z2,SP,KENDO))
GOTO2127
DUM=RZTRP(SU,Z,X,KM,SP)
FX=AIMAG(FZTRP(SU,Z,SP,KM))
F3=Y-FX
RELAXD=(ABS(F1)+ABS(F2)+ABS(F3)).LT..0001

C IF FIRST TRY IS UNSUCCESSFUL, GET SMOOTHED SLOPE DATA AND TRY AGAIN
C IN
C
C IF((ITST.LE.20.AND.ABS(DELN/ETA).LE.1000.).OR.EDGES) GOTO2128
C DO (ITERATION WITH BETTER SLOPES)
C PROCEDURE(ITERATION WITH BETTER SLOPES)
C WRITE(6,5) I
C FORMAT(' ITERATION PROCEEDS WITH SMOOTHER SLOPE DATA FOR LINE ',I4)
C DO 2139 I1=1,400
C XYETA(I1)=1.E20
C YVETA(I1)=1.E20
C IF(I1.LE.400) SXYETA(I1)=0.
C IF(I1.LE.400) SYVETA(I1)=0.
C CONTINUE
C
C DO (ITERATION SETUP AGAIN)

```



```

C      PROCEDURE ( ITERATION SETUP)
ENPOL=ENOPLS
RELAXD=.FALSE.
FALD=.FALSE.
EDGES=.FALSE.
BOTTOM=.FALSE.
QSO33130
QSO33140
QSO33150
QSO33160
QSO33170
QSO33180
QSO33190
QSO33200
QSO33210
QSO33220
QSO33230
QSO33240
QSO33250
QSO33260
QSO33270
QSO33280
QSO33290
QSO33300
QSO33310
QSO33320
QSO33330
QSO33340
QSO33350
QSO33360
QSO33370
QSO33380
QSO33390
QSO33400
QSO33410
QSO33420
QSO33430
QSO33440
QSO33450
QSO33460
QSO33470
QSO33480
QSO33490
QSO33500
QSO33510
QSO33520
QSO33530
QSO33540
QSO33550
QSO33560
QSO33570
QSO33580
QSO33590
QSO33600

C      DO (GRID-LINE COORDINATE LOADING AGAIN)
PROCEDURE (GRID-LINE COORDINATE LOADING)
ITST=0
JTST=0
DO 2109 I1=1,400
XOETA(I1)=1.E20
YOETA(I1)=1.E20
IF(I1.LE.400) SDXETA(I1)=0.
IF(I1.LE.400) SDYETA(I1)=0.
CONTINUE
2109 DO 21115 I1=1,ENPOL
IF (ABS(CX(I1)) .GT. 20.) XX(I1)=SIGN(7.*ABS(XX(I,2)),XX(I,1))
XOETA(I1)=CMPLX(ET(I1),XX(I1,I1))
YOETA(I1)=CMPLX(ET(I1),YY(I1,I1))
NOTO=SGEN(SDYETA,YOETA,ENPOL)
IF(NOTO.NE.0) WRITE(6,2) NOTO
NOTO=SGEN(SDXETA,XOETA,ENPOL)
IF(NOTO.NE.0) WRITE(6,2) NOTO
END
C
Y=YY(I,ENO)
IF(Y.EQ.0.) Y=SIGN(1.E-04,YY(I,ENO-1))
X=XX(I,ENO-1)
XOO=X
ETA= CAPK*(ENO-2)/(ENO-1)
IF(Y.LE.0.) AND.I.NE.1) BOTTOM=.TRUE.
IF(I.EQ.ZNO.AND.LAMDAO.GT.0.) BOTTOM=.TRUE.
DF1DN=(CX(I,ENO)-XX(I,ENO-1))/(ET(ENO-1)-ET(ENO))
DF2DN=(YY(I,ENO)-YY(I,ENO-1))/(ET(ENO-1)-ET(ENO))
DF3DX=0.
IF(DF2DN+DF1DN*DF3DX.EQ.0.) DF3DX=1.
DELN=0.
DELX=0.
DELY=0.
SP=0.
END
C
EDGES=.TRUE.
DO 2146 I6=1,ENO
DO 2146 I6=1,ENOPLS
XYETA(I6)=XOETA(I6)
QSO33130
QSO33140
QSO33150
QSO33160
QSO33170
QSO33180
QSO33190
QSO33200
QSO33210
QSO33220
QSO33230
QSO33240
QSO33250
QSO33260
QSO33270
QSO33280
QSO33290
QSO33300
QSO33310
QSO33320
QSO33330
QSO33340
QSO33350
QSO33360
QSO33370
QSO33380
QSO33390
QSO33400
QSO33410
QSO33420
QSO33430
QSO33440
QSO33450
QSO33460
QSO33470
QSO33480
QSO33490
QSO33500
QSO33510
QSO33520
QSO33530
QSO33540
QSO33550
QSO33560
QSO33570
QSO33580
QSO33590
QSO33600

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QSO333610
QSO333620
QSO333630
QSO333640
QSO333650
QSO333660
QSO333670
QSO333680
QSO333690
QSO333700
QSO333710
QSO333720
QSO333730
QSO333740
QSO333750
QSO333760
QSO333770
QSO333780
QSO333790
QSO333800
QSO333810
QSO333820
QSO333830
QSO333840
QSO333850
QSO333860
QSO333870
QSO333880
QSO333890
QSO333900
QSO333910
QSO333920
QSO333930
QSO333940
QSO333950
QSO333960
QSO333970
QSO333980
QSO333990
QSO334000
QSO334010
QSO334020
QSO334030
QSO334040
QSO334050
QSO334060
QSO334070
QSO334080

```

2146 YYETA(I6)=YOETA(I6)
      DA=.02
      DELSMX=.06667
      I2S=ENOPLS
      C SMOOTH THE SLOPE DATA
      CALL XYCALC(I,I2S,XYETA,XYETA,SYETA)
      DO 2150 I6=1,I2S
2150 XYETA(I6)=CMPLX(SXYETA(I6),SYETA(I6))
      DO 2154 I4=1,400
      SYETA(I4)=0.
2154 SYETA(I4)=0.
      I2Y=ENOPLS
      CALL XYCALC(I,I2Y,YYETA,XYETA,SYETA)
      DELSMX=.06667
      DO 2158 I6=1,I2Y
2158 YYETA(I6)=CMPLX(SXYETA(I6),SYETA(I6))
      NOTO=SGEN(SXYETA,XYETA,I2S)
      NOTO=SGEN(SXYETA,YYETA,I2Y)
      C WRITE(6,TEXT)
      C END OF BETTER SLOPE ACQUISITION, EDGES NOW = .TRUE.
2128 IF(ITST.GT.50.OR.ABS(DELN/ETA).GT.1000.) FAILED=.TRUE.
      IF(RELAXD) GOTO2129
      DELN = (F3-F2-DF3DX*F1)/(DF2DN+DF1DN*DF3DX)
      DELX = -F1-DF1DN*DELN
      DELY = -F3-DF3DX*DELX
      C DO (SEARCH FOR BODY SLOPE)
      C PROCEDURE (SEARCH FOR BODY SLOPE)
      K4=1
      K3=KM
      K2=1
      IF(.NOT.BOTTOM) GOTO2162
      K2=KM+1
      K3=END
      K4=1
2162 DO 2164 K1=K2,K3,K4
2164 IF(XBOD(K1).GE.X+DELX) GOTO2167
      CONTINUE
      K1=K3
2167 DF3DX=(YBOD(K1-1)-YBOD(K1))/
      * (XBOD(K1)-XBOD(K1-1))
      C END
      C DO (SEARCH FOR GRID-LINE SLOPE)
      C PROCEDURE (SEARCH FOR GRID-LINE SLOPE)
      IF(.NOT.EDGES) GOTO2170
      DO 2172 J=1,I2S
2172 IF(REAL(XYETA(J)).GE.ETA) GOTO2175
      CONTINUE

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2175 IF (J.EQ.I2S+1) J=I2S
DO 2180 JY=1,I2Y
IF (REAL(XYETA(JY)).GE.ETA) GOTO2183
CONTINUE
2183 IF (JY.EQ.I2Y+1) JY=I2Y
DF1DN=(AIMAG(XYETA(J))-AIMAG(XYETA(J-1)))/
1 (REAL(XYETA(J-1))-REAL(XYETA(J)))
DF2DN=(AIMAG(YYETA(JY))-AIMAG(YYETA(JY-1)))/
1 (REAL(YYETA(JY-1))-REAL(YYETA(JY)))
GOTO2171
2170 DO 2188 J=1,ENOPLS
IF (ET(J).GE.ETA) GOTO2191
CONTINUE
2188 IF (J.EQ.ENOPLS+1) J=ENOPLS
DF1DN=(XX(I,J)-XX(I,J-1))/(ET(J-1)-ET(J))
DF2DN=(YY(I,J)-YY(I,J-1))/(ET(J-1)-ET(J))
CONTINUE
2171 C
END
2129 IF (.NOT.(DF2DN+DF3DX.EQ.0..OR.
1 ((I.EQ.1.OR.I.EQ.ZNO).AND.LAMDAO.EQ.0..OR.
1 (.NOT.SMOOTH.AND.ABS(XX(I,END)).GT..98*PLATE.AND.FAILED))) GOTO2121
RELAXD=.TRUE.
FAILD=.FALSE.
Y=YY(I,END)
X=XBOD(KM)
IF (I.EQ.1) X=XBOD(1)
IF (SMOOTH) GOTO2135
Y=0.
X=XBOD(1)
IF (I.GT.ZNO/2.AND.I.LT.3*ZNO/2) X=XBOD(KM)
DUM=IZTRP(SDXETA,XOETA,X,ENO,SPE)
ETA=REAL(FZTRP(SDXETA,XOETA,SPE,ENO))
2135
2121 IF (.NOT.(RELAXD.OR.FAILD)) GOTO2122
C
2119 END OF ITERATION FOR ETA LINE-BODY INTERSECTION
IF (RELAXD.OR.ABS(XX(I,ENO)).LE.CHOP*PLATE.AND..NOT.FAILD) GOTO3004
IF (FAILD) WRITE(6,3) I
IF (.NOT.FAILD) WRITE(6,4) I,XX(I,ENO),PLATE
3 FORMAT('O ITERATION FAILED FOR LINE ',I4,
1, 'PROCEEDING TO EDGE REGION TECHNIQUE.')
4 FORMAT('O ITERATION NOT ATTEMPTED FOR LINE ',I4,
1, 'BODY X TOO CLOSE TO LE OR TE: ',2E15.6,'PROCEED TO EDGE TECH..')
ISAVE(ISA)=I
NSAVE(ISA)=1
IF (BOTTOM) NSAVE(ISA)=-1
ISA=ISA+1
DO 208 J=1,ENOPLS
3004

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208 IF(ET(J).GE.ETA) GOTO211
211 CONTINUE
IF(J.EQ.ENOPLS+1) ETA=ET(ENOPLS)
IF(.NOT.RELAXD) GOTO202
XX(I,ENO)=X
YY(I,ENO)=Y
ETS(I)=ETA
DO (ETA,VALUE,STRETCH)
PROCEDURE (ETA,VALUE,STRETCH)
ENM1=ENO-1
DO 20196 J=2,ENM1
ETANEW=ET(J)/CAPK*ETA
SPX=SDXETA(1)
SPY=SDYETA(1)
DUM=RZTRP(SDXETA,XOETA,ETANEW,ENPOLS,SPX)
XX(I,J)=AIMAG(FZTRP(SDXETA,XOETA,SPX,ENPOLS))
DUM=RZTRP(SDYETA,YOETA,ETANEW,ENPOLS,SPY)
YY(I,J)=AIMAG(FZTRP(SDYETA,YOETA,SPY,ENPOLS))
20196 ENDO
C
202 CONTINUE (EDGE REGIONS)
C DO (EDGE REGIONS)
C PROCEDURE (EDGE REGIONS)
C *EDGE REGION TECHNIQUE* = INTERPOLATE ON CURVE OF INTERSECTION POINTS
C DEFINED BY SUCCESSFUL NEIGHBORING LINES.
C
NOZ02=ZN0/2
IF(ISAVE(1).GE.NOZ02) GOTO2020
DO 2202 I3=1,ISA
IF(ISAVE(I3).GT.NOZ02) GOTO2205
CONTINUE
2202 I3=ISA
2205 I3=I3-1
ISAP=ISA
DO 2208 I4=1,I3
ISAVE(ISAP)=ISAVE(I4)
ISAP=ISAP+1
ISAM1=ISA-1
DO 2212 I4=1,ISAM1
I4I3=I4+I3
ISAVE(I4I3)=ISAVE(I4I3)
DO 2216 I1=1,400
XYETA(I1)=1.E20
YYETA(I1)=1.E20
IF(I1.GT.400) GOTO2216
SXYETA(I1)=0.
2212
2020

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```

SYVETA(I1)=0.
SU(I1)=0.
SD(I1)=0.
CONTINUE
I2=0
IS=1
NZ2M11=ZN2M1-1
C      LOAD VALUES OF BODY Y AND ZET FROM ALL SUCCESSFUL LINE ITERATION
C      S INTO
C      THE ARRAY XYETA AND SMOOTH IT.
DO 2222 I1=NOZ02,NZ2M11
  IF(I1.GT.ISA) GOTO2222
  IF(I1.SAVE(IS).EQ.I1) GOTO2228
  I2=I2+1
  THE=XX(I1,ENO)*(THETL-THET)/(-1.6*CHOP*PLATE)
  IF(XX(I1,ENO).LT.-CHOP*.80*PLATE)THE=THEIL
  IF(XX(I1,ENO).GT.CHOP*.80*PLATE)THE=THEIT
  YEE=Y(I1,ENO)*COS(THET)+XX(I1,ENO)*SIN(THET)
  YEE=YEE*10.
  XYETA(I2)=CMPLX(ZET(I1),YEE)
  XYETA(I2)=CMPLX(ZET(I1),ETS(I1))
  IF(I1.SAVE(IS).EQ.I1)IS=IS+1
  CONTINUE
DO 2230 I1=1,NOZ02
  IF(I1.SAVE(IS).EQ.I1) GOTO2234
  I2=I2+1
  ZED=ZET(I1)-2.*CAPKP
  THE=XX(I1,ENO)*(THETL-THET)/(-1.6*PLATE)
  IF(XX(I1,ENO).LT.-CHOP*.80*PLATE)THE=THEIL
  IF(XX(I1,ENO).GT.CHOP*.80*PLATE)THE=THEIT
  YEE=Y(I1,ENO)*COS(THET)+XX(I1,ENO)*SIN(THET)
  YEE=YEE*10.
  XYETA(I2)=CMPLX(ZED,YEE)
  XYETA(I2)=CMPLX(ZED,ETS(I1))
  IF(I1.SAVE(IS).EQ.I1)IS=IS+1
  CONTINUE
I2S=I2
DELSMX=-5
DA=.05
CALL XYCALC(I,I2S,XYETA,SU,SD)
DELSMX=-.066667
DO 2236 I6=1,I2S
  XYETA(I6)=CMPLX(SU(I6),SD(I6))
  NOT0=SGEN(SXYETA,XYETA,I2S)
  NOT0=SGEN(SYVETA,YVETA,I2)
  WRITE(6,TEXS)
  SPT=0.
C

```



```

SPL=0.
ISAM1=ISA-1
OO 2240 IS=1,ISAM1
SPX=0.
SPE=0.
TE=.FALSE.
I1=ISAVE(IS)
I=I1
IMM1=I-1
IF(IMM1.EQ.0)IMM1=ZN2M1-1

IF(I.GT.ZN2M1/4.AND.I.LT.3*ZN2M1/4)TE=.TRUE.

IF(TE)SPL=0.
ZED=ZET(I1)

C INTERPOLATE ON THE TABLE OF Y VALUES IN XYETA USING THE KNOWN VAL
C UE OF ZETA
C FOR EACH UNSUCCESSFUL LINE.

IF(.NOT.TE.AND.ZED.GT..85*CAPKP)ZED=ZED-2.*CAPKP
DUM=RZTRP(SXYETA,XYETA,ZED,I2S,SPX)
Y=A1MAG(FZTRP(SXYETA,XYETA,SPX,I2S))/10.

C AFTER Y IS FOUND, OBTAIN X FROM TABLE OF L.E. AND T.E. BODY SHAPE
C S
C IN EDGL AND EDGT.

IF(.NOT.SMOOTH)GOTO2244
IF(.NOT.TE)GOTO2246
DUM=RZTRP(SEDGT,EDGT,Y,I2I,SPT)
X=A1MAG(FZTRP(SEDGT,EDGT,SPT,I2I))
IF(ABS(X-XX(IMM1,ENO))).LE.1.5/FLOAT(ZNO))GOTO22461
DUM=RZTRP(SEDGT,EDGT,Y,I2I,SPT)
X=A1MAG(FZTRP(SEDGT,EDGT,SPT,I2I))
GOTO2245
22461 DUM=RZTRP(SEDGL,EDGL,Y,I2L,SPL)
2246 X=A1MAG(FZTRP(SEDGL,EDGL,SPL,I2L))
IF(ABS(X-XX(IMM1,ENO))).LE.1.5/FLOAT(ZNO))GOTO22441
DUM=RZTRP(SEDGL,EDGL,Y,I2L,SPL)
X=A1MAG(FZTRP(SEDGL,EDGL,SPL,I2L))
GOTO2245
22441 IF(Y.GT.0.:OR.I.EQ.1)GOTO2252
2244 DUM=IZTRP(SD,Z2,Y,KENDO,SP)

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```

X=REAL(FZTRP(SD,Z2,SP,KENDO))
GOTO 2245
2252 DUM=IZTRP(SU,Z,Y,KM,SP)
X=REAL(FZTRP(SU,Z,SP,KM))

2245 IF(.NOT. TE) Y=(Y-X*SIN(THETL))/COS(THETL)
IF(TE) Y=(Y-X*SIN(THET))/COS(THET)
C DO (GRID-LINE COORDINATE LOADING)
C PROCEDURE (GRID-LINE COORDINATE LOADING)
ITST=0
JTST=0
DO 21109 I1=1,400
XOETA(I1)=1.E20
YOETA(I1)=1.E20
IF(I1.LE.400) SDXETA(I1)=0.
IF(I1.LE.400) SDYETA(I1)=0.
21109 CONTINUE
DO 2115 I1=1,ENPOLS
IF(ABS(XX(I,1)).GT.20.) XX(I,1)=SIGN(7.*ABS(XX(I,2)),XX(I,1))
XOETA(I1)=CMPLX(ET(I1),XX(I,1))
YOETA(I1)=CMPLX(ET(I1),YY(I,1))
NOTO=SGEN(SDYETA,YOETA,ENPOLS)
IF(NOTO.NE.0) WRITE(6,2) NOTO
NOTO=SGEN(SDXETA,XOETA,ENPOLS)
IF(NOTO.NE.0) WRITE(6,2) NOTO
END
DUM=IZTRP(SDXETA,XOETA,X,ENPOLS,SPE)
ETA=REAL(FZTRP(SDXETA,XOETA,SPE,ENPOLS))

C DO (ETA VALUE STRETCH FOR EDGE REGION POINTS)
C PROCEDURE (ETA VALUE STRETCH)
ENM1=ENO-1
DO 2196 J=2,ENM1
ETANEW=ET(J)/CAPK*ETA
SPX=0.
SPY=0.
DUM=RZTRP(SDXETA,XOETA,ETANEW,ENPOLS,SPX)
XX(I,J)=AIMAG(FZTRP(SDXETA,XOETA,SPX,ENPOLS))
DUM=RZTRP(SDYETA,YOETA,ETANEW,ENPOLS,SPY)
YY(I,J)=AIMAG(FZTRP(SDYETA,YOETA,SPY,ENPOLS))
END
2196 IF(XX(I,1).EQ.XX(I,ENO-1).AND. YY(I,1).EQ.YY(I,ENO-1)) WRITE (6,7) I
C FORMAT(10GR ID LINE NO. ',I4,' HAS DEGENERATED TO POINT.',
7 1,' TRY THETL,THET = LE,TE CAMBER ANGLES.')
XX(I,ENO)=X

```



```

2240      YY(I,ENO)=Y
C      END
      DO 218 J1=2,ENO
      XX(ZN2M1,J1)=XX(1,J1)
      YY(ZN2M1,J1)=YY(1,J1)
      RETURN
218
C
C
C      SUBROUTINE TOSTAG(S,ZET,CHORDO)
C      INVERT THE CONFORMAL TRANSFORMATION FROM FLATPLATE CASCADE OF ZERO
C      STAGGER
C      TO THE UNIT CIRCLE. ADD DESIRED SOLIDITY AND STAGGER TERMS AND RE
C      VERT TO
C      PHYSICAL PLANE.
C      SOURCE,      HAWTHORNE (LISTED AS REF. 4 OF REF. 2 OF THE USERS M
C      ANUAL)
C
C      INTEGER ZNO,ZN2M1,ENO,ENOPLS
C      DIMENSION ZET(100)
C      COMMON/GEOM/ZNO,ENO,RLE,RTE,A,CHORD,XUPS,XDNS,STAG,F,CAKK(4),PI,
1LNK,VB,KN,NED,BB,DOSURF,R,SOLID2,ENOPLS
C      COMMON /ENTIRE/ XGRID(100,30),YGRID(100,30)
C      COMPLEX AI/(0.,1.)/,AHIAN,AHTAN2,AHYPT,ZCMX,WCMX,AQT1,AQT2,READK
C      COMPLEX ZGRID
C      READK=1./R
C      ALAMDA=.5*(READK+1./READK)
C      ZN2M1=2*ZNO-1
C      N2ZM11=ZN2M1-1
C      XGRID(1,1)=4.*XGRID(2,1)
C      XGRID(ZN2M1,1)=XGRID(1,1)
C      XGRID(ZNO,1)=-XGRID(1,1)
C      DO 1 I=1,N2ZM11
C      DO 1 J=1,ENOPLS
C      SIG=1.
C      IF(J.GT.ENO) SIG=-1.

```



```

C      EQNS. FROM FIGS B,5C AND D
1      AL=ATAN(TAN(G)*(RD*RD-1.)/(RD*RD+1.))
      CSTAB(I,J)=1./PI*(COS(G)*ALOG{(RD*RD+2.*RD*COS(AL)+1.)/(RD*RD-1.)})
      1*RD*COS(AL)+1.)))+2.*SIN(G)*ATAN(2.*RD*SIN(AL)/(RD*RD-1.))
      STAGG=STAG*180./PI
20     DO 20 J=1,25
      IF(STAGG.LE.GAMTAB(J))GOTO21
      CONTINUE
21     J=25
      JSTAR=J
      JSM1=J-1
      DO 40 J=JSM1,JSTAR
      J1=J-JSM1+1
      DO 30 I=1,25
      IF(COVERS.GE.CSTAB(I,J))GOTO31
      CONTINUE
      I=25
      ISTAR(J1)=I
      CONTINUE
      ISM1=ISTAR(2)-1
      ISSM1=ISTAR(1)-1
      IS=ISTAR(2)
      ISS=ISTAR(1)
      R1=RTAB(ISSM1)+(RTAB(ISSM1)-RTAB(ISS))*(COVERS-CSTAB(ISS,JSM1))/
      1(CSTAB(ISSM1)-CSTAB(ISS,JSM1))
      R2=RTAB(IS)+(RTAB(ISSM1)-RTAB(IS))*(COVERS-CSTAB(IS,JSTAR))/
      1(CSTAB(ISSM1)-CSTAB(IS,JSTAR))
      R=R1+(R2-R1)*(STAGG-GAMTAB(JSM1))/(GAMTAB(JSTAR)-GAMTAB(JSM1))
      IF(COVERS.GT.5.)R=1.0001
      ALFA=ATAN(TAN(STAG)*(R*R-1.)/(R*R+1.))
      RETURN
      END
      FUNCTION FUDS(E,Z,SCK)
C      CALCULATES FUNCTION 'T' IN EQN. 1., REF. 2. OF USER MANUAL
      COMMON/GEOM/ DUMP(19),G
      COMMON/FUNCOS/S,C,D,SN,CN,DN
      CALL JELF(S,C,D,E,SCK)
      CALL JELF(SN,CN,DN,Z,G)
      B=S*DN*S*DN+(C*D*SN*CN)**2

```



```

FUDES = SQRT(B)
RETURN
END
FUNCTION OWOW(SCK)
C   CALCULATES FUNCTION 'OMEGA' IN EQN. 1., REF. 2 OF USERS MANUAL
Q5037930
Q5037940
Q5037950
Q5037960
Q5037970
Q5037980
Q5037990
Q5038000
Q5038010
Q5038020
Q5038030
Q5038040
Q5038050
Q5038060
Q5038070
Q5038080
Q5038090
Q5038100
Q5038110
Q5038120
Q5038130
Q5038140
Q5038150
Q5038160
Q5038170
Q5038180
Q5038190
Q5038200
Q5038210
Q5038220
Q5038230
Q5038240
Q5038250
Q5038260
Q5038270
Q5038280
Q5038290
Q5038300
Q5038310
Q5038320
Q5038330
Q5038340
Q5038350
Q5038360
Q5038370
Q5038380
Q5038390
Q5038400

COMMON/FUNCOS/S,C,D,SN,CN,DN
IF(S.EQ.0.)S=1.E-20
B= C*D*SN*CN/S/DN
OWOW = ATAN(B)
RETURN
END
FUNCTION BADZAC(SCK)
C   CALCULATES FUNCTION 'GAMMA' IN EQN. 1., REF. 2 OF USERS MANUAL
Q5037930
Q5037940
Q5037950
Q5037960
Q5037970
Q5037980
Q5037990
Q5038000
Q5038010
Q5038020
Q5038030
Q5038040
Q5038050
Q5038060
Q5038070
Q5038080
Q5038090
Q5038100
Q5038110
Q5038120
Q5038130
Q5038140
Q5038150
Q5038160
Q5038170
Q5038180
Q5038190
Q5038200
Q5038210
Q5038220
Q5038230
Q5038240
Q5038250
Q5038260
Q5038270
Q5038280
Q5038290
Q5038300
Q5038310
Q5038320
Q5038330
Q5038340
Q5038350
Q5038360
Q5038370
Q5038380
Q5038390
Q5038400

COMMON/FUNCOS/S,C,D,SN,CN,DN
BADZAC = CN*CN+(1.-SCK)*S*S*SN*SN
RETURN
END
SUBROUTINE JELF(SN,CN,DN,X,SCK)
C   COMPUTES JACOBIAN ELLIPTIC FCNS SN,CN,DN
Q5037930
Q5037940
Q5037950
Q5037960
Q5037970
Q5037980
Q5037990
Q5038000
Q5038010
Q5038020
Q5038030
Q5038040
Q5038050
Q5038060
Q5038070
Q5038080
Q5038090
Q5038100
Q5038110
Q5038120
Q5038130
Q5038140
Q5038150
Q5038160
Q5038170
Q5038180
Q5038190
Q5038200
Q5038210
Q5038220
Q5038230
Q5038240
Q5038250
Q5038260
Q5038270
Q5038280
Q5038290
Q5038300
Q5038310
Q5038320
Q5038330
Q5038340
Q5038350
Q5038360
Q5038370
Q5038380
Q5038390
Q5038400

IF X IS GIVEN AS THE ELLIPTIC INTEGRAL OF THE FIRST KIND WITH MOD
ULUS K
FROM ZERO TO SIN(PHI) WITH 0<PHI<PI/2, THEN
SCK = 1-K*K
SN(X,K)=SIN(PHI)
CN(X,K)=COS(PHI)
DN(X,K)=SQRT(1.-K*K*SIN(PHI)**2)
AND
C   DIMENSION ARI(12),GEO(12)
Q5037930
Q5037940
Q5037950
Q5037960
Q5037970
Q5037980
Q5037990
Q5038000
Q5038010
Q5038020
Q5038030
Q5038040
Q5038050
Q5038060
Q5038070
Q5038080
Q5038090
Q5038100
Q5038110
Q5038120
Q5038130
Q5038140
Q5038150
Q5038160
Q5038170
Q5038180
Q5038190
Q5038200
Q5038210
Q5038220
Q5038230
Q5038240
Q5038250
Q5038260
Q5038270
Q5038280
Q5038290
Q5038300
Q5038310
Q5038320
Q5038330
Q5038340
Q5038350
Q5038360
Q5038370
Q5038380
Q5038390
Q5038400

CM=SCK
Y=X
IF(SCK) 3,1,4
D=EXP(X)
A=1./D
B=A+D
CN=2./B
DN=CN
SN=TANH(X)
RETURN

```



```

3      D=1.-SCK
      CM=-SCK/D
      D=SQRT(D)
      Y=D*X
      A=1.
      DN=1.
      DO 6 I=1,12
      L=I
      ARI(I)=A
      CM=SQRT(CM)
      GEO(I)=CM
      C=(A+CM)*.5
      IF (ABS(A-CM)-1.E-4*A) 7,7,5
5      CM=A*CM
6      A=C
7      Y=C*Y
      SN=SIN(Y)
      CN=COS(Y)
      IF (SN) 8,13,8
8      A=CN/SN
      C=A*C
      DO 9 I=1,L
      K=L-I+1
      B=ARI(K)
      A=C*A
      C=DN*C
      DN=(GEO(K)+A)/(B+A)
9      A=C/B
      A=1./SQRT(C*C+1.)
      IF (SN) 10,11,11
10     SN=-A
      GO TO 12
11     SN=A
12     CN=C*SN
13     IF (SCK) 14,2,2
14     A=DN
      DN=CN
      CN=A
      SN=SN/D
      RETURN
      END
      SUBROUTINE XYCALC(KSTART,K2,Z,X,Y)
      ---XYCALC ---
      C.....GENERATES DATA FILES FOR ON-BODY POINTS.
      INTEGER SGEN
      REAL
      COMPLEX Z(400),DZ(400),D2Z,ZZ,FZTRP,DZTRP
      C(400),S(400),SP(400)

```



```

LOGICAL THIN,EVEN,SPGEN,DONE
COMMON /MAN/ DELSMX,PIO2,DELS1,IHUB
DIMENSION X(400),Y(400)
COMMON /SPGEN/ A,DSMAX,RMAX,THIN,B,TMIN,DSEND
DATA NSMAX,EMPTY/400,1.0E20/

```

C..... INITIALIZE PROGRAM.

```

SI=0.0
NMAX=400
DSMAX=DELSMX
DELS1=DELSMX
THIN=.FALSE.
RMAX=1.2
DSEND=DSMAX
DONE=.FALSE.
EVEN=.FALSE.
B=0.3
TMIN=0.1
NFIN=0
NSP=0

```

C..... INPUT BODY POINTS AND BODY TYPE.

```

DO 25 I=1,NSMAX
IF (REAL(Z(I)).EQ.EMPTY) GO TO 30

```

25 NS=I

30 S(1)=SI

IBAD=SGEN(S,Z,NS)

WRITE(6,140)

FORMAT(31)THE FOLLOWING IS S FROM XYCALC///)

C 140

WRITE(6,#)S

WRITE(6,145)

FORMAT(31)THE FOLLOWING IS Z FROM XYCALC///)

C 145

WRITE(6,#)Z

WRITE(6,150)

FORMAT(32)THE FOLLOWING IS NS FROM XYCALC///)

C 150

WRITE(6,#)NS

IF (IBAD.NE.0) WRITE (6,125)IBAD

C..... SET UP DERIVATIVES + CURVATURES.

DO 35 I=1,NS

DZ(I)=DZTRP(S,Z,S(I),NS)

DO 40 I=1,NS

D2Z=DZTRP(S,DZ,S(I),NS)

C(I)=AIMAG(CONJG(DZ(I))*D2Z)/CABS(DZ(I))*3

40

C..... INPUT AUXILIARY (CONTROL) DATA.

IF (NFIN.EQ.0) NFIN=NS

SFIN=S(NFIN)

QSO38890
QSO38900
QSO38910
QSO38920
QSO38930
QSO38940
QSO38950
QSO38960
QSO38970
QSO38980
QSO38990
QSO39000
QSO39010
QSO39020
QSO39030
QSO39040
QSO39050
QSO39060
QSO39070
QSO39080
QSO39090
QSO39100
QSO39110
QSO39120
QSO39130
QSO39140
QSO39150
QSO39160
QSO39170
QSO39180
QSO39190
QSO39200
QSO39210
QSO39220
QSO39230
QSO39240
QSO39250
QSO39260
QSO39270
QSO39280
QSO39290
QSO39300
QSO39310
QSO39320
QSO39330
QSO39340
QSO39350
QSO39360


```

DSMAX=AMAX1(DSMAX,DSEND)
C.....GENERATE BODY POINTS ON A SEGMENT.
IF (.NOT.SPGEN(S,Z,C,NS,SP,NSP,SFIN,NMAX)) GO TO 130

C.....OUTPUT RESULTING ON-BODY POINTS.
85 DO 90 I=1,NSP
   IBY=KSTART+I-1
   ZZ=FZTRP(S,Z,SP(I),NS)
   DZ(I)=DZTRP(S,Z,SP(I),NS)
   DZ2=DZTRP(S,DZ,SP(I),NS)
   C(I)=AIMAG(CONJG(DZ(I))*DZ2)/CABS(DZ(I))**3
90  X(IBY)=REAL(ZZ)
   Y(IBY)=AIMAG(ZZ)
   K1=KSTART
   K2=NSP+KSTART-1
120 RETURN
C.....ERROR MESSAGES.
125 FORMAT(21H SGEN FAILED. IBAD= ,I3)
130 WRITE(6,I35)
135 FORMAT(34H SPGEN UNABLE TO COMPLETE SEGMENT )
STOP
END
INTEGER FUNCTION SGEN(S,F,NS)
REAL S(400)
COMPLEX F(400),DZTRP
DATA MAX,N,FN,TEST/4,10,10.0,0.01/
DO 10 I=2,NS
  S(I)=S(I-1)+CABS(F(I)-F(I-1))
DO 30 K=1,MAX
  SGEN=0
DO 25 I=2,NS
  DS=S(I)-S(I-1)
  DARG=DS/FN
  ARG0=S(I-1)-DARG/2.0
  SUM=0.0
DO 15 J=1,N
  ARG=ARG0+FLQAT(J)*DARG
  TVQQ=CABS(DZTRP(S,F,ARG,NS))-1.0
  SUM=SUM+TVQQ
SUM=SUM/FN
ERROR=ABS(SUM)
WRITE(6,I9)
FORMAT(42H0 THE FOLLOWING IS TVQQ,SUM,ERROR FROM SGEN)
C
19 WRITE(6,*)TVQQ,SUM,ERROR
DS=DS*SUM
DO 20 J=1,NS

```

QS039370
 QS039380
 QS039390
 QS039400
 QS039410
 QS039420
 QS039430
 QS039440
 QS039450
 QS039460
 QS039470
 QS039480
 QS039490
 QS039500
 QS039510
 QS039520
 QS039530
 QS039540
 QS039550
 QS039560
 QS039570
 QS039580
 QS039590
 QS039600
 QS039610
 QS039620
 QS039630
 QS039640
 QS039650
 QS039660
 QS039670
 QS039680
 QS039690
 QS039700
 QS039710
 QS039720
 QS039730
 QS039740
 QS039750
 QS039760
 QS039770
 QS039780
 QS039790
 QS039800
 QS039810
 QS039820
 QS039830
 QS039840


```

20      S(J)=S(J)+DS
25      IF(ERROR.GT.TEST.AND.SGEN.EQ.0)SGEN=1
30      CONTINUE
      IF(SGEN.EQ.0)RETURN
      RETURN
      END
C..... LOGICAL FUNCTION SPGEN (S,Z,C,NS,SP,NSP,SFIN,NMAX)
C..... GENERATES TABLE SP HAVING VALUES OF PARAMETER S AS WIDELY SPACED
C..... AS POSSIBLE AND YET SATISFYING THE FOLLOWING CONDITIONS ON DS:
C      1 NSP .LE. NMAX
C      2 DS .LE. A/C(S) (C=CURVATURE)
C      3 DS .LE. DSMAX
C      4A DS(1) .LE. DS(I-1)*RMAX
C      4B DS(1) .GE. DS(I-1)/RMAX
C      FOR THIN SECTIONS, AN ADDITIONAL CONDITION IS:
C      DS .LE. B*TLOC (TLOC=LOCAL THICKNESS)
C..... SPGEN = .TRUE. IF ALL CONDITIONS HAVE BEEN SATISFIED.

      REAL S(400),C(400),SP(400)
      COMPLEX Z(400),FZTRP
      LOGICAL THIN,FIN
      COMMON /SPGENC/ A,DSMAX,RMAX,THIN,B,TMIN,DSEND
      COMMON /MAN/ DELSMX,PI02,DELS1,IHUB
      DATA ONE,CMIN/1.0001,1.0E-6/

C..... INITIALIZATION SECTION.
      SPGEN=.FALSE.
      J1=MAX0(NSP,2)+1
      IF (NSP.GT.1) GO TO 15
      IF (NSP.LT.1) SP(1)=S(1)
      DELS1=DELS1
      SP(2)=SP(1)+DS1
      WRITE(6,51)
      FORMAT(30H)THE FOLLOWING IS S FROM SPGEN////////)
      WRITE(6,*)S
      WRITE(6,52)
      FORMAT(30H)THE FOLLOWING IS C FROM SPGEN////////)
      WRITE(6,*)C
      WRITE(6,53)
      FORMAT(33H)THE FOLLOWING IS SBAR FROM SPGEN////////)
      WRITE(6,*)SBAR
      WRITE(6,54)
      FORMAT(31H)THE FOLLOWING IS NS FROM SPGEN////////)
      WRITE(6,*)NS
C..... BEGIN MAIN LOOP.
15      DO 45 J=J1,NMAX
          L=J

```



```

20      I=L
25      DSLAST=SP(I-1)-SP(I-2)
      SBAR=SP(I-1)+DSLAST/2.0
      CA=AMAX1(CMIN,ABS(FNTRP(S,C,SBAR,NS)))
      DSLIM=AMIN1(DS1,DSLAST*RMAX)
      IF (.NOT. THIN) GO TO 30
      TLOC=CABS(FZTRP(S,Z,SBAR,NS)-FZTRP(S,Z,S(NS)-SBAR,NS))
      DSLIM=AMIN1(DSLIM,B*AMAX1(TLOC,TMIN))
30      DSFIN=SFIN-SP(I-1)
      NEVEN=DSFIN/DSLIM/ONE+1.0
      DSEVEN=DSFIN/FLOAT(NEVEN)
      DS=AMIN1(A/CA,DSEVEN)
      IF (I.NE.J) DS=AMIN1(DS,DSLAST/RMAX)

      C.....CALCULATED VALUE OF DS SATISFIES CONDITIONS 2 THRU 4A.TEST FOR 4B.
      IF (DS.GE.DSLAST/RMAX) GO TO 40

      C.....IF CONDITION 4B IS NOT SATISFIED, RE-DO EARLIER INTERVALS
      C.....USING SMALLER VALUES OF DS. IF RE-DOING ALL INTERVALS WON'T
      C.....WORK, START OVER USING SMALLER STARTING VALUE OF DS (DS1).
35      L=L-1
      IF (L.GE.J1) GO TO 20
      IF (NSP.GT.1) RETURN
      DS1=DS1/RMAX
      GO TO 10

      C.....IF CONDITIONS 2 THRU 4B ARE SATISFIED, TEST FOR FINISH.
40      SP(I)=SP(I-1)+DS
      FIN=SFIN/SP(I).LE.ONE
      IF (FIN.AND.DS.GT.DSEND) GO TO 35
      IF (FIN) GO TO 50
      IF (I.GE.J) GO TO 45
      I=I+1
      GO TO 25
45      CONTINUE
      C.....SPGEN=FALSE. IF CONDITION 1 CANNOT BE SATISFIED.
      RETURN

      C.....IF CONDITIONS ARE SATISFIED, UPDATE NSP.
50      NSP=I
      DELSL=DS
      SPGEN=.TRUE.
      RETURN
      END
      C.....COMPLEX FUNCTION DZTRP (A,F,X,NA)
      C.....COMPLEX DERIVATIVE EVALUATION FOR DOUBLE 3-POINT INTERPOLATION.
      C.....COMPLEX F(400)
      REAL A(400)

```

QSO40330
 QSO40340
 QSO40350
 QSO40360
 QSO40370
 QSO40380
 QSO40390
 QSO40400
 QSO40410
 QSO40420
 QSO40430
 QSO40440
 QSO40450
 QSO40460
 QSO40470
 QSO40480
 QSO40490
 QSO40500
 QSO40510
 QSO40520
 QSO40530
 QSO40540
 QSO40550
 QSO40560
 QSO40570
 QSO40580
 QSO40590
 QSO40600
 QSO40610
 QSO40620
 QSO40630
 QSO40640
 QSO40650
 QSO40660
 QSO40670
 QSO40680
 QSO40690
 QSO40700
 QSO40710
 QSO40720
 QSO40730
 QSO40740
 QSO40750
 QSO40760
 QSO40770
 QSO40780
 QSO40790
 QSO40800


```

COMMON /NTRPC3/ I1,I2,C(4)
C.....FIRST EVALUATE FUNCTION COEFFICIENTS.
CALL FNTRPA (A,X,NA)
CALL DNTRPC
C.....THEN EVALUATE FUNCTION VALUE.
C      GO TO 10
C      ENTRY DZTRP1 (F)
C      DZTRP1=0.
10    DZTRP=0.0
      J=0
      DO 1 I=I1,I2
        J=J+1
        DZTRP=DZTRP+C(J)*F(I)
      RETURN
      END
C.....COMPLEX FUNCTION FZTRP (A,F,X,NA)
COMPLEX FUNCTION EVALUATION BY DOUBLE 3-POINT INTERPOLATION.
C.....COMPLEX F(400)
REAL A(400)
COMMON /NTRPC2/ I1,I2,C(4)
C.....FIRST EVALUATE FUNCTION COEFFICIENTS.
CALL FNTRPA (A,X,NA)
CALL DNTRPC
C.....THEN EVALUATE FUNCTION VALUE.
C      GO TO 10
C      ENTRY FZTRP1 (F)
C      FZTRP1=0.
10    FZTRP=0.0
      J=0
      DO 1 I=I1,I2
        J=J+1
        FZTRP=FZTRP+C(J)*F(I)
      RETURN
      END
C.....FUNCTION FNTRP (A,F,X,NA)
FUNCTION EVALUATION FOR DOUBLE 3-POINT INTERPOLATION.
C.....REAL F(400),A(400)
COMMON /NTRPC2/ I1,I2,C(4)
C.....FIRST EVALUATE FUNCTION COEFFICIENTS.
CALL FNTRPA (A,X,NA)
CALL DNTRPC
C.....THEN EVALUATE FUNCTION VALUE.
C      GO TO 5
C      ENTRY FNTRP1 (F)
C      FNTRP1=0.
5    FNTRP=0.0
      J=0
      DO 10 I=I1,I2

```

Q5040810
 Q5040820
 Q5040830
 Q5040840
 Q5040850
 Q5040860
 Q5040870
 Q5040880
 Q5040890
 Q5040900
 Q5040910
 Q5040920
 Q5040930
 Q5040940
 Q5040950
 Q5040960
 Q5040970
 Q5040980
 Q5040990
 Q5041000
 Q5041010
 Q5041020
 Q5041030
 Q5041040
 Q5041050
 Q5041060
 Q5041070
 Q5041080
 Q5041090
 Q5041100
 Q5041110
 Q5041120
 Q5041130
 Q5041140
 Q5041150
 Q5041160
 Q5041170
 Q5041180
 Q5041190
 Q5041200
 Q5041210
 Q5041220
 Q5041230
 Q5041240
 Q5041250
 Q5041260
 Q5041270
 Q5041280


```

10      J=J+1
      FNTRP=FNTRP+C(J)*F(I)
      RETURN
      END
      SUBROUTINE DNTRPC
      CALCULATION OF C COEFFICIENTS FOR DERIVATIVES OF DOUBLE
      3-POINT INTERPOLATION.
      COMMON /NTRPC1/ L,I,A11,A12,A13,A14,A22,A23,A24,A33,A34,A44
      COMMON /NTRPC3/ I1,I2,C1,C2,C3,C4
      IF (L.LE.1) GO TO 13
      IF (L-3) 12,11,10
      FOR DOUBLE 3-POINT INTERPOLATION.
      10      C1=(A22+A33+A22)/A23*A33/A12/A13
      C4=-(A33+A22+A33)/A23*A22/A34/A24
      P=A23*A23
      C2=-((A11+A33+A11)*A33/A12+(A33*A44+A22*A33)/A24)/P
      C3=-(A44+A22+A44)*A22/A34+(A22*A11+A33*A22)/A13/P
      GO TO 14
      FOR SIMPLE 3-POINT INTERPOLATION.
      11      C1=(A33+A22)/A12/A13
      C2=-(A33+A11)/A12/A23
      C3=(A22+A11)/A13/A23
      GO TO 14
      FOR 2-POINT INTERPOLATION.
      12      C1=1.0/A12
      C2=-C1
      GO TO 14
      ONLY ONE TABLE VALUE GIVEN.
      13      C1=0.0
      14      I1=I
      I2=I+L-1
      RETURN
      END
      SUBROUTINE FNTRPA(A,X,NA)
      COMMON SUBROUTINE EVALUATES A COEFFICIENTS IN DOUBLE
      3-POINT INTERPOLATIONS.
      C      L=NO. OF POINTS IN THE FIT
      C      I=INDEX TO FIRST POINT
      REAL A(400)
      COMMON /NTRPC1/ L,I,A11,A12,A13,A14,A22,A23,A24,A33,A34,A44
      GET I AND L BY TABLE LOOK-UP.
      L=LIMIT(1,NA,3)
      M=MAXO(1,NA-2)
      CALL TLU(A,X,NA,J)
      IF (J.EQ.LIMIT(2,J,M)) L=4
      I=LIMIT(1,J-1,M)
      CALCULATE A-ARRAY.
      C      A11=A(I)

```

Q S041290
 Q S041300
 Q S041310
 Q S041320
 Q S041330
 Q S041340
 Q S041350
 Q S041360
 Q S041370
 Q S041380
 Q S041390
 Q S041400
 Q S041410
 Q S041420
 Q S041430
 Q S041440
 Q S041450
 Q S041460
 Q S041470
 Q S041480
 Q S041490
 Q S041500
 Q S041510
 Q S041520
 Q S041530
 Q S041540
 Q S041550
 Q S041560
 Q S041570
 Q S041580
 Q S041590
 Q S041600
 Q S041610
 Q S041620
 Q S041630
 Q S041640
 Q S041650
 Q S041660
 Q S041670
 Q S041680
 Q S041690
 Q S041700
 Q S041710
 Q S041720
 Q S041730
 Q S041740
 Q S041750
 Q S041760


```

A22=A(I+1)
A33=A(I+2)
IF (L.NE.4) IF (L-2) 20,15,10
A44=A(I+3)
A14=A11-A44
A24=A22-A44
A34=A33-A44
A44=X-A44
A13=A11-A33
A23=A22-A33
A33=X-A33
A12=A11-A22
A22=X-A22
A11=X-A11
RETURN
END
SUBROUTINE FNTRPC
CALCULATION OF C COEFFICIENTS FOR FUNCTION VALUES BY DOUBLE
3-POINT INTERPOLATION.
C.....COMMON /NTRPC1/L,I,A11,A12,A13,A14,A22,A23,A24,A33,A34,A44
C.....COMMON /NTRPC2/ I1,I2,C1,C2,C3,C4
IF (L.LE.1) GO TO 25
IF (L-3) 20,15,10
C.....FOR DOUBLE 3-POINT INTERPOLATION.
10 C1=+A22/A23*A22/A12*A33/A13
C4=-A22/A23*A33/A34*A22/A24
P2=A23/A23*A11/A23
P3=A22/A23*A44/A23
C2=-A33*(P2/A12+P3/A24)
C3=+A22*(P3/A34+P2/A13)
GO TO 30
C.....FOR SIMPLE 3-POINT INTERPOLATION.
15 C1=+A22/A12*A33/A13
C2=-A11/A12*A33/A23
C3=+A11/A13*A22/A23
GO TO 30
C.....FOR 2-POINT INTERPOLATION.
20 C1=+A22/A12
C2=-A11/A12
GO TO 30
C.....ONLY ONE TABLE VALUE GIVEN.
25 C1=1.0
30 I1=1
I2=I+L-1
RETURN
END
SUBROUTINE TLU (TABLE,ARG,N,I)
TABLE LOOK UP: FINDS I SUCH THAT

```



```

C      ARG.GE.TABLE(I).AND.ARG.LT.TABLE(I+1)
C      IF I=0, ARG.LT.TABLE(I)
C      IF I=N, ARG.GE.TABLE(N)
C      REAL TABLE(400)
C      I=LIMIT(I,N)
C      IF (ARG.GE.TABLE(I)) GO TO 15
C      .....DESCEND IN TABLE.
10      I=I-1
C      IF (I.LE.0) RETURN
C      IF (ARG.GE.TABLE(I)) RETURN
C      GO TO 10
C      .....ASCEND IN TABLE.
15      IF (I.GE.N) RETURN
C      IF (ARG.LT.TABLE(I+1)) RETURN
C      I=I+1
C      GO TO 15
C      END
C      FUNCTION LIMIT (I,J,K)
C      INTEGER FUNCTION LIMITS J BETWEEN I AND K.
C      .....
C      LIMIT=I
C      IF (J.LT.LIMIT) RETURN
C      LIMIT=K
C      IF (J.GT.LIMIT) RETURN
C      LIMIT=J
C      RETURN
C      END
C      LOGICAL FUNCTION XNTRP (A,F,F0,NA,X)
C      INVERSE FUNCTION FOR DOUBLE 3-POINT INTERPOLATION.
C      .....
C      GIVEN TABLES A AND F (EACH OF LENGTH NA), THE VALUE OF X IS
C      FOUND FOR WHICH FNTRP (A,F,X,NA)=F0. ONLY SOLUTIONS LARGER
C      THAN THE ENTRY VALUE OF X ARE CONSIDERED; ONLY THE SMALLEST
C      OF THESE IS RETURNED. IF NO SOLUTION IS FOUND, XNTRP=.FALSE.
C      AND X IS LEFT UNALTERED.
C      REAL A(400),F(400),C(4),R(3)
C      INTEGER II(3),REALX,RCMPLX,ICMPLX,TYPE
C      LOGICAL LAST,SIZE
C      COMMON /NTRPC1/ L,I,EXTRA(10)
C      COMMON /NTRPC5/ M,B(4,4)
C      DATA REALX,RCMPLX,ICMPLX,EPSLON/0,1,2,1.0E-5/
C      COMPLEX FZ(400)
C      TYPE=REALX
C      GO TO 100
C      .....ALTERNATE ENTRIES FOR COMPLEX TYPE FUNCTION TABLES:
C      .....RZTRP IS USED TO GET X FOR WHICH REAL(FZTRP(A,F,X,NA))=F0.

```

Q5042250
 Q5042260
 Q5042270
 Q5042280
 Q5042290
 Q5042300
 Q5042310
 Q5042320
 Q5042330
 Q5042340
 Q5042350
 Q5042360
 Q5042370
 Q5042380
 Q5042390
 Q5042400
 Q5042410
 Q5042420
 Q5042430
 Q5042440
 Q5042450
 Q5042460
 Q5042470
 Q5042480
 Q5042490
 Q5042500
 Q5042510
 Q5042520
 Q5042530
 Q5042540
 Q5042550
 Q5042560
 Q5042570
 Q5042580
 Q5042590
 Q5042600
 Q5042610
 Q5042620
 Q5042630
 Q5042640
 Q5042650
 Q5042660
 Q5042670
 Q5042680
 Q5042690
 Q5042700
 Q5042710
 Q5042720


```

ENTRY RZTRP (A,FZ,F0,NA,X)
RZTRP=0.
C..... COMPLEX FZ(NA) THIS WAS MOVED UP TO COMPILE PROPERLY ON NPS 370
TYPE=RCMPLX
GO TO 100
Q5042730
Q5042740
Q5042750
Q5042760
Q5042770
Q5042780
Q5042790
Q5042800
Q5042810
Q5042820
Q5042830
Q5042840
Q5042850
Q5042860
Q5042870
Q5042880
Q5042890
Q5042900
Q5042910
Q5042920
Q5042930
Q5042940
Q5042950
Q5042960
Q5042970
Q5042980
Q5042990
Q5043000
Q5043010
Q5043020
Q5043030
Q5043040
Q5043050
Q5043060
Q5043070
Q5043080
Q5043090
Q5043100
Q5043110
Q5043120
Q5043130
Q5043140
Q5043150
Q5043160
Q5043170
Q5043180
Q5043190
Q5043200

C..... IZTRP IS USED TO GET X FOR WHICH AIMAG(FZTRP(A,F,X,NA))=F0.
ENTRY IZTRP (A,FZ,F0,NA,X)
IZTRP=0.
TYPE=ICMPLX

C..... INITIALIZATION.
100 XIN=X
XMAX=XIN
DX=0.0

C..... CALCULATE POLYNOMIAL COEFFICIENTS.
1 XMIN=AMAX1(XIN+DX,XMAX-DX)
CALL BNTRP (A,XMAX,NA)
LAST=M.GE.NA-1
IF (LAST) GO TO 2
MAX=M+L-3
XMAX=A(MAX)
DO 3 J=1,L
C(J)=0.0
DO 3 N=1,L
IN=I+N-1
IF (TYPE.EQ.REALX) C(J)=C(J)+B(N,J)*F(IN)
IF (TYPE.EQ.RCMPLX) C(J)=C(J)+B(N,J)*REAL(FZ(IN))
IF (TYPE.EQ.ICMPLX) C(J)=C(J)+B(N,J)*AIMAG(FZ(IN))
CONTINUE
C(1)=C(1)-F0
IF (L.EQ.4.AND.ABS(C(L)).LT.1.E-04)L=3
LL=L
IF (LL.LT.2) GO TO 8
IF (C(LL).NE.0.0) GO TO 5
LL=LL-1
GO TO 4

C..... GET ROOTS OF POLYNOMIAL.
5 NR=1
IF (LL.EQ.2) R(1)=-C(1)/C(2)
IF (LL.EQ.3) NR=NRRTS2(C,R)
IF (LL.EQ.4) NR=NRRTS3(C,R)

C..... TEST ROOTS OF POLYNOMIAL.
IF (NR.LE.0) GO TO 8
IF (.NOT.SIZE(R,II,NR)) CALL ORDER (R,II,NR)

```



```

GO TO 24
C.....ENTER HERE FOR 3 OR MORE COEFFICIENTS.
3  P=1.0/A23
   IF (L.GT.3) GO TO 4
   B13=Q/A13
   B23=-Q*P
   B33=P/A13
   GO TO 34
C.....ENTER HERE FOR 4 COEFFICIENTS.
4  P2=P*P
   B14=P*Q/A13
   B24=-P2/A12-P2/A24
   B34=P2/A34+P2/A13
   B44=-P/A34/A24
   B13=(Q+Q)/A13
   B23=-P*(Q+Q)-P/A24
   B33=P2*(A24/A34+(A23-A12)/A13)
   B43=-1.0/A34/A24
   B41=0.0
   B42=0.0
   B12=A23/A12/A13
   B22=P-Q
   B32=-A12/A13/A23
34  B31=0.0
   B11=0.0
   B21=1.0
   RETURN
END
C.....INTEGER FUNCTION NRRTS3 (C,R)
      FINDS REAL ROOTS R, OF A CUBIC WITH COEFFICIENTS C, WHEN:
      C(1) + C(2)*X + C(3)*X**2 + C(4)*X**3 = 0.0
C
      REAL C(4),R(3),K1,K2
      DATA THIRD,K1,K2/0.3333333,2.094395,4.188790/
      QRT(ARG)=SIGN(ABS(ARG)**THIRD,ARG)
C.....CONVERT TO NORMAL FORM AND CALCULATE NORMAL COEFFICIENTS.
      CNORM=3.0*C(4)
      P=C(3)/CNORM
      Q=C(2)/CNORM
      B=P**3-1.5*(P*Q-C(1)/CNORM)
      B2=B**2
      A=Q-P*P
      A3=A**3
      RAD=B2+A3
      IF (RAD) 3,2,1

```



```

C..... THERE IS ONE REAL ROOT.
1  NRRTS3=1
   IF (RAD.NE.0.0) RAD=SQRT(RAD)
   A=-B+RAD
   B=-B-RAD
   IF (A.NE.0.0) A=QRT(A)
   IF (B.NE.0.0) B=QRT(B)
   R(1)=A+B
   GO TO 10

```

```

C..... THERE ARE TWO REAL ROOTS.
2  NRRTS3=2
   IF (B.EQ.0.0) GO TO 1
   R(1)=QRT(B)
   R(2)=-2.0*R(1)
   GO TO 10

```

```

C..... THERE ARE THREE REAL ROOTS.
3  NRRTS3=3
   PHI= ARCCOS(SIGN(SQRT(-B2/A3),-B))/3.0
   CR=2.0*SQRT(-A)
   R(1)=CR*COS(PHI)
   R(2)=CR*COS(PHI+K1)
   R(3)=CR*COS(PHI+K2)

```

```

C..... CONVERT BACK TO ORIGINAL FORM.
10 DO 11 I=1,NRRTS3
11  R(I)=R(I)-P
   RETURN

```

```

ENTRY NRRTS2 (C,R)
C..... FINDS REAL ROOTS  $R_1$  OF A QUADRATIC WITH COEFFICIENTS C, WHEN:
 $C(1) + C(2)*X + C(3)*X**2 = 0.0$ 
C

```

```

C..... CALCULATE RADICAL.
RAD=C(2)**2-4.0*C(3)*C(1)
IF (RAD) 21,22,23

```

```

C..... NO REAL ROOTS.
21 NRRTS3=0
   NRRTS2=0
   RETURN

```

```

C..... ONE REAL ROOT.
22 NRRTS3=1
   R(1)=-C(2)/2.0/C(3)
   NRRTS2=1

```

```

Q5044170
Q5044180
Q5044190
Q5044200
Q5044210
Q5044220
Q5044230
Q5044240
Q5044250
Q5044260
Q5044270
Q5044280
Q5044290
Q5044300
Q5044310
Q5044320
Q5044330
Q5044340
Q5044350
Q5044360
Q5044370
Q5044380
Q5044390
Q5044400
Q5044410
Q5044420
Q5044430
Q5044440
Q5044450
Q5044460
Q5044470
Q5044480
Q5044490
Q5044500
Q5044510
Q5044520
Q5044530
Q5044540
Q5044550
Q5044560
Q5044570
Q5044580
Q5044590
Q5044600
Q5044610
Q5044620
Q5044630
Q5044640

```


Q5044650
Q5044660
Q5044670
Q5044680
Q5044690
Q5044700
Q5044710
Q5044720
Q5044730
Q5044740
Q5044750
Q5044760
Q5044770
Q5044780
Q5044790
Q5044800
Q5044810
Q5044820
Q5044830
Q5044840
Q5044850
Q5044860
Q5044870
Q5044880
Q5044890
Q5044900
Q5044910
Q5044920
Q5044930
Q5044940
Q5044950
Q5044960
Q5044970
Q5044980
Q5044990
Q5045000
Q5045010
Q5045020
Q5045030
Q5045040
Q5045050
Q5045060
Q5045070
Q5045080
Q5045090
Q5045100
Q5045110
Q5045120

```

RETURN
C.....TWO REAL ROOTS.
23 NRRTS3=2
RAD=SQRT(RAD)
TWOA=2.0*C(3)
R(1)=-((RAD+C(2))/TWOA
R(2)=+(RAD-C(2))/TWOA
NRRTS2=2
RETURN
END
LOGICAL FUNCTION SIZE(X,I,N) ORDERED BY SIZE OF X.
C.....CREATES THE POINTER ARRAY I, ORDERED BY SIZE OF X.
C.....VALUE IS .TRUE. IF X ARRAY IS IN ORDER.
C.....DIMENSION X(3),I(3)
C.....COMPLEX Z(3),Z5
C.....SIZE=.TRUE.
DO 2 J=1,N
K=J
1 IF (K.LE.1) GO TO 2
L=1(K-1)
IF (X(J).GE.X(L)) GO TO 2
I(K)=L
K=K-1
SIZE=.FALSE.
GO TO 1
I(K)=J
2 RETURN
ENTRY ORDER(X,I,N)
ORDER=0.
REARRANGES X ARRAY ACCORDING TO POINTER ARRAY I.
C.....DO 14 J=1,N
IF (I(J).LE.0) GO TO 13
M=J
S=X(M)
L=I(M)
11 I(M)=-L
IF (L.EQ.J) GO TO 12
X(M)=X(L)
M=L
GO TO 11
12 X(M)=S
13 I(J)=IABS(I(J))
14 CONTINUE
RETURN
ENTRY ZORDER(Z,I,N)
ZORDER=0.
REARRANGES Z (COMPLEX) ARRAY ACCORDING TO POINTER ARRAY I.
C.....

```



```

C      COMPLEX Z(N),ZS THIS WAS MOVED UP TO COMPILE PROPERLY ON NPS 370
DO 24 J=1,N
IF (I(J).LE.0) GO TO 23
M=J
ZS=Z(M)
L=I(M)
I(M)=-L
IF (L.EQ.J) GO TO 22
Z(M)=Z(L)
M=L
GO TO 21
21      Z(M)=ZS
22      I(J)=IABS(I(J))
23      CONTINUE
24      RETURN
END
SUBROUTINE PJGRID(ZET,ET,ZCAM,IMAXY,PITCH)

C      ELECTROSTATIC ANALOG GRID GENERATOR

C      J. J. ADAMCZYK
C      NASA LEWIS RESEARCH CENTER 1980

C      (SEE REF. 2, QSONIC USERS MANUAL)

COMMON/ENTIRE/ X(100,30),Y(100,30),ETA(100,30),ZETA(100,30)
COMMON/CROSS/XQ(4,100),YQ(4,100),EQ(4,100),ZQ(4,100),ZETB(100),
1STREN(63),FUN(100),GUN(100),ARG(100),ZBODY(63),DTREN(63)
COMMON/GEOM/NZGRID,NEGRID,RLE,RTE,C,CHORB,XUPS,XDNS,STAG,CC,CAP(4)
1,P1
1,RNK,VB,KN,NUM
COMPLEX A,B,ZO,ZA,ZB,ZTEMP,ZTEMQ
COMPLEX SUM3,SUM4,SUM5,SUM6,STREN
COMPLEX SUMD,HSIN
COMPLEX ZTEL,AI,HTAN,Z,SUM
COMPLEX SOUR,ZCAM,ZBODY,ZPET
COMPLEX ZST
DOUBLE PRECISION DTREN,BINF
DIMENSION ZPET(100,30),ZCAM(100),ET(100),ZET(100)
EQUIVALENCE (ZPET(1,1),ETA(1,1))
COMMON/CRHOSS/ BINF(63,63),SOUR(63,63)
LOGICAL XNTRP,TEST
NETA0=50
NZET0=50
NZET4=50

```



```

IMID=1
NUMX=31
NUMY=14
NUMZ=16
NZGRID MUST BE ODD

AI=CMPLX(0.0,1.0)
PI=3.1415927
CHORD=CHORB*COS(STAG)
STAG=STAG*180./PI
S=PITCH
WRITE(6,1006) NEGRID,NZGRID,IMAXY
FORMAT(5X,'NEGRID= ',I3,' NZGRID,ODD= ',I3,' IMAXY= ',I3)
CONTINUE
WRITE(6,1020)
FORMAT(10X,'SURFACE COORDINATES')
WRITE(6,1030) (ZCAM(I),I=1,NUM)
FORMAT(7X,2F12.7)
WRITE(6,1040) NUM,PITCH,CHORD,STAG
FORMAT(4X,'NUMBER OF BODY POINTS',I5,10X,'PITCH',F12.7,10X,' CHD ',
1 F12.7,' STAGGER',F12.7)
ZST=ZCAM(1)
DO 25 I=1,NUM
ZCAM(I)=ZCAM(I)-ZST
CONTINUE
NUM=NUM-1
PSAVE=PITCH
PITCH=2.0*PITCH
XMAX=0.0
IMAX=1
DO 6000 I=1,NUM
IF(XMAX .LE. REAL(ZCAM(I))) XMAX=REAL(ZCAM(I))
IF(XMAX .LE. REAL(ZCAM(I))) IMAX=I
CONTINUE
DO 30 I=1,MUM
IF(IMID .EQ. 1) ZBODY(I)=(ZCAM(I)+ZCAM(I+1))/2.0
DO 30 J=1,MUM
A=ZCAM(J)
B=ZCAM(J+1)
ZO=(A+B)/2.0
ZA=CLOG(PI/PITCH*(ZBODY(I)-A))
ZB=CLOG(PI/PITCH*(ZBODY(I)-B))
IF(I .EQ. J) ZA=ZA
IF(I .EQ. J) .AND. AIMAG(ZB) .LT. 0.0 .AND. J .LT. IMAX) ZB=ZB+2.0
**AI*PI
IF(I .LT. J .AND. AIMAG(ZA) .LT. 0.0 .AND. I .LT. IMAXY) ZA=ZA+2.0
**AI*PI

```

Q5045610
Q5045620
Q5045630
Q5045640
Q5045650
Q5045660
Q5045670
Q5045680
Q5045690
Q5045700
Q5045710
Q5045720
Q5045730
Q5045740
Q5045750
Q5045760
Q5045770
Q5045780
Q5045790
Q5045800
Q5045810
Q5045820
Q5045830
Q5045840
Q5045850
Q5045860
Q5045870
Q5045880
Q5045890
Q5045900
Q5045910
Q5045920
Q5045930
Q5045940
Q5045950
Q5045960
Q5045970
Q5045980
Q5045990
Q5046000
Q5046010
Q5046020
Q5046030
Q5046040
Q5046050
Q5046060
Q5046070
Q5046080


```

IF(I .LT. J .AND. AIMAG(ZB) .LT. 0.0 .AND. I .LT. IMAXY) ZB=ZB+2.0 QSO46090
*AI*PI QSO46100
IF(I .GT. J) ZA=ZA QSO46110
IF(I .GT. J) ZB=ZB QSO46120
IF(I .GE. J .AND. J .GE. IMAX/2.0 .AND. AIMAG(ZA) .GT. PI/2.0) ZA= QSO46130
*ZA-2.0*PI*AI QSO46140
IF(I .GT. J .AND. J .GE. IMAX/2.0 .AND. AIMAG(ZB) .GT. PI/2.0) ZB=ZB QSO46150
*-2.0*PI*AI QSO46160
CONTINUE QSO46170
SOUR(I,J)=(ZBODY(I)-A)*ZA-(ZBODY(I)-B)*ZB+(A-B) QSO46180
ZTEL=(ZBODY(I)-ZO)*PI/PI*CH QSO46190
HTAN=(CEXP(ZTEL)-CEXP(-ZTEL))/(CEXP(ZTEL)+CEXP(-ZTEL)) QSO46200
IF(CABS(ZTEL) .EQ. 0.0) SOUR(I,J)=SOUR(I,J) QSO46210
IF(CABS(ZTEL) .NE. 0.0) SOUR(I,J)=SOUR(I,J)+CLOG(HTAN/ZTEL)*(B-A) QSO46220
A1=ABS(REAL(B-A)) QSO46230
A2=ABS(AIMAG(B-A)) QSO46240
IF(A1 .GE. A2) BINF(I,J)=REAL(SOUR(I,J))+AIMAG(B-A)/REAL(B-A)*AIMA QSO46250
*G(SOUR(I,J)) QSO46260
IF(A1 .LT. A2) BINF(I,J)=-AIMAG(SOUR(I,J))-REAL(B-A)/AIMAG(B-A)*RE QSO46270
*AL(SOUR(I,J)) QSO46280
CONTINUE QSO46290
QSO46300
SOLUTION OF LINEAR EQUATIONS FOR ELECTROSTATIC CHARGE STRENGTH DIS QSO46310
TRIBUTION QSO46320
QSO46330
IF(NUM .GT. 1) GO TO 40 QSO46340
STREN(1)=1.0/BINF(1,1) QSO46350
GO TO 50 QSO46360
CONTINUE QSO46370
DO 45 I=1,MUM QSO46380
DTREN(I)=1.0DO QSO46390
CONTINUE QSO46400
QSO46410
QSO46420
CALL CHLSKY(BINF,DTREN,MUM) QSO46430
CONTINUE QSO46440
QSO46450
QSO46460
QSO46470
QSO46480
QSO46490
QSO46500
QSO46510
QSO46520
QSO46530
QSO46540
QSO46550
QSO46560

```

30
C
C
C

40

45

50

51


```

55 I=1,MUM
SUM2=0.0
SUM7=0.0
DO 56 J=1,MUM
A=ZCAM(J)
B=ZCAM(J+1)
A1=ABS(REAL(B-A))
A2=ABS(AIMAG(B-A))
IF(A1 .GE. A2) SUM2=SUM2+BINF(I,J)*REAL(STREN(J))
IF(A1 .LT. A2) SUM2=SUM2+BINF(I,J)*AIMAG(STREN(J))
FUN1=AIMAG(SOUR(I,J))-REAL(SOUR(I,J))*AIMAG(B-A)/REAL(B-A)
SUM7=SUM7+REAL(STREN(J))*FUN1
CONTINUE
ZETB(I)=SUM7
CONTINUE
CHORX=CHORD
DELX=3.0*CHORX/(NUMX-1.0)
DO 60 I=1,1
DO 60 J=1,NUMY
X(I,J)=-2.0*PSAVE
CONTINUE
DELY=PSAVE/(NUMY-2)
DO 70 I=1,1
DO 70 J=1,NUMY
Y(I,J)=DELY*(J-2)
IF(J .EQ. 1) Y(I,J)=-0.00001
IF(J .EQ. 2) Y(I,J)=0.00001
SUM=0.0
Z=X(I,J)+AI*Y(I,J)
IF(X(I,J) .LT. 0.0 .OR. X(I,J) .GT. XMAX) GO TO 7031
DO 7060 L=1,IMAX
IF(X(I,J) .GE. REAL(ZCAM(L)) .AND. X(I,J) .LE. REAL(ZCAM(L+1))) GO
*O TO 7080
CONTINUE
CONTINUE
L1=L
DO 7100 L=IMAX,NUM
IF(X(I,J) .LE. REAL(ZCAM(L)) .AND. X(I,J) .GE. REAL(ZCAM(L+1))) GO
* TO 7120
CONTINUE
CONTINUE
L2=L
YA=AIMAG(ZCAM(L1))
YR=AIMAG(ZCAM(L1+1))
XA=REAL(ZCAM(L1))
XB=REAL(ZCAM(L1+1))
Y1=YA+((YB-YA)/(XB-XA))*(X(I,J)-XA)
YA=AIMAG(ZCAM(L2))

```

QSO46570
 QSO46580
 QSO46590
 QSO46600
 QSO46610
 QSO46620
 QSO46630
 QSO46640
 QSO46650
 QSO46660
 QSO46670
 QSO46680
 QSO46690
 QSO46700
 QSO46710
 QSO46720
 QSO46730
 QSO46740
 QSO46750
 QSO46760
 QSO46770
 QSO46780
 QSO46790
 QSO46800
 QSO46810
 QSO46820
 QSO46830
 QSO46840
 QSO46850
 QSO46860
 QSO46870
 QSO46880
 QSO46890
 QSO46900
 QSO46910
 QSO46920
 QSO46930
 QSO46940
 QSO46950
 QSO46960
 QSO46970
 QSO46980
 QSO46990
 QSO47000
 QSO47010
 QSO47020
 QSO47030
 QSO47040


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7031 YB=AIMAG(ZCAM(L2+1))
      XA=REAL(ZCAM(L2))
      XB=REAL(ZCAM(L2+1))
      Y2=YA+(YB-YA)/(XB-XA)*(X(I,J)-XA)
      CONTINUE
      DO 75 IX=1,MUM
        A=ZCAM(IX)
        B=ZCAM(IX+1)
        ZA=CLOG(PI/PITCH*(Z-A))
        ZB=CLOG(PI/PITCH*(Z-B))
        IF(X(I,J).GT.0.0) GO TO 7000
        IFLA=1
        IF(Y(I,J).GE.0.0) GO TO 7010
        ZA=ZA
        ZB=ZB
        GO TO 7020
7010 CONTINUE
        IF(AIMAG(ZA).LT.0.0) ZA=ZA+2.0*AI*PI
        IF(AIMAG(ZB).LT.0.0) ZB=ZB+2.0*AI*PI
        GO TO 7020
7000 CONTINUE
        IF(X(I,J).GT.XMAX) GO TO 7040
        IF(Y(I,J).LT.Y1.AND.Y(I,J).GT.Y2) IFLA=2
        IF(Y(I,J).LT.Y1) GO TO 7140
        IF(Y(I,J).LT.Y1) GO TO 7140
        IF(AIMAG(ZA).LT.-PI/2.0) ZA=ZA+2.0*AI*PI
        IF(AIMAG(ZB).LT.-PI/2.0) ZB=ZB+2.0*AI*PI
        GO TO 7020
7140 CONTINUE
        IF(Y(I,J).LE.Y2) GO TO 7160
        IF(AIMAG(ZA).LT.0.0.AND.IX.GE.IMAX) ZA=ZA+2.0*AI*PI
        IF(AIMAG(ZB).LT.0.0.AND.IX.GE.IMAX) ZB=ZB+2.0*AI*PI
        GO TO 7020
7160 CONTINUE
        ZA=ZA
        ZB=ZB
        IF(IX.GE.IMAXY.AND.AIMAG(ZA).GT.PI/2.0) ZA=ZA-2.0*PI*AI
        IF(IX.GE.IMAXY.AND.AIMAG(ZB).GT.PI/2.0) ZB=ZB-2.0*PI*AI
        GO TO 7020
7040 CONTINUE
        IFLA=1
        ZA=ZA
        ZB=ZB
7020 CONTINUE
5000 SUM=SUM+STREN(IX)*(A-B+(Z-A)*ZA-(Z-B)*ZB)
      ZO=(A+B)/2.0
      ZTEL=(Z-ZO)*PI/PITCH
      HTAN=(CEXP(ZTEL)-CEXP(-ZTEL))/(CEXP(ZTEL)+CEXP(-ZTEL))

```



```

SUM=SUM+STREN(IX)*CLOG(HTAN/ZTEL)*(B-A)
IF(I .GT. 1 .AND. I .LT. NUMX) GO TO 3010
SUM3=(A-B)+(Z-A)*ZA-(Z-B)*ZB
SUM3=SUM3*STREN(IX)
SUM4=CLOG(HTAN/ZTEL)*(B-A)
SUM4=SUM4*STREN(IX)
SUM5=CLOG(1.0/ZTEL)*(B-A)
SUM5=SUM5*STREN(IX)
SUM6=CLOG(HTAN)*(B-A)
SUM6=SUM6*STREN(IX)
CONTINUE
CONTINUE
ETA(I,J)=REAL(SUM)
IF(X(I,J) .LT. XMAX .AND. X(I,J) .GT. 0.0 .AND. Y(I,J) .LT. Y1 .
*AND
1 Y(I,J) .GT. Y2) ETA(I,J)=1.05
ZETA(I,J)=AIMAG(SUM)
CONTINUE
NUMD=NUMY-1
DO 310 ID=1, NUMD
ARG(ID)=Y(1, ID+1)
FUN(ID)=ETA(1, ID+1)
GUN1(ID)=ZETA(1, ID+1)
CONTINUE
FO=0.0
YSTAR2=.95*PSAVE/2.
TEST=XNTRP(ARG, FUN, FO, NUMD, YSTAR2)
ZETA2=FNTRP(ARG, GUN1, YSTAR2, NUMD)
ETEST=0.0
ITEST=1
DO 330 I=1, NUMD
IF(ETEST .LE. ETA(1, I+1)) ETEST=ETA(1, I+1)
IF(ETEST .LE. ETA(1, I+1)) ITEST=I
CONTINUE
IF(ITEST .EQ. 1) ITEST=2
AQ1=ZETA(1, ITEST+1)
DELT=Y(1, 4)-Y(1, 2)
AQ2=(ZETA(1, ITEST+2)-ZETA(1, ITEST))/(2.0*DELT)
AQ3=(ZETA(1, ITEST+2)+ZETA(1, ITEST)-2.0*ZETA(1, ITEST+1))/(2.0*DELT*
**2)
BQ2=(ETA(1, ITEST+2)-ETA(1, ITEST))/(2.0*DELT)
BQ3=(ETA(1, ITEST+2)+ETA(1, ITEST)-2.0*ETA(1, ITEST+1))/(2.0*DELT**2)
YLMAX=-BQ2/(2.0*BQ3)
ZETA4=AQ1+AQ2*YLMAX+AQ3*YLMAX**2
DELT=ZETA(1, 2)-ZETA(1, 1)
DO 360 I=1, MUM
ARG(I)=ZETA(I)
FUN(I)=REAL(ZBODY(I))

```

3010
75

70

310

330


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360      CONTINUE
      XBOD1=FNTRP(ARG,FUN,ZETA4,MUM)
      XBOD3=FNTRP(ARG,FUN,0.0,MUM)
      DO 370 I=1,MUM
      FUN(I)=AIMAG(ZBODY(I))
370      CONTINUE
      YBOD1=FNTRP(ARG,FUN,ZETA4,MUM)
      YBOD3=FNTRP(ARG,FUN,0.0,MUM)
      ILIM=MUM+2
      XQ(1,1)=XBOD1
      XQ(1,ILIM)=XBOD1
      YQ(1,1)=YBOD1
      YQ(1,ILIM)=YBOD1
      ZQ(1,1)=ZETA4
      ZQ(1,ILIM)=-ZETA4
      EQ(1,1)=1.0
      EQ(1,ILIM)=1.0
      DO 380 I=1,MUM
      IF(ZETB(I)).GT. ZETA4) GO TO 390
380      CONTINUE
390      CONTINUE
      ISTART=I
      DO 410 I=ISTART,MUM
      IL=I-ISTART+2
      XQ(1,IL)=REAL(ZBODY(I))
      YQ(1,IL)=AIMAG(ZBODY(I))
      ZQ(1,IL)=ZETB(I)
      EQ(1,IL)=1.0
410      CONTINUE
      IEND=ISTART-1
      DO 420 I=1,IEND
      IL=MUM-ISTART+I
      XQ(1,IL)=REAL(ZBODY(I))
      YQ(1,IL)=AIMAG(ZBODY(I))
      ZQ(1,IL)=ZETB(I)-DELZ
      EQ(1,IL)=1.0
420      CONTINUE

      C      DETERMINE LOCATION OF PERIODIC BOUNDARY POINTS
      DO 110 IL=2,4
      IF(IL.EQ.2) XQ(2,1)=YSTAR2
      IF(IL.EQ.2) EQ(2,1)=-1.50*PSAVE
      IF(IL.EQ.2) EQ(2,1)=0.0
      IF(IL.EQ.2) ZQ(2,1)=ZETA2
      IF(IL.EQ.2) DELX=(CHORX+3.*PSAVE)/(NETA0-1.0)
      IF(IL.EQ.2) IEND=NETA0

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```

IF(IL,IL) .EQ. 2) ETA0=0.0
IF(IL,IL) .EQ. 3) YQ(3,1)=YBOD3
IF(IL,IL) .EQ. 3) XQ(3,1)=XBOD3
IF(IL,IL) .EQ. 3) EQ(3,1)=1.0
IF(IL,IL) .EQ. 3) ZQ(3,1)=0.0
IF(IL,IL) .EQ. 3) DELX=(2.0*PSAVE)/(NZETO-1.0)
IF(IL,IL) .EQ. 3) IEND=NZETO
IF(IL,IL) .EQ. 3) ZETA0=0.0
IF(IL,IL) .EQ. 4) YQ(4,1)=YBOD1
IF(IL,IL) .EQ. 4) XQ(4,1)=XBOD1
IF(IL,IL) .EQ. 4) EQ(4,1)=1.0
IF(IL,IL) .EQ. 4) ZQ(4,1)=ZETA4
IF(IL,IL) .EQ. 4) DELX=(-2.0*PSAVE-XBOD1)/(NZETA4-1.0)
IF(IL,IL) .EQ. 4) IEND=NZETA4
IF(IL,IL) .EQ. 4) ZETA0=ZETA4
DO 110 I=2, IEND
XQ(IL,I)=XQ(IL,I-1)+DELX
YQ(IL,I)=YQ(IL,I-1)
DO 120 ITOL=1,200
SUM=0.0
SUMD=0.0
Z=XQ(IL,I)+AI*YQ(IL,I)
IF(XQ(IL,I) .LT. 0.0 .OR. XQ(IL,I) .GT. XMAX) GO TO 130
DO 140 L=1, IMAX
IF(XQ(IL,I) .GE. REAL(ZCAM(L)) .AND. XQ(IL,I) .LE. REAL(ZCAM(L+1)))
*) GO TO 150
CONTINUE
L1=L
DO 160 L=IMAX,NUM
IF(XQ(IL,I) .LE. REAL(ZCAM(L)) .AND. XQ(IL,I) .GE. REAL(ZCAM(L+1)))
*) GO TO 170
CONTINUE
L2=L
YA=AIMAG(ZCAM(L1))
YB=AIMAG(ZCAM(L1+1))
XA=REAL(ZCAM(L1))
XB=REAL(ZCAM(L1+1))
Y1=YA+(YB-YA)/(XB-XA)*(XQ(IL,I)-XA)
YA=AIMAG(ZCAM(L2))
YB=(AIMAG(ZCAM(L2+1)))
XA=REAL(ZCAM(L2))
XB=REAL(ZCAM(L2+1))
Y2=YA+(YB-YA)/(XB-XA)*(XQ(IL,I)-XA)
CONTINUE
DO 180 IX=1,MUM
A=ZCAM(IX)

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      B=ZCAM(IX+1)
      ZA=CLOG(PI/PITCH*(Z-A))
      ZB=CLOG(PI/PITCH*(Z-B))
      IF(XQ(IL,I)) .GT. 0.0) GO TO 190
      IF(YQ(IL,I)) .GE. 0.0) GO TO 200
      ZA=ZA
      ZB=ZB
      GO TO 210
200 CONTINUE
      IF(AIMAG(ZA) .LT. 0.0) ZA=ZA+2.0*AI*PI
      IF(AIMAG(ZB) .LT. 0.0) ZB=ZB+2.0*AI*PI
      GO TO 210
190 CONTINUE
      IF(XQ(IL,I)) .GT. XMAX) GO TO 220
      IF(YQ(IL,I)) .LT. Y1) GO TO 230
      IF(AIMAG(ZA) .LT. -PI/2.0) ZA=ZA+2.0*AI*PI
      IF(AIMAG(ZB) .LT. -PI/2.0) ZB=ZB+2.0*AI*PI
      GO TO 210
230 CONTINUE
      IF(YQ(IL,I)) .LE. Y2) GO TO 240
      IF(AIMAG(ZA) .LT. 0.0 .AND. IX .GE. IMAX) ZA=ZA+2.0*AI*PI
      IF(AIMAG(ZB) .LT. 0.0 .AND. IX .GE. IMAX) ZB=ZB+2.0*AI*PI
      GO TO 210
240 CONTINUE
      ZA=ZA
      ZB=ZB
      IF(IX .GE. IMAXY .AND. AIMAG(ZA) .GT. PI/2.0) ZA=ZA-2.0*PI*AI
      IF(IX .GE. IMAXY .AND. AIMAG(ZB) .GT. PI/2.0) ZB=ZB-2.0*PI*AI
      GO TO 210
220 CONTINUE
      ZA=ZA
      ZB=ZB
210 CONTINUE
      SUM=SUM+STREN(IX)*(A-B+(Z-A)*ZA-(Z-B)*ZB)
      SUMD=SUMD+STREN(IX)*(ZA-ZB)
      ZQ=(A+B)/2.0
      ZTEL=(Z-ZQ)*PI/PITCH
      HTAN=(CEXP(ZTEL)-CEXP(-ZTEL))/(CEXP(ZTEL)+CEXP(-ZTEL))
      HSIN=0.5*(CEXP(ZTEL*2.0)-CEXP(-ZTEL*2.0))
      SUM=SUM+STREN(IX)*CLOG(HTAN/ZTEL)*(B-A)
      SUMD=SUMD+STREN(IX)*(PI/PSAVE/HSIN-1.0/(Z-ZQ))*(B-A)
      CONTINUE
      ETAF=REAL(SUM)
      ZETAF=AIMAG(SUM)
      ETAFD=AIMAG(SUMD)
      ZETAFD=-REAL(SUMD)
      F1=ETAO-ETAF
      G1=ZETA0-ZETAF
180

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Q5048970
Q5048980
Q5048990
Q5049000
Q5049010
Q5049020
Q5049030
Q5049040
Q5049050
Q5049060
Q5049070
Q5049080
Q5049090
Q5049100
Q5049110
Q5049120
Q5049130
Q5049140
Q5049150
Q5049160
Q5049170
Q5049180
Q5049190
Q5049200
Q5049210
Q5049220
Q5049230
Q5049240
Q5049250
Q5049260
Q5049270
Q5049280
Q5049290
Q5049300
Q5049310
Q5049320
Q5049330
Q5049340
Q5049350
Q5049360
Q5049370
Q5049380
Q5049390
Q5049400
Q5049410
Q5049420
Q5049430
Q5049440

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120 DELY1=-F1/ETAFD
250 DELY2=-G1/ZETAFD
      IF(IL.EQ.2) DELI=DELY1
      IF(IL.EQ.2) DELT=DELY2
      YQ(IL,I)=YQ(IL,I)+DELT
      IF(ABS(DELT).LT.1.E-06) GO TO 250
      CONTINUE
110 CONTINUE
      EQ. 2) EQ(IL,I)=0.0
      IF(IL.EQ.2) ZQ(IL,I)=ZETAF
      EQ. 3) EQ(IL,I)=ETAF
      IF(IL.EQ.3) ZQ(IL,I)=0.0
      EQ. 4) EQ(IL,I)=ETAF
      IF(IL.EQ.4) ZQ(IL,I)=ZETA4
      CONTINUE

      NEND=2*NZGRID-1
      DO 500 I=1,NEND
      DO 500 J=1,NEGRID
      ETA(I,J)=0.0
      ZETA(I,J)=0.0
      X(I,J)=0.0
      Y(I,J)=0.0
      CONTINUE
      DELZ=ZQ(4,1)/(NZGRID-1.0)
      DELE=1.0/(NEGRID-1.0)
      DO 510 I=1,NETAO
      ARG(I)=ZQ(2,I)
      FUN(I)=XQ(2,I)
      GUN1(I)=YQ(2,I)
      CONTINUE
      DO 520 J=1,NZGRID
      ETA(J,1)=0.0
      ZETA(J,1)=ZQ(4,1)-DELZ*(J-1.0)
      RQ=ZETA(J,1)
      X(J,1)=FNTRP(ARG,FUN,RQ,NETAO)
      Y(J,1)=FNTRP(ARG,GUN1,RQ,NETAO)
      CONTINUE
      NEND=2*NZGRID-1
      ISTART=NZGRID+1
      DO 530 J=ISTART,NEND
      IML=2*NZGRID-J
      ETA(J,1)=0.0
      ZETA(J,1)=-ZETA(IML,1)
      X(J,1)=X(IML,1)

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Q5049450
 Q5049460
 Q5049470
 Q5049480
 Q5049490
 Q5049500
 Q5049510
 Q5049520
 Q5049530
 Q5049540
 Q5049550
 Q5049560
 Q5049570
 Q5049580
 Q5049590
 Q5049600
 Q5049610
 Q5049620
 Q5049630
 Q5049640
 Q5049650
 Q5049660
 Q5049670
 Q5049680
 Q5049690
 Q5049700
 Q5049710
 Q5049720
 Q5049730
 Q5049740
 Q5049750
 Q5049760
 Q5049770
 Q5049780
 Q5049790
 Q5049800
 Q5049810
 Q5049820
 Q5049830
 Q5049840
 Q5049850
 Q5049860
 Q5049870
 Q5049880
 Q5049890
 Q5049900
 Q5049910
 Q5049920

530	Y(J,1)=Y(IML,1)-PSAVE	Q S049930
	CONTINUE	Q S049940
	ILIM=MUM+2	Q S049950
	DO 540 I=1, ILIM	Q S049960
	ARG(I)=ZQ(I,I)	Q S049970
	FUN(I)=XQ(I,I)	Q S049980
	GUNI(I)=YQ(I,I)	Q S049990
540	CONTINUE	Q S050000
	DO 550 J=1, NEND	Q S050010
	ETA(J, NEGRID)=1.0	Q S050020
	ZETA(J, NEGRID)=ZETA(J,1)	Q S050030
	RQ=ZETA(J, NEGRID)	Q S050040
	X(J, NEGRID)=FNTRP(ARG, FUN, RQ, ILIM)	Q S050050
	Y(J, NEGRID)=FNTRP(ARG, GUNI, RQ, ILIM)	Q S050060
550	CONTINUE	Q S050070
	DO 560 I=1, NZET4	Q S050080
	IML=NZET4+1-I	Q S050090
	ARG(I)=EQ(4, IML)	Q S050100
	FUN(I)=XQ(4, IML)	Q S050110
	GUNI(I)=YQ(4, IML)	Q S050120
560	CONTINUE	Q S050130
	DO 570 I=1, NEGRID	Q S050140
	ETA(I, I)=(I-1.0)*DELE	Q S050150
	ZETA(I, I)=ZQ(4, I)	Q S050160
	RQ=ETA(I, I)	Q S050170
	X(I, I)=FNTRP(ARG, FUN, RQ, NZET4)	Q S050180
	Y(I, I)=FNTRP(ARG, GUNI, RQ, NZET4)	Q S050190
570	CONTINUE	Q S050200
	DO 580 I=1, NEGRID	Q S050210
	ETA(NEND, I)=ETA(I, I)	Q S050220
	ZETA(NEND, I)=-ZETA(I, I)	Q S050230
	X(NEND, I)=X(I, I)	Q S050240
	Y(NEND, I)=Y(I, I)	Q S050250
580	CONTINUE	Q S050260
	DO 585 I=1, NZETO	Q S050270
	IML=NZETO+1-I	Q S050280
	ARG(I)=EQ(3, IML)	Q S050290
	FUN(I)=XQ(3, IML)	Q S050300
	GUNI(I)=YQ(3, IML)	Q S050310
585	CONTINUE	Q S050320
	DO 587 I=1, NEGRID	Q S050330
	ETA(NZGRID, I)=(I-1.0)*DELE	Q S050340
	ZETA(NZGRID, I)=0.0	Q S050350
	RQ=ETA(NZGRID, I)	Q S050360
	X(NZGRID, I)=FNTRP(ARG, FUN, RQ, NZETO)	Q S050370
	Y(NZGRID, I)=FNTRP(ARG, GUNI, RQ, NZETO)	Q S050380
587	CONTINUE	Q S050390
	X(1,1)=-4.0*PSAVE	Q S050400


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X(NZGRID,1)=4.0*PSAVE
X(NEND,1)=-4.0*PSAVE
Y(1,1)=YQ(4,NZET4)
Y(NZGRID,1)=YQ(3,NZET0)
Y(NEND,1)=YQ(4,NZET4)
L=NEGRID
L=NEND
L=NZGRID
C
C
C
      GIVEN PERIODIC BOUNDARY AND BLADE SHAPE, SOLVE THE BOUNDARY VALUE
      PROBLEM
      FOR THE INTERNAL GRID POINTS.
      BIJ=2.0*(1.0/(DELE**2)+1.0/(DELZ**2))
      BIJP=1.0/(DELE**2)
      BIJM=BIJP
      BIPJ=1.0/(DELZ**2)
      BIMJ=BIPJ
      NEG2=NEGRID-1
      NZG2=NEND-1
      EPP=1.E-05
      DO 600 ITER=1,100
      ERR=0.0
      DO 610 I=2,NZG2
      DO 610 J=2,NEG2
      IF(I.EQ.NZGRID) GO TO 610
      XHOLD=X(I,J)
      YHOLD=Y(I,J)
      X(I,J)=C/BIJ*(BIPJ*X(I+1,J)+BIMJ*X(I-1,J)+BIJP*X(I,J+1)+BIJM*X(I
      * ,J-1))+(1.-C)*X(I,J)
      Y(I,J)=C/BIPJ*(BIPJ*Y(I+1,J)+BIMJ*Y(I-1,J)+BIJP*Y(I,J+1)+BIJM*Y(I
      * ,J-1))+(1.-C)*Y(I,J)
      ERR=ERR+ABS(X(I,J)-XHOLD)+ABS(Y(I,J)-YHOLD)
      CONTINUE
610      IF(ITER.LT.5) GO TO 600
      ERR=ERR/(2.0*NEG2*NZG2)
      IF(ERR.LE.EPP) GO TO 670
      KPRT=ITER/200
      IF(ITER.NE.200*KPRT) GO TO 600
      DO 620 I=1,NEND
      CONTINUE
620      CONTINUE
600
C
C
C
      CONTINUE
670

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4444 WRITE(6,'4444') ITER,ERR
      FORMAT(' ITER COUNT FOR INTERNAL GRID POINTS= ',I3,' ERR= ',E15.5)
DO 650 I=1,NEND
DO 650 J=1,NEGRID
  ZPET(I,J)=X(I,J)+AI*Y(I,J)
CONTINUE

650  MM=NEGRID
      NN=NEND
      K=1
      ZPET(1,1)=-2.0*CHORB+AI*YQ(4,NZET4)
      ZPET(NZGRID,1)=2.0*CHORB+AI*YQ(3,NZETO)
      ZPET(NEND,1)=-2.0*CHORB+AI*YQ(4,NZET4)
      ZPET(1,1)=-2.0*CHORX+0.
      ZPET(NEND,1)=ZPET(1,1)
      ZPET(NZGRID,1)=2.0*CHORX+0.

C
C
C
675  DO 675 I=1,NEND
      DO 675 J=1,NEGRID
        ZPET(I,J)=ZPET(I,J)*CEXP(-AI*STAG*PI/180.0)
        X(I,J)=REAL(ZPET(I,J))
        Y(I,J)=AIMAG(ZPET(I,J))
        CONTINUE
        ETADF1=-DELZ
        ETADF2=-ETADF1
        ZETDF1=DELE
        ZETDF2=-ZETDF1
        ET(1)=FLOAT(NZGRID-1)*(-DELZ)
        ZET(1)=0.
        DO 4844 I1=2,NEND
          ET(I1)=DELZ+ET(I1-1)
        DO 4845 I1=2,NEGRID
          ZET(I1)=DELE+ZET(I1-1)
        NOZ=NEND
        DO 780 I=1,NEND
          DO 780 J=1,NEGRID
            ZPET(I,J)=ZPET(I,J)*CEXP(AI*STAG*PI/180.0)
          CONTINUE
        DO 790 I=1,NEND
          ZTEMP=(ZPET(I,NEGRID)+ZPET(I+1,NEGRID))/2.0
          ZTEMQ=ZTEMP*CEXP(-AI*STAG*PI/180.0)
          XT=REAL(ZTEMP)
          YI=AIMAG(ZTEMP)
          XR=REAL(ZTEMQ)
          YR=AIMAG(ZTEMQ)
          CONTINUE
790

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STAG=STAG*PI/180.
PITCH=PSAVE
RETURN
END
SUBROUTINE CHLSKY(A,C,N)
IMPLICIT REAL*8 (A-H,O-Z)
- CHOLESKY - SOLVES AN N BY N SYSTEM OF EQUATIONS WITH COEFFICIENT
C C C
MATRIX A(I,J), CONSTANT VECTOR C(I), AND SOLUTION VECTOR.
C C C
CHOLESKY'S METHOD IS USED. IT REQUIRES N**2 + O(N) OPERATIONS.
C C C
DIMENSION A(63,63),C(63)
C C
- CALCULATION OF SOLUTION MATRIX. NOTE BOTH THE UPPER AND LOWER
C C C
TRIANGULAR MATRICES ARE STORED AS REPLACEMENT VALUES IN MATRIX A.
C C C
ALSO THE SOLUTION VECTOR REPLACES THE CONSTANT VECTOR (C).
C C C

IST = 1
JST = 2
DO 50 K = 1,N
C C
- CALCULATION OF LOWER TRIANGULAR MATRIX ELEMENTS
C C C
DO 10 I = IST,N
J = 0
J = J+1
IF (J.GE.K) GO TO 10
A(I,K) = A(I,K) - A(I,J)*A(J,K)
GO TO 20
CONTINUE
10
C C
- CALCULATION OF UPPER TRIANGULAR MATRIX ELEMENTS
C C C
IF (K.EQ.N) GO TO 50
DO 40 J = JST,N
I = 0
I = I+1
IF (I.GE.K) GO TO 40
A(K,J) = A(K,J)-A(K,I)*A(I,J)
GO TO 30
A(K,J) = A(K,J)/A(K,K)
IST = IST+1
JST = JST+1
30
40
50
C C
- CALCULATION OF CONSTANT VECTOR ELEMENTS. ENTRY POINT FOR MULTIPLE
C C C
SOLUTION INVOLVING THE SAME COEFFICIENT MATRIX, BUT CHANGES IN
C C C
CONSTANT MATRIX.
C C C

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C      ENTRY CHGCNT(A,C,N)
      NPI = N+1
      DO 70 K = 1,N
      I = 0
      IF (I.GE.K) GO TO 70
      C(K) = C(K) - A(K,I)*C(I)
      GO TO 60
      C(K) = C(K)/A(K,K)
70
C      - EVALUATION OF SOLUTION MATRIX
C
      DO 90 K = 1,N
      L = NPI-K
      M = NPI
      IF (M.LE.L) GO TO 90
      C(L) = C(L)-A(L,M)*C(M)
      GO TO 80
      CONTINUE
      RETURN
      END
80
90

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S051850
 Q S051860
 Q S051870
 Q S051880
 Q S051890
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 Q S052010
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 Q S052030
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 Q S052070

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